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The search for seismic signatures of movement at the glacier bed in a polythermal valley glacier

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ABSTRACT. A passive seismology experiment was conducted across the main overdeepening of Storglaciären in the Tarfala Valley, northern Sweden, to investigate the spatial and temporal distribution of basal microseismic waveforms in relation to known dynamics of this small polythermal sub-arctic glacier. The high ablation rate made it difficult to keep geophones buried and well-coupled to the glacier during the experiment and reduced the number of days of good quality data collection. The characterisation of typical and atypical waveforms showed that the dominant waveforms were from near-surface events such as crevassing. Waveforms resembling basal microseismic signals were very rare and seldom observed on more than two seismic stations simultaneously. The analysis of waveforms, amplitudes and particle motions suggested a near-field origin for most events. Even though basal sliding is known to occur in the overdeepening, no convincing examples of basal waveforms were detected, suggesting basal microseismic signals are rare or difficult to detect beneath polythermal glaciers like Storglaciären. We discuss the reasons for failing to locate basal signals, consider the origin of common waveforms, and make recommendations for setting-up passive seismology experiments on glaciers with high ablation rates.
INTRODUCTION

Subglacial processes such as basal sliding exert a strong control on glacier flow, so any understanding of glacier dynamics requires consideration of subglacial hydrology, soft-bed rheology and the strength of coupling between the glacier and its bed (Fischer and others, 1996). For example, the soft-bed deformation model shows how glaciers overriding soft, water-saturated beds can impart sufficient shear stress to initiate deep, widespread and pervasive deformation which makes a significant contribution to the forward motion of the glacier (Boulton and Hindmarsh, 1987). The soft-bed deformation model has been used to explain fast flow in ice streams (Blankenship and others, 1986; Boulton and Hindmarsh, 1987; Alley and others, 1987; Boutron and others, 2001), glacier surges (Fischer and Clarke, 2001), and binge-purge cycles in palaeo-ice sheets leading to Heinrich events and abrupt climate change (MacAyeal, 1993; Clark, 1994). However, the applicability of the soft-bed deformation model is highly contested. The competing ice-bed mosaic model characterises subglacial deformation as a discrete, depth-limited, cumulative and time-transgressive process. In this model sticky spots (areas of high basal drag) and basal sliding are more important controls on glacier flow than deformation (Piotrowski and others, 2001; Piotrowski and others, 2004; Thomason and Iverson, 2009). It is important to resolve the uncertainties regarding subglacial processes as a better understanding of the subglacial environment is required to parameterize ice sheet models, to predict glacio-dynamic response to climate change, and to match modelled glacier dynamics to sediment-landform associations (Carr, 2004; Boulton and Hagdorn, 2006; IPCC, 2007; Passchier and others, 2010).

The inaccessibility of the subglacial environment makes direct observations of subglacial processes difficult; borehole investigations and observations in glacial tunnels may provide valuable insights, but they only provide a snapshot of a spatially limited part of the glacier bed (Clarke, 2005). By contrast, passive seismology offers a potential means of indirectly observing subglacial processes at a high temporal resolution, over a relatively wide area, and over a period of several days or weeks (Roux and others, 2008). Passive seismology experiments can be designed to detect natural microseismic events within a few kilometres of their source.

A variety of glacial processes are thought to generate microseismic signals through the brittle failure of ice and the release of elastic strain energy, with up to tens of events per minute being recorded and a wide-variety of waveforms produced (West and others, 2010). In addition, hydraulic transients are generated by water flow and reverberations in water-filled cavities and complex hybrid signals can be generated by brittle ice failure followed by the flow of pressurized water into fractures (St. Lawrence and Qamar 1979; Walter and others, 2008; West and others, 2010). High frequency waveforms originating from the glacier...
bed are characterised by impulsive P-wave onset, with most P-wave energy in the vertical axis, and no (or limited) surface wave energy; the separation of the P- and S-waves is approximately proportional to the ice thickness (Smith, 2006). Differences in the frequency, spatial distribution and timing of basal microseismic events have been used to infer glacier bed conditions in Antarctica. Anandakrishnan and Bentley (1993) detected 20-times more basal signals from the Kamb Ice Stream (formerly Ice Stream C) than the Whillans Ice Stream (formerly Ice Stream B). They inferred that the lower number of events detected beneath the Whillans Ice Stream were associated with a dilatant and pervasively deforming soft-bed which initiated and sustained fast ice flow, whereas the loss of till dilatancy beneath the Kamb Ice Stream resulted in shutdown of fast flow. Basal microseismic events beneath the Kamb Ice Stream occurred in clusters which were associated with the development of low angle thrusts and stick-slip movements (periods of glacier acceleration followed by periods of no activity). Similarly, Smith (2006) and Smith and Murray (2009) found that zones of fast-ice flow in the Rutford Ice Stream were associated with smooth, pervasively deforming beds, and these zones produced 6-times fewer basal signals than rough-bedded regions where basal sliding or stick-slip movement dominated. As such, Smith (2006) argued that passive seismology could be used to map out the style of basal motion beneath glaciers.

In temperate valley glaciers, the dominance of near-surface events associated with meltwater flow and crevassing can make basal signals difficult to distinguish (Walter and others, 2008). Also, the inability to identify events on more than one station, combined with frequent difficulties in measuring P-S separation times where the ice is very thin, often preclude common methods of basal event location. On Gornergletscher in the Swiss Alps, Walter and others (2008) found that basal waveforms were very rare (< 0.5% of all events detected) and tended to occur only in the early morning; they attributed the temporal clustering of basal signals to extensional ice fracturing caused by the glacier re-coupling to its bed. Similarly, only 8% of the events detected by Stuart and others (2005) on surging Bakaninbreen, Svalbard, were interpreted as basal signals produced by brittle fracture at the glacier bed.

As part of a wider study of subglacial processes and their relation to flow dynamics in subarctic polythermal glaciers, we established a passive seismology experiment on Storglaciären, northern Sweden. Our aim was to catalogue and characterise microseismic events in order to better understand how these events relate to glacier flow. The particular focus was on the detection of basally-derived signals that may provide evidence about glacier bed conditions and processes. Figure 1 shows how the known flow dynamics of Storglaciären may act as potential sources of microseismic signals.

FIGURE 1
STUDY SITE

Storglaciären is a small polythermal valley glacier located on the eastern side of the Kebnekaise Mountains in the sub-arctic region of northern Sweden (67°55’ N, 18°35’ E; Fig. 2). Storglaciären has been the focus of extensive glaciological research since 1949 and much is known about its dynamic behaviour (e.g. Jansson and Hooke, 1989; Holmlund and Jansson, 1999; Evans and others, 2008; Moore, 2009; Gusmeroli and others, 2012). It covers an area of approximately 3 km² and has a volume of 0.38 km³, 85% of which is temperate ice (Holmlund and others, 1996). The glacier flows from a head elevation of 1730 m to a terminus position at 1120 m, where the cold surface layer reaches a maximum thickness of 60 m (Jansson, 1995). Bedrock riegels produce four overdeepenings in the longitudinal profile of the glacier. The main overdeepening, which occurs just below the equilibrium line and where the glacier attains its maximum thickness of approximately 250 m, has a depth of c. 60 m (Hooke, 1989).

FIGURE 2

SURVEY PROCEDURES

In July 2010, five seismic stations were deployed in a four-point diamond array across the main overdeepening and set to continuously record with a sample rate of 1000 Hz. This location was selected because: basal sliding and stick-slip movements are likely in this area (Iverson and others, 1995; Fischer and others, 1996); these processes are thought to generate basal microseismic signals; and the greater thickness of the glacier in this area maximises the chance of getting sufficient P- and S-wave separation to allow for accurate event identification and location.

Stations were separated by around 200 m, similar to the average depth of the glacier in this area (Smith, 2006), although rockfalls, crevasses, moulins, and supraglacial channels constrained the locations and resulted in the array becoming somewhat elongated (Fig. 2). Each station consisted of a 4.5 Hz 3-component geophone with pre-amplifier and oriented with their N-S axis perpendicular to flow. To ensure the geophones remained stable and well coupled to the ice, they were mounted on pre-moulded concrete blocks with a flat upper surface and holes to allow the three pointed feet to pass through and be frozen into the ice below. Each geophone assembly was placed in pit dug 0.5 m into the ice surface. A plastic bucket was placed over each geophone and the pits back-filled with ice and covered with a rock cairn to reduce surface noise and to add protection from melt. Data were recorded by ISSI SAQS data loggers housed inside Zarges boxes. The boxes and connecting cables were also buried and protected by rock cairns. Each station was powered by a lead-acid
battery (housed in the Zarges box), and two solar panels. A common time signal was derived
from Garmin GPS units secured to the solar panels and connected to the loggers.

DATA ANALYSIS METHODS

The geophones remained buried, well-coupled to the glacier and level on approximately 18
of the 29 days of the experiment and these days yielded data of sufficient quality to allow for
waveform characterisation. PQL II software (McNamara and Boaz, 2011) was used to
manually inspect in detail five 24-hour periods of good quality data in order to characterise
the typical and atypical waveforms present. Inspection was undertaken both with and without
a 100 Hz high pass filter applied. This can help distinguish high frequency basal events from
surface events which display a significant low-frequency surface wave component
(Anandakrishnan, pers. comm). P-, S- and surface-wave arrivals were differentiated on the
basis of particle motion and polarisation characteristics. Waveform types were classified
visually on the basis of duration, amplitude, form and steepness of onset.

To assist in the identification of events originating at the glacier bed, a model of the array
was constructed based on inter-station distances and elevations with basal events assumed
directly beneath Station CC at a realistic depth of 200 m. Assuming P- and S-wave velocities
of 3.6 kms\(^{-1}\) and 1.8 kms\(^{-1}\) respectively (Roethlisberger, 1972), basal events would yield P-S
separation times of 0.05 s for Station CC and 0.1 s for outlying stations.

WAVEFORM CHARACTERISATION AND INTERPRETATION

The physical characteristics of the five main waveforms detected are described in Table 1,
along with their interpretations. Examples of real events are shown in Fig. 3. Different types
of event were dominant at different times. This is illustrated in Table 2, which shows a
comparison of the number of events of each type that occurred at between 03:00 – 04:00 hours
and 15:00 – 16:00 hours on the 14\(^{th}\) July.

Type 1 waveforms were the most common events and were detected on all stations. Type
1b and 1c waveforms were typically detected on either Station BW or CS first, and observed
to rapidly reduce in amplitude as they traversed the array. Type 1 waveforms are interpreted
as surface/near-surface events occurring at different epicentral distances across the array
(Deichmann and others, 2000; Mikesell and others, 2012). They have characteristics similar
to those produced by crevassing, with weak P-waves and dominant surface waves.

Due to the absence of surface waves, Type 2 waveforms resemble high frequency
intermediate or basal signals (Smith, 2006). Type 2 waveforms are rare and seldom
detected on more than two stations at once, making determination of their source location
difficult. In the majority of cases, Type 2 waveforms are only weakly detected on adjacent
stations or not detected at all, which suggests that the distance between the seismic source and the geophone receiver is less than the inter-station spacing (West and others, 2010), that is, less than 170 m for station CS which is located in an area where the depth to the bed is known to be ~250 m. Moreover, the observed P- and S-wave separation time for many Type 2 waveforms is <0.01s which is far too short for basal events. The majority of Type 2 waveforms show a P-wave with sub-horizontal linear particle motion oriented perpendicular to ice flow, implying a non-vertical propagation path for P waves. As such, we interpret Type 2 waveforms not as basal signals but as near-field events from intermediate depth (where we define ‘near-field’ as significantly closer to one station than any other such that for small events little or no energy can be identified above the background noise at adjacent stations).

Type 3 waveforms are episodic and high frequency (260 Hz dominant in Fig. 3e). They only occur on one or two stations simultaneously, and are most frequently detected on Stations CS, CC and BW. As with Type 2 waveforms, the failure to detect Type 3 waveforms on all stations suggests that these are near-field events. The lack of, or inability to discriminate, P- and S-waves also suggests Type 3 waveforms are generated by near-field events. However, Type 3 waveforms lack high-amplitude surface waves and each episode has a strong and impulsive onset, which suggests these events are not formed by the surface processes related to crevassing that generate Type 1 waveforms. The origin of Type 3 waveforms requires further investigation.

West and others (2010) identified a hybrid waveform on the Bering Glacier, Alaska, having impulsive high-frequency onset followed by a slow decaying low-frequency tail. The hybrid waveform was interpreted as the product of brittle ice fracture followed by the flow of pressurized water into the fracture and reverberation. Englacial fracturing in the overdeepening of Storglaciären may generate similar hybrid signals. Occasionally, Type 1 waveforms are immediately preceded by high frequency events (often similar to Type 2 waveforms) and it is possible that this is a high frequency-low frequency hybrid waveform (Fig. 3). One other possible explanation is the excitation of the spurious modes of resonance of the geophones due to adverse tilt (Faber and Maxwell, 1997). However, the specified first spurious resonant frequency of the I/O SM6 4.5 Hz geophone is 140 Hz, significantly different to that observed here.

FIGURE 3

DISCUSSION

Basal signals

Borehole experiments suggest that Storglaciären’s flow dynamics are dominated by basal sliding, and that stick-slip motion and sticky-spots occur (Iverson and others, 1995; Fischer
As such, it is surprising that no clear basal signals have been detected. We propose three hypotheses for the failure to detect basal signals.

**Hypothesis 1: Pervasive soft-bed deformation is widespread throughout the ablation area and generates few basal signals**

Fast glacier flow associated with pervasive soft-bed deformation generates few basal signals in Antarctic ice streams (Smith, 2006), although some basal signals are detected. A dilatant till that is pervasively deforming reduces friction and causes little basal fracturing within the ice, and so generates little seismic activity. Although soft-bed deformation has been observed in the upper ablation area (Uaa) and lower ablation area (Laa) of Storglaciären (Iverson and others 2002), basal sliding is thought to be the more important control of flow dynamics because the till is not deforming uniformly and the depth of deformation is limited to ~35cm (Iverson and others, 1995; Fischer and others, 1996). The presence of regelation ice in the basal ice facies at the contemporary glacier margin, and lodged stoss and lee boulders with flow-parallel striations in proglacial exposures of subglacial till (Cook, pers. comm), demonstrate that basal sliding has been an important component of Storglaciären’s recent flow dynamics. Moreover, the clast-rich and coarse grained subglacial till which is now exposed on the forefield reveals strong flow-parallel clast fabrics indicative of strong glacier-bed coupling, and shows evidence of grain bridging, clast crushing and clast/boulder lodgement, which suggests that at least part of the glacier’s basal shear stress has previously been taken up by clast-rich and boulder-rich sticky spots. We suggest a similar mosaic of sticky and deforming spots exists beneath the present glacier because till strain rates vary with changes in effective pressure, which are controlled by local variations in basal water pressure (Iverson and others, 1995). As such, pervasive soft-bed deformation is unlikely to be uniform or continuous throughout the ablation area and cannot be used by itself to explain the absence of basal signals.

**Hypothesis 2: Basal sliding does not generate basal signals in temperate ice**

Basal sliding accounts for 60-70% of the surface velocity of polythermal Storglaciären (Jansson, 1995) and yet no basal signals have been detected. Likewise, Walter and others (2008) found no link between basal sliding and the generation of basal signals in warm-based Gornergletscher, Switzerland. The subglacial environment of Storglaciären’s Uaa consists of temperate ice and is characterised by consistently high basal water pressures which probably produce a zone of low basal drag (Holmlund and Jansson, 2002). Few basal ice fractures or sticky spots are likely to develop in a zone of low basal drag, especially if temperate ice deforms plastically around bed asperities, and this may help to explain the absence of basal signals in the Uaa. Stuart and others (2005) also found a region where no
basal signals were detected up-glacier of the surging wave front on polythermal
Bakaninbreen, Svalbard, which they attributed to plastic failure in a zone of temperate ice.

However, basal water pressures and basal drag are more variable in Storglaciären’s Laa
and this gives the potential for basal signals to be generated by various mechanisms. High
basal water pressures are thought to periodically and locally decouple the glacier from its
bed in the Laa, which leads to flow accelerations through basal slip, with resistance to flow
being taken up by sticky spots or lateral drag (Iverson and others, 1995). Flow accelerations
also occur in the Uaa but are out of phase with variations in basal water pressure (Jansson,
1995; Fischer and others, 1996). Although high basal water pressures reduce effective
pressure, till strain rates reduce to a minimum during glacier-bed decoupling and basal
signals could be generated as the soft-bed relaxes elastically in shear (Fischer and Clarke,
2001). Furthermore, Walter and others (2008) demonstrated that extensional fractures occur
in temperate basal ice when a glacier re-couples to its bed as basal water pressures fall, and
this process produces clusters of basal signals. If this is correct, then re-coupling processes
should periodically generate basal signals in the Laa as basal water pressures fall.
Theoretically, basal signals are also likely to be produced at sticky spots throughout the
ablation area where patches of cold-based ice or stiff till fracture. As such, it is surprising that
no basal signals have been detected, especially on Station FE which straddles the Uaa/Laa
boundary.

Hypothesis 3: Basal signals are rare and difficult to detect in temperate glaciers or
polythermal glaciers that largely consist of temperate ice

We suggest that this is the most likely reason for failing to detect basal signals for three
reasons:

a) Low signal to noise ratio. Various processes, such as supraglacial and englacial water
flow, help to generate a noisy environment on valley glaciers, especially during the day, and
even after filtering this can make it difficult to recognise unique events and to accurately pick
P- and S-wave arrival times on seismic traces. By contrast, seismic data sets from the
Antarctic ice streams are characterised by low ambient noise levels.

b) High frequency basal events are swamped by the thousands of near-field, long period,
and high amplitude surface events that occur every day. Now that waveform characterisation
is complete, future investigations will focus on whether it is possible to use known surface
events to run a null based cross-correlation that removes any matching waveforms from the
data set, and which leaves behind only the anomalous and non-surface waveforms.

c) Body waves are of significantly lower amplitude than surface waves for a given epicentral
distance due to both greater attenuation of the higher frequency content and spherical rather
than cylindrical geometrical spreading losses. Also, at a glacier’s surface, high frequency waveforms can be preferentially attenuated by dense networks of crevasses (Walter and others, 2008). High frequency basal signals may also be attenuated by a dense system of water-filled englacial fractures. It is known that water is mainly routed through the main overdeepening of Storglaciären via an interconnected system of englacial fractures which typically have openings 40 mm wide and dip at 70°, and which have been observed to extend to a depth of 131 m (Fountain and others, 2005). Some fractures are water-filled, although water flows slowly through them, and may drain to the bed. The origin of the fractures is unknown but the lack of basal signals suggests they are probably not formed by basal crevassing. The fractures may be formed in situ by extensional flow through the overdeepening or by hydro-fracturing. It is possible that bi-modal high frequency/low frequency hybrid waveforms could be generated by the opening of englacial fractures and the subsequent flow of water into the fracture, and this requires further investigation.

Practical data-collection issues encountered and associated recommendations

The high ablation rate on Storglaciären caused problems throughout the experiment. Air temperatures near to the array reached 9.8°C at 1382 m altitude by late-July, with melt of up to 10 cm per day (Matthews, pers. comm). Initial deployment of the seismic array was delayed because meltwater could not penetrate the impermeable cold ice surface layer, resulting in pools forming on the glacier surface and in the pits dug for the geophones. As the melt season progressed, the glacier drainage system became more organised and sufficient surface meltwater was evacuated to allow the stations to be established.

The high ablation rate, combined with several severe storms with wind speeds in excess of 35 ms\(^{-1}\), meant that each seismic station had to be re-deployed at the same site on four separate occasions because cairns had collapsed and cables and geophones had become exposed, or the geophones were so badly tilted they required re-levelling. Our experience is that each station requires monitoring on an almost daily basis to combat these issues and maximise the duration over which quality data are obtained. The frequency of re-deployment could be reduced by action to minimise the melt rate around each station. One possibility would be to paint or coat equipment with a high albedo material, or geotextile covers could be used to cover equipment and blanket the surface around each station. Geotextile covers such as IceProtector 500 and Toptex 350 have been shown to reduce snow melt by up to 65% in alpine and arctic regions (Olefs and Fischer, 2008; Pomeroy, 2009). An alternative approach would be to deploy the array in autumn, allowing the geophones to freeze-in, and recovering it in spring. Basal sliding is thought to occur all year long on Storglaciären, although the glacier is less dynamically active when basal water pressures are reduced (Holmlund and Jansson, 2002), and the reduction in noise from flowing water might afford a
better chance of detecting basal signals. However, winter conditions place restrictions on the

use of solar panels, so alternative power sources would be required.

Achieving and maintaining a good coupling between the geophone and an uneven glacier

ice surface at the base of an excavated pit proved to be problematic. The 3-component

geophones must be kept approximately level to maximise data quality. Our method of

inserting a pre-moulded concrete block at the base of each pit provided a good solution. The

use of concrete blocks helped to keep the geophones level, correctly orientated, and

provided a good geophone-glacier coupling.

CONCLUSION

Passive seismology experiments are rendered difficult on glaciers with high surface ablation

rates and careful station design is required to mitigate its effects. Protecting stations with

geotextile covers is one possibility. The data from Storglaciären is consistent with that

collected on temperate glaciers in that basal microseismic signals are rare/absent and/or
difficult to detect. The reasons for this are uncertain, but we hypothesise that it may result

from: (a) consistently high basal water pressures in Storglaciären’s upper ablation area

creating a zone of low basal drag which, combined with soft-bed deformation, may create

conditions where few basal signals are generated; (b) the plastic deformation associated

with temperate ice failing to generate microseismic signals, despite the major contribution of

basal sliding to glacier flow; (c) basal signals being difficult to detect on glaciers consisting of

mainly temperate ice because they are drowned out by other signals or preferentially

attenuated by a dense network of water-filled englacial fractures. Although we have failed to

recognise microseismic evidence of glacier the focus of future work.

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### Table 1. Typical and atypical waveforms

<table>
<thead>
<tr>
<th>Waveform</th>
<th>Type 1a</th>
<th>Type 1b</th>
<th>Type 1c</th>
<th>Type 2</th>
<th>Type 3</th>
</tr>
</thead>
<tbody>
<tr>
<td>Onset</td>
<td>Impulsive P.</td>
<td>Weak impulsive to emergent P; S difficult to pick.</td>
<td>Relatively weak but impulsive P; S difficult to pick.</td>
<td>Impulsive P and S.</td>
<td>Impulsive P but lack of P-S separation suggests near-field event.</td>
</tr>
<tr>
<td></td>
<td>Sharp peak soon after onset on all channels, but decays across array.</td>
<td>Highest amplitude surface waves have broader, higher and more rounded peaks than Type 1a.</td>
<td>Event builds towards later and more pronounced peaks than in Type 1a and Type 1b. Occasionally coda has short high frequency onset and long, decaying, low frequency tail.</td>
<td>Strong early peak, P wave strongest on Z-axis (vertical), S on N or E axis.</td>
<td>Episodic event with sharp peaks, often forms cigar-shaped coda.</td>
</tr>
<tr>
<td>Amplitude</td>
<td>Mainly (relatively) low frequency, 10-100 Hz, peaks at 10-20, and 60-80 Hz, small component &gt;100 Hz.</td>
<td>Low frequency 10-100 Hz, removed by high pass filter (100 Hz) as lack higher frequency component of Type 1c events.</td>
<td>Wide range, with distinct peaks at 10-50 Hz and &gt; 100 Hz. Some have low frequency spike at 3 Hz.</td>
<td>High frequency, &gt;100 Hz.</td>
<td>Very high frequency event, peaks at 150-250 Hz and 400 Hz+.</td>
</tr>
<tr>
<td></td>
<td>Typically 0.5 s, but &lt; 1 s.</td>
<td>&lt; 1 s.</td>
<td>Typically 0.5 s.</td>
<td>Short, &lt;0.1 s, but 'apparent' P and S-wave separation &lt; 0.01 s for many events.</td>
<td>Typically 3-5s, but can be up to 14s. Consists of multiple pulses each lasting between 0.03 s and 0.06 s, with a 0.175 s interval between each.</td>
</tr>
<tr>
<td>Duration</td>
<td>Relatively common on all stations, especially during the day when recorded first on Station CC, but less so than Type 1b/1c. Event moves relatively slowly across array, losing amplitude.</td>
<td>Very common, especially at night. Usually hit Station BW or CS first and move across array losing amplitude in this order: BW or CS – CC – CN – FE, or can be FE-BW in direction. Surface events.</td>
<td>Very common, especially during the day. Usually hit station CS, CC, or CN first and lose amplitude across array. May cluster along centre line of glacier.</td>
<td>Rare, mostly detected in early morning 03.00-05.00 hrs local time. Single events seldom detected on more than one or two channels. Occasionally precede Type 1c events.</td>
<td>Become more common towards end of July, especially at night. Less common during early July. Can get repeated episodic events with up to 13 events per hour, but typically only detected on one station.</td>
</tr>
<tr>
<td>Distribution</td>
<td>Type 1 waveforms, with their dominant frequencies of 10-100 Hz, impulsive onsets, strong R-waves, weak P-waves, and durations of &lt;1s, are typical of waveforms produced by ice quakes related to the opening and closing of crevasses (Neave and Savage, 1970). Hydraulic transients have been observed to produce waveforms with a frequency of 3 Hz, but unlike type 1c events they have harmonic tremor and a decaying sine wave associated with resonance in water filled cavities (Stuart and others, 2005). Hybrid forms might exist. Type 1b and Type 1c events are occasionally preceded by, or merged with, a short duration high frequency event. Bi-modal high-frequency/low-frequency hybrid waveforms may be produced by ice fracture followed by the flow and reverberation of pressurised water into the fracture (West and others, 2010); may be related to the formation of englacial fractures.</td>
<td>Type 2 events resemble basal events. However, P and S-wave separation too short to be basal signals for many events. Weak signature on adjacent stations and polarisation analysis suggests near-field origin, most likely of intermediate depth.</td>
<td>High frequency episodic events with impulsive onset. Particle motions of Type 3 events are indicative of a near-field origin. Origin unknown.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Table 2. Example of temporal distribution of microseismic events by type. Data are for number of events detected on 3 or more stations on 14 July 2010.

<table>
<thead>
<tr>
<th>Station on which event first detected</th>
<th>03:00 – 04:00 hours (100 events)</th>
<th>15:00 -16:00 hours (105 events)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Type 1a</td>
<td>Type 1b</td>
</tr>
<tr>
<td>CN</td>
<td>2</td>
<td>0</td>
</tr>
<tr>
<td>CS</td>
<td>8</td>
<td>5</td>
</tr>
<tr>
<td>BW</td>
<td>2</td>
<td>58</td>
</tr>
<tr>
<td>CC</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>Total</td>
<td>12</td>
<td>63</td>
</tr>
<tr>
<td>Total (%)</td>
<td>12.0</td>
<td>63.0</td>
</tr>
</tbody>
</table>

*Type 3 events can be more common at night with up to 13 events of between 3-5 s/hr detected towards the end of July.
**FIGURE CAPTIONS**

**Fig. 1.** Schematic representation of potential sources of microseismic signals from Storglaciären. (1) Stick-slip movements resulting in basal faulting and clusters of basal signals. Average surface velocity of glacier is 35 mm/day, but with a maximum of up to 100 mm/day (Holmlund and Jansson, 2002). Glacier accelerates with extensional flow across riegel. Glacier flow rate varies over short timescales. (2) Brittle fracture related to crevassing. (3) Brittle fracture related to opening/closing of englacial fractures – possible complex hybrid waveforms. (4) Hydraulic transients related to water flow and widening of crevasses/fractures/conduits. Moulins and crevasses route water to the bed in the lower ablation area, where there are wide variations in basal water pressures. High basal water pressures decouple glacier from bed and linked to flow accelerations, but reduced shearing in tills. (5) Decoupling/recoupling of glacier to bed may generate brittle fracture and basal signals. Basal water pressures 60-80% of overburden pressure in main overdeepening, which may be a zone of low basal drag, but is more variable in the lower ablation area (Holmlund and Jansson, 2002). (6) Non-uniform till deformation – release of elastic strain energy through brittle failure at sticky spots or bed relaxing in shear during decoupling. (7) Hydraulic jacking in water-filled cavities pulls the glacier forward; hydraulic jacking may produce englacial/subglacial signals and hydraulic transients. Other sources: rockfalls, serac collapse, atmospheric noise, anthropogenic noise.

**Fig. 2.** Location diagram for Storglaciären and the disposition of the seismic array over the main overdeepening.

**Fig. 3.** Examples of waveforms detected at Storglaciären. The amplitudes of the traces are event normalised. (A) Relatively rare type 2 event resembling a basal signal recorded on 2 stations. Note the impulsive P wave onset and high frequency (100 Hz high pass filter applied). (B) Type 1a event detected first on station CS with impulsive onset and rapidly decaying in amplitude across the array. (C) Type 1b event. Note the weak P wave onset and strong high amplitude surface wave arrivals. Type 1b events are largely removed by a 100 Hz high pass filter. (D) Type 1c event. Note the weak P wave onset. Type 1c events contain a significant higher frequency component which is not removed by a 100 Hz high pass filter and builds to a later and higher peak than Type 1a events. (E) Type 3 event recorded on one station. Episodic type 3 events can last for up to 14 seconds. Dashed box indicates location of (F). (F) Detail of Type 3 events showing high frequency and impulsive onset.
upper ablation area
main overdeepening

1. 60-70% glacier flow due to basal sliding

maximum glacier thickness 250m

2. Water routed through interconnected englacial fractures

3. Compressional flow in overdeepening

4. Extensional flow across riegel

5. Soft-bed of 30-70cm thick till.

6. Pervasive deformation controlled by variations in effective pressure. Glacier flow is out of phase with variations in basal water pressure and till strain rate in overdeepening, resistance to flow from lateral drag and/or sticky spots

lower ablation area

7. Sydakk (south stream) flows subglacially, dendritic drainage system develops later in summer

average glacier thickness 100m

4. Moulins and crevasses route water to bed.