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GENERALIZED OSCILLATORY INTEGRALS AND FOURIER INTEGRAL OPERATORS

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Abstract In this paper, a theory is developed of generalized oscillatory integrals (OIs) whose phase functions and amplitudes may be generalized functions of Colombeau type. Based on this, generalized Fourier integral operators (FIOs) acting on Colombeau algebras are defined. This is motivated by the need for a general framework for partial differential operators with non-smooth coefficients and distribution data. The mapping properties of these FIOs are studied, as is microlocal Colombeau regularity for OIs and the influence of the FIO action on generalized wavefront sets.

Keywords: algebras of generalized functions; Fourier integral operators; microlocal analysis

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1. Introduction

This paper is part of a programme that seeks to solve linear partial differential equations with non-smooth coefficients and strongly irregular data and to study the qualitative properties of the solutions. While a well-established theory with powerful analytic methods is available in the case of operators with (relatively) smooth coefficients [18], many models from physics involve non-smooth variations of the physical parameters and consequently require partial differential operators where the smoothness assumption on the coefficients is dropped. Typical examples are equations that describe the propagation of elastic waves in discontinuous media with point sources or stationary solutions of such equations with strongly singular potential. In such cases, the theory of distributions does not provide a general framework in which solutions exist because of the structural restraint in dealing with nonlinear operations (see [22, 26, 31]), such as the product of a discontinuous function with the prospective solution.
An alternative framework is provided by the theory of Colombeau algebras of generalized functions \([4, 16, 31]\). In this setting, multiplication of distributions is possible and generalized solutions can be obtained that solve the equations in a strict differential-algebraic sense. By interpreting the non-smooth coefficients and data as elements of the Colombeau algebra, the existence and uniqueness have now been established for many classes of equations \([1–3, 5, 20, 24, 27, 29, 31–33, 35]\). In order to study the regularity of solutions, microlocal techniques (in particular, pseudodifferential operators with generalized amplitudes and generalized wavefront sets) must be introduced into this setting. This has been done in the papers \([13–15, 19, 21, 23, 25, 28, 34]\) concerning elliptic equations and hypoellipticity.

As in the classical case, Fourier integral operators arise prominently in the study of solvability of hyperbolic equations, regularity of solutions and the inverse problem (determining the non-smooth coefficients from the data: an important problem in geophysics \([6]\)). In the case of differential operators with coefficients belonging to the Colombeau algebras, this leads to Fourier integral operators with generalized amplitudes and generalized phase functions. The purpose of this paper is to develop the theory of that type of Fourier integral operators and to derive first results on propagation of singularities.

We begin with the following observation. Suppose generalized Fourier integral operators have been defined as acting on a Colombeau algebra (as will be done in this paper). Evaluating the result at a point produces a map from the Colombeau algebra into the ring of generalized constants \(\tilde{\mathbb{C}}\), that is, an element of the dual of the Colombeau algebra. In this way, the notion of a dual of a Colombeau algebra enters, that is, the space of \(\tilde{\mathbb{C}}\)-linear maps which are continuous with respect to the so-called sharp topology. Thus, regularity not only of Colombeau generalized functions but also of the elements of the dual space is to be investigated. Within the Colombeau algebra \(\mathcal{G}(\Omega)\) (\(\Omega\) is an open subset of \(\mathbb{R}^n\)), regularity theory is based on the subalgebra \(\mathcal{G}^\infty(\Omega)\) whose intersection with \(\mathcal{D}'(\Omega)\) coincides with \(\mathcal{C}^\infty(\Omega)\). An element of the dual can be regular in more subtle ways; it may be defined by an element of \(\mathcal{G}(\Omega)\) or by an element of \(\mathcal{G}^\infty(\Omega)\). Thus, for elements of the dual, two different notions of singularity arise: the \(\mathcal{G}\)-singular support and the \(\mathcal{G}^\infty\)-singular support (and similarly for the wavefront sets).

Having said this, we can now describe the contents of the paper in more detail. In §2 we collect the material from Colombeau theory that we need. In particular, we recall topological notions, generalized symbols and various tools for studying regularity. Furthermore, the \(\mathcal{G}(\Omega)\)-wavefront and \(\mathcal{G}^\infty(\Omega)\)-wavefront set of a functional on the Colombeau algebra is introduced. In §3, we develop the foundations for generalized Fourier integral operators: oscillatory integrals with generalized phase functions. As in the classical case, a generalized phase function is homogeneous of degree 1 in its second variable. The classical condition that the gradient should not vanish has to be replaced by invertibility of the norm of the gradient as a Colombeau generalized function. Generalized oscillatory integrals are then supplemented by an additional parameter in §4, leading to the notion of a Fourier integral operator with generalized amplitude and phase function. We study the mapping properties of such operators on Colombeau algebras. As has been noticed in elliptic theory \([15, 24]\), two asymptotic scales are required with respect to regularity.
theory using $G^\infty(\Omega)$: the usual scale defining the representatives of the elements of the Colombeau algebra and the so-called slow scale. We show that Fourier integral operators with slow-scale phase function and regular amplitude map $G^\infty(\Omega)$ into itself. Section 4 also contains an example indicating how such operators arise from first-order hyperbolic equations with non-smooth coefficients. Section 5 is devoted to investigating in more detail the functionals that are given by generalized oscillatory integrals on the Colombeau algebra. We study the regions on which the norm of the gradient of the phase function is not invertible and its complement. Both regions come in two different versions, depending the asymptotic scale chosen (i.e. normal scale or slow scale), which in turn correspond to $G$-regularity or $G^\infty$-regularity. We find bounds on the wavefront set of these functionals, again with respect to the two notions of regularity. In the case of classical phase functions, these bounds reduce to the classical ones involving the conic support of the amplitude and the critical set of the phase function. In the generalized case, this condition can only be formulated by a more complicated condition of non-invertibility. We show how this condition of non-invertibility can be used to compute the generalized wavefront set of the kernel of the Fourier integral operator arising from first-order hyperbolic equations. The development of a complete calculus of generalized Fourier integral operators has been initiated in [12] and will be the subject of future research as well as the connection with symplectic geometry and application to weakly hyperbolic problems.

2. Basic notions: Colombeau and duality theory

This section gives some background on Colombeau and duality theory for the techniques used throughout the current paper. As main sources we refer the reader to [9, 10, 13, 15, 16].

2.1. Nets of complex numbers

Before dealing with the major points of the Colombeau construction we begin by recalling some definitions concerning elements of $\mathbb{C}^{(0,1]}$.

A net $(u_\varepsilon)_\varepsilon$ in $\mathbb{C}^{(0,1]}$ is said to be strictly non-zero if there exist $r > 0$ and $\eta \in (0, 1]$ such that $|u_\varepsilon| \geq \varepsilon^r$ for all $\varepsilon \in (0, \eta]$.

The regularity issues discussed in §§ 4 and 5 will make use of the following concept of slow-scale net (s.s.n.). A slow-scale net is a net $(r_\varepsilon)_\varepsilon \in \mathbb{C}^{(0,1]}$ such that

$$\forall q \geq 0 \quad \exists c_q > 0 \quad \forall \varepsilon \in (0, 1], \quad |r_\varepsilon|^q \leq c_q \varepsilon^{-1}.$$  

A net $(u_\varepsilon)_\varepsilon$ in $\mathbb{C}^{(0,1]}$ is said to be slow-scale-strictly non-zero if there exist a slow-scale net $(s_\varepsilon)_\varepsilon$ and $\eta \in (0, 1]$ such that $|u_\varepsilon| \geq 1/s_\varepsilon$ for all $\varepsilon \in (0, \eta]$.

2.2. $\tilde{\mathbb{C}}$-modules of generalized functions based on a locally convex topological vector space $E$

The most common algebras of generalized functions of Colombeau type as well as the spaces of generalized symbols we deal with are introduced and investigated under a topological point of view by referring to the following models.
Let $E$ be a locally convex topological vector space topologized through the family of semi-norms $\{p_i\}_{i \in I}$. The elements of
\[
M_E := \{ (u_ε) \in E^{[0,1]} : \forall i \in I \exists N \in \mathbb{N}, \ p_i(u_ε) = O(ε^{-N}) \text{ as } ε \to 0 \},
\]
\[
M_E^sc := \{ (u_ε) \in E^{[0,1]} : \forall i \in I \exists (ω_ε) \text{s.s.n.}, \ p_i(u_ε) = O(ω_ε) \text{ as } ε \to 0 \},
\]
\[
M_E^∞ := \{ (u_ε) \in E^{[0,1]} : \forall N \in \mathbb{N} \forall i \in I, \ p_i(u_ε) = O(ε^{-N}) \text{ as } ε \to 0 \},
\]
\[
N_E := \{ (u_ε) \in E^{[0,1]} : \forall i \in I \forall q \in \mathbb{N}, \ p_i(u_ε) = O(ε^q) \text{ as } ε \to 0 \}
\]
are called $E$-moderate, $E$-moderate of slow-scale type, $E$-regular and $E$-negligible, respectively. We define the space of \textit{generalized functions based on $E$} as the factor space $G_E := M_E/N_E$.

The ring of \textit{complex generalized numbers}, denoted by $\hat{C}$, is obtained by taking $E = \mathbb{C}$. $\hat{C}$ is not a field since, by [16, Theorem 1.2.38], only the elements that are strictly non-zero (i.e. the elements which have a representative strictly non-zero) are invertible and vice versa. Note that all the representatives of $u \in \hat{C}$ are strictly non-zero since we know that there exists at least one which is strictly non-zero. When $u$ has a representative that is slow-scale–strictly non-zero we say that it is \textit{slow-scale invertible}.

For any locally convex topological vector space $E$, the space $G_E$ has the structure of a $\hat{C}$-module. The $\hat{C}$-module $G_E^c := M_E^c/N_E$ of \textit{generalized functions of slow-scale type} and the $\hat{C}$-module $G_E^∞ := M_E^∞/N_E$ of \textit{regular generalized functions} are subrings of $G_E$ with more refined assumptions of moderateness at the level of representatives. We use the notation $u = [(u_ε)]$ for the class of $(u_ε) \in G_E$. This is the usual way adopted in the paper to denote an equivalence class.

The family of semi-norms $\{p_i\}_{i \in I}$ on $E$ determines a \textit{locally convex $\hat{C}$-linear topology} on $G_E$ (see [9, Definition 1.6]) by means of the \textit{valuations}
\[
v_{p_i}([(u_ε)]) := v_{p_i}((u_ε)) := \sup\{ b \in \mathbb{R} : p_i(u_ε) = O(ε^b) \text{ as } ε \to 0 \}
\]
and the corresponding \textit{ultra-pseudo-semi-norms} $\{P_i\}_{i \in I}$. For the sake of brevity we omit definitions and properties of valuations and ultra-pseudo-semi-norms in the abstract context of $\hat{C}$-modules. Such a theoretical presentation can be found in [9, §§1.1 and 1.2]. We recall that on $\hat{C}$ the valuation and the ultra-pseudo-norm obtained through the absolute value in $\mathbb{C}$ are denoted by $v_C$ and $|.|_C$, respectively. Concerning the space $G_E^∞$ of regular generalized functions based on $E$ the moderateness properties of $M_E^∞$ allows us to define the valuation
\[
v_E^∞((u_ε)) := \sup\{ b \in \mathbb{R} : \forall i \in I, \ p_i(u_ε) = O(ε^b) \text{ as } ε \to 0 \},
\]
which extends to $G_E^∞$ and leads to the ultra-pseudo-norm $P_E^∞(u) := e^{-v_E^∞(u)}$.

The Colombeau algebra $G(Ω) = E_M(Ω)/N(Ω)$ can be obtained as a $\hat{C}$-module of $G_E$ type by choosing $E = E(Ω)$. Topologized through the family of semi-norms $P_{K,i}(f) = \sup_{x \in K, |α| \leq i} |D^α f(x)|$, where $K \subseteq Ω$, the space $E(Ω)$ induces on $G(Ω)$ a metrizable and complete locally convex $\hat{C}$-linear topology which is determined by the ultra-pseudo-semi-norms $P_{K,i}(u) = e^{-v_{P_{K,i}}(u)}$. $G(Ω)$ is continuously embedded in each
tools for dealing with the topological duals of the Colombeau algebras \( \hat{G}(\Omega) \) since \( \mathcal{E}_M(\Omega) \cap N_{\mathcal{C}^k(\Omega)} \subseteq \mathcal{E}_M(\Omega) \cap N_{\mathcal{G}^\infty(\Omega)} = N(\Omega) \) and the topology on \( \hat{G}(\Omega) \) is finer than the topology induced by any \( \mathcal{G}^\infty(\Omega) \) on \( G(\Omega) \). From a structural point of view, \( \Omega \to \hat{G}(\Omega) \) is a fine sheaf of differential algebras on \( \mathbb{R}^n \).

The Colombeau algebra \( G_\epsilon(\Omega) \) of generalized functions with compact support is topologized by means of a strict inductive limit procedure. More precisely, setting \( G_K(\Omega) := \{ u \in G_\epsilon(\Omega) : \text{supp } u \subseteq K \} \) for \( K \in \Omega \), \( G_\epsilon(\Omega) \) is the strict inductive limit of the sequence of locally convex topological \( \hat{C} \)-modules \( (G_K(\Omega))_{n \in \mathbb{N}} \), where \( (K_n)_{n \in \mathbb{N}} \) is an exhausting sequence of compact subsets of \( \Omega \) such that \( K_n \subseteq K_{n+1} \). We recall that the space \( G_K(\Omega) \) is endowed with the topology induced by \( G_{D_{K'}(\Omega)} \), where \( K' \) is a compact subset containing \( K \) in its interior. In detail, we consider on \( G_K(\Omega) \) the ultra-pseudo-semi-norms \( P_{G_K(u)}(u) = e^{-v_{K,n}(u)} \). Note that the valuation \( v_{K,n}(u) := v_{P_{G_{K'}(\Omega)}}(u) \) is independent of the choice of \( K' \) when it acts on \( G_K(\Omega) \).

Regularity theory in the Colombeau context as initiated in [31] is based on the subalgebra \( G^\infty(\Omega) \) of all elements \( u \) of \( G(\Omega) \) having a representative \( (u_\epsilon)_\epsilon \) belonging to the set

\[
\mathcal{E}_M^\infty(\Omega) := \left\{(u_\epsilon)_\epsilon \in \mathcal{E}[\Omega] : \forall K \in \Omega \ \exists N \in \mathbb{N} \right. \\
\left. \forall \alpha \in \mathbb{N}^n, \sup_{x \in K} |\partial^\alpha u_\epsilon(x)| = O(\epsilon^{-N}) \text{ as } \epsilon \to 0 \right\},
\]

\( G^\infty(\Omega) \) can be seen as the intersection \( \bigcap_{K \in \Omega} G^\infty(K) \), where \( G^\infty(K) \) is the space of all \( u \in G(\Omega) \) having a representative \( (u_\epsilon)_\epsilon \) satisfying the following condition: there exists \( N \in \mathbb{N} \) for all \( \alpha \in \mathbb{N}^n, \sup_{x \in K} |\partial^\alpha u_\epsilon(x)| = O(\epsilon^{-N}) \). The ultra-pseudo-semi-norms \( P_{G^\infty(K)}(u) = e^{-v_{G^\infty(K)}} \), where

\[ v_{G^\infty(K)} := \sup_{b \in \mathbb{R}} \left\{ \alpha \in \mathbb{N}^n, \sup_{x \in K} |\partial^\alpha u_\epsilon(x)| = O(\epsilon^b) \right\}. \]

equip \( G^\infty(\Omega) \) with the topological structure of a Fréchet \( \hat{C} \)-module.

Finally, let us consider the algebra \( G^\infty_\epsilon(\Omega) := G^\infty(\Omega) \cap G_\epsilon(\Omega) \). On \( G^\infty_\epsilon(\Omega) := \{ u \in G^\infty(\Omega) : \text{supp } u \subseteq K \} \) with \( K \in \Omega \), we define the ultra-pseudo-norm \( P_{G^\infty_\epsilon(K)}(u) = e^{-v_{G^\infty_\epsilon(K)}}(u) \) and \( K' \) is any compact set containing \( K \) in its interior. At this point, given an exhausting sequence \( (K_n)_{n} \) of compact subsets of \( \Omega \), the strict inductive limit procedure equips \( G^\infty_\epsilon(\Omega) = \bigcup_n G^\infty_{K_n}(\Omega) \) with a complete and separated locally convex \( \hat{C} \)-linear topology.

### 2.3. Topological dual of a Colombeau algebra

A duality theory for \( \hat{C} \)-modules had been developed in [9] in the framework of topological and locally convex topological \( \hat{C} \)-modules. Starting from an investigation of \( L(G, \hat{C}) \), the \( \hat{C} \)-module of all \( \hat{C} \)-linear and continuous functionals on \( G \), it provides the theoretical tools for dealing with the topological duals of the Colombeau algebras \( G_\epsilon(\Omega) \) and \( G(\Omega) \). Throughout the paper, \( L(G(\Omega), \hat{C}) \) and \( L(G_\epsilon(\Omega), \hat{C}) \) are endowed with the topology of uniform convergence on bounded subsets. This is determined by the ultra-pseudo-semi-norms

\[ P_{B^*}(T) = \sup_{u \in B} |T(u)|_\epsilon, \]
where $B$ is varying in the family of all bounded subsets of $\mathcal{G}(\Omega)$ and $\mathcal{G}_c(\Omega)$, respectively. From general results concerning the relation between boundedness and ultra-pseudo-semi-norms in the context of locally convex topological $\mathcal{C}$-modules, we have that $B \subseteq \mathcal{G}(\Omega)$ is bounded if and only if for all $K \subseteq \Omega$ and $i \in \mathbb{N}$ there exists a constant $C > 0$ such that $\mathcal{P}_{K,i}(u) \leq C$ for all $u \in B$. In particular, the strict inductive limit structure of $\mathcal{G}_c(\Omega)$ yields that $B \subseteq \mathcal{G}_c(\Omega)$ is bounded if and only if it is contained in some $\mathcal{G}_K(\Omega)$ and bounded there if and only if

$$\exists K \subseteq \Omega \quad \forall n \in \mathbb{N} \quad \exists C > 0 \quad \forall u \in B, \quad \mathcal{P}_{\mathcal{G}_K(\Omega),i}(u) \leq C.$$  

For the choice of topologies illustrated in this section, [10, Theorem 3.1] shows the following chains of continuous embeddings:

\begin{align*}
\mathcal{G}^\infty(\Omega) &\subseteq \mathcal{G}(\Omega) \subseteq \mathcal{L}(\mathcal{G}_c(\Omega), \mathcal{C}), \quad (2.1) \\
\mathcal{G}_c^\infty(\Omega) &\subseteq \mathcal{G}_c(\Omega) \subseteq \mathcal{L}(\mathcal{G}(\Omega), \mathcal{C}), \quad (2.2) \\
\mathcal{L}(\mathcal{G}(\Omega), \mathcal{C}) &\subseteq \mathcal{L}(\mathcal{G}_c(\Omega), \mathcal{C}). \quad (2.3)
\end{align*}

In (2.1) and (2.2) the inclusion in the dual is given via integration ($u \to (v \to \int_\Omega u(x)v(x)\,dx)$) (for definitions and properties of the integral of a Colombeau generalized functions see [16]), while the embedding in (2.3) is determined by the inclusion $\mathcal{G}_c(\Omega) \subseteq \mathcal{G}(\Omega)$. Since $\Omega \to \mathcal{L}(\mathcal{G}_c(\Omega), \mathcal{C})$ is a sheaf, we can define the support of a functional $T$ (denoted by $\text{supp} T$). In analogy with distribution theory from [10, Theorem 1.2] we have that $\mathcal{L}(\mathcal{G}(\Omega), \mathcal{C})$ can be identified with the set of functionals in $\mathcal{L}(\mathcal{G}_c(\Omega), \mathcal{C})$ having compact support.

By (2.1) it is meaningful to measure the regularity of a functional in $\mathcal{L}(\mathcal{G}_c(\Omega), \mathcal{C})$ with respect to the algebras $\mathcal{G}(\Omega)$ and $\mathcal{G}^\infty(\Omega)$. We define the $\mathcal{G}$-singular support of $T$ (sing $\text{supp}_\mathcal{G} T$) as the complement of the set of all points $x \in \Omega$ such that the restriction of $T$ to some open neighborhood $V$ of $x$ belongs to $\mathcal{G}(V)$. Analogously, replacing $\mathcal{G}$ with $\mathcal{G}^\infty$ we introduce the notion of $\mathcal{G}^\infty$-singular support of $T$ denoted by sing $\text{supp}_\mathcal{G}^\infty T$. This investigation of regularity is connected with the notions of generalized wavefront sets considered in §2.5 and will be focused on the functionals in $\mathcal{L}(\mathcal{G}_c(\Omega), \mathcal{C})$ and $\mathcal{L}(\mathcal{G}(\Omega), \mathcal{C})$, which have a ‘basic’ structure. In detail, we say that $T \in \mathcal{L}(\mathcal{G}_c(\Omega), \mathcal{C})$ is basic if there exists a net $(T_\varepsilon)_\varepsilon \in \mathcal{D}'(\Omega)^{(0,1]}$ fulfilling the following condition: for all $K \subseteq \Omega$ there exist $j \in \mathbb{N}$, $c > 0$, $N \in \mathbb{N}$ and $\eta \in (0,1]$ such that

$$\forall f \in \mathcal{D}_K(\Omega) \quad \forall \varepsilon \in (0,\eta], \quad |T_\varepsilon(f)| \leq c\varepsilon^{-N} \sup_{x \in K, |\alpha| \leq j} |\partial^\alpha f(x)|$$

and $Tu = [(T_\varepsilon u_\varepsilon)_\varepsilon]$ for all $u \in \mathcal{G}_c(\Omega)$.

In the same way a functional $T \in \mathcal{L}(\mathcal{G}(\Omega), \mathcal{C})$ is said to be basic if there exists a net $(T_\varepsilon)_\varepsilon \in \mathcal{E}'(\Omega)^{(0,1]}$ such that there exist $K \subseteq \Omega$, $j \in \mathbb{N}$, $c > 0$, $N \in \mathbb{N}$ and $\eta \in (0,1]$ with the property

$$\forall f \in \mathcal{C}^\infty(\Omega) \quad \forall \varepsilon \in (0,\eta], \quad |T_\varepsilon(f)| \leq c\varepsilon^{-N} \sup_{x \in K, |\alpha| \leq j} |\partial^\alpha f(x)|$$

and $Tu = [(T_\varepsilon u_\varepsilon)_\varepsilon]$ for all $u \in \mathcal{G}(\Omega)$.
Clearly, the sets of basic functionals are \( \mathcal{C} \)-linear subspaces of \( \mathcal{L}(\mathcal{G}_c(\Omega), \mathcal{C}) \) and \( \mathcal{L}(\mathcal{G}(\Omega), \mathcal{C}) \) respectively. In addition, if \( T \) is a basic functional in \( \mathcal{L}(\mathcal{G}_c(\Omega), \mathcal{C}) \) and \( u \in \mathcal{G}_c(\Omega) \), then \( uT \in \mathcal{L}(\mathcal{G}(\Omega), \mathcal{C}) \) is basic. We recall that the nets \( (T_x)_x \), which define basic maps as above, were considered in [7, 8] with slightly more general notions of moderateness and different choices of notation and language.

2.4. Generalized symbols

For the convenience of the reader we recall a few basic notions concerning the sets of symbols employed in the course of the paper.

Definitions

Let \( \Omega \) be an open subset of \( \mathbb{R}^n, m \in \mathbb{R} \) and \( \rho, \delta \in [0, 1] \). \( S^m_{\rho, \delta}(\Omega \times \mathbb{R}^p) \) denotes the set of symbols of order \( m \) and type \( (\rho, \delta) \) as introduced by Hörmander [17]. The subscript \( (\rho, \delta) \) is omitted when \( \rho = 1 \) and \( \delta = 0 \). If \( V \) is an open conic set of \( \Omega \times \mathbb{R}^p \), we define \( S^m_{\rho, \delta}(V) \) as the set of all \( a \in \mathcal{C}^\infty(V) \) such that, for all \( K \in V \),

\[
\sup_{(x, \xi) \in K^c} |\xi|^{-m+\rho|\alpha|−\delta|\beta|} |\partial^\alpha_x \partial^\beta_\xi a(x, \xi)| < \infty,
\]

where \( K^c := \{(x, t\xi) : (x, \xi) \in K, \ t \geq 1\} \). We also make use of the space \( S^1_{\text{log}}(\Omega \times \mathbb{R}^p \setminus \emptyset) \) of all \( a \in S^1(\Omega \times \mathbb{R}^p \setminus \emptyset) \) homogeneous of degree 1 in \( \xi \). Note that the assumption of homogeneity allows us to state the defining conditions above in terms of the semi-norms

\[
\sup_{x \in K, \xi \in \mathbb{R}^p \setminus \emptyset} |\xi|^{-1+\alpha} |\partial^\alpha_x \partial^\beta_\xi a(x, \xi)|,
\]

where \( K \) is any compact subset of \( \Omega \).

The space of generalized symbols \( \mathcal{S}^m_{\rho, \delta}(\Omega \times \mathbb{R}^p) \) is the \( \mathcal{C} \)-module of \( \mathcal{G}_E \) type obtained by taking \( E = S^m_{\rho, \delta}(\Omega \times \mathbb{R}^p) \) equipped with the family of semi-norms

\[
|a|_{\rho, \delta, K, j}^{(m)} = \sup_{x \in K, \xi \in \mathbb{R}^n} |\partial^\alpha_x \partial^\beta_\xi a(x, \xi)|^{m+\rho|\alpha|−\delta|\beta|} \sup_{x \in K, \xi \in \mathbb{R}^n} |\xi|^{-m+\rho|\alpha|−\delta|\beta|}, \ K \in \Omega, \ j \in \mathbb{N}.
\]

The valuation corresponding to \( || \cdot |\rho, \delta, K, j \rangle \) gives the ultra-pseudo-semi-norm \( \mathcal{P}^{(m)}_{\rho, \delta, K, j} \). The space \( \mathcal{S}^m_{\rho, \delta}(\Omega \times \mathbb{R}^p) \) topologized through the family of ultra-pseudo-semi-norms \( \{\mathcal{P}^{(m)}_{\rho, \delta, K, j} \}_{K \in \Omega, \ j \in \mathbb{N}} \) is a Fréchet \( \mathcal{C} \)-module. In analogy with \( \mathcal{S}^m_{\rho, \delta}(\Omega \times \mathbb{R}^p) \), we use the notation \( \mathcal{S}^m_{\rho, \delta}(V) \) for the \( \mathcal{C} \)-module \( \mathcal{G}_E S^m_{\rho, \delta}(V) \).

\( \mathcal{S}^m_{\rho, \delta}(\Omega_x \times \mathbb{R}_x^p) \) has the structure of a sheaf with respect to \( \Omega \). Thus, it is meaningful to talk of the support with respect to \( x \) of a generalized symbol \( a \) (\( \text{supp}_x a \)). In particular, when \( a \in \mathcal{S}^m_{\rho, \delta}(\Omega_x \times \Omega_y \times \mathbb{R}^p) \) we have the notions of support with respect to \( x \) (\( \text{supp}_x a \)) and support with respect to \( y \) (\( \text{supp}_y a \)).

We define the conic support of \( a \) in \( \mathcal{S}^m_{\rho, \delta}(\Omega \times \mathbb{R}^p) \) (\( \text{cone supp}_a \)) as the complement of the set of points \( (x_0, \xi_0) \in \Omega \times \mathbb{R}^p \) such that there exists a relatively compact open neighbourhood \( U \) of \( x_0 \), a conic open neighbourhood \( \Gamma \) of \( \xi_0 \) and a representative \( (a_x)_x \) of \( a \) satisfying the condition

\[
\forall \alpha \in \mathbb{N}^p, \ \forall \beta \in \mathbb{N}^n, \ \forall q \in \mathbb{N}, \ \sup_{x \in U, \xi \in \Gamma} |\xi|^{-m+\rho|\alpha|−\delta|\beta|} |\partial^\alpha_x \partial^\beta_\xi a_x(x, \xi)| = O(\varepsilon^q) \quad \text{as} \ \varepsilon \to 0.
\]

(2.4)
By definition cone $\text{supp} \, a$ is a closed conic subset of $\Omega \times \mathbb{R}^p$. The generalized symbol $a$ is 0 on $\Omega \setminus \pi_x(\text{cone supp} \, a)$.

**Regular symbols**

The space of regular symbols $\tilde{\mathcal{S}}^m_{p,\delta,rg}(\Omega \times \mathbb{R}^p)$ as introduced in [15] can be topologized as a locally convex topological $\hat{C}$-module by observing that it coincides with $\bigcap_{K \in \Omega} \tilde{\mathcal{S}}^m_{p,\delta,rg}(K \times \mathbb{R}^p)$, where $\tilde{\mathcal{S}}^m_{p,\delta,rg}(K \times \mathbb{R}^p)$ is the set of all $a \in \tilde{\mathcal{S}}^m_{p,\delta}(\Omega \times \mathbb{R}^p)$ such that there exists a representative $(a_\varepsilon)_\varepsilon$ fulfilling the following property:

$$\exists N \in \mathbb{N} \quad \forall j \in \mathbb{N}, \quad |a_\varepsilon|^{(m)}_{p,\delta,K,j} = O(\varepsilon^{-N}) \text{ as } \varepsilon \to 0. \quad (2.5)$$

On $\tilde{\mathcal{S}}^m_{p,\delta,rg}(K \times \mathbb{R}^p)$ we define the valuation $v^{(m)}_{p,\delta,K,j}$ given, at the level of representatives, by

$$\sup\{b \in \mathbb{R} : \forall j \in \mathbb{N}, \quad |a_\varepsilon|^{(m)}_{p,\delta,K,j} = O(\varepsilon^b) \text{ as } \varepsilon \to 0\},$$

and the corresponding ultra-pseudo-seminorm

$$P^{(m)}_{p,\delta,K,rg}(a) = e^{-v^{(m)}_{p,\delta,K,j}(a)}.$$

$\tilde{\mathcal{S}}^m_{p,\delta,rg}(K \times \mathbb{R}^p)$ is endowed with the locally convex $\hat{C}$-linear topology determined by the usual ultra-pseudo-semi-norms on $\tilde{\mathcal{S}}^m_{p,\delta}(\Omega \times \mathbb{R}^p)$ and by $P^{(m)}_{p,\delta,K,rg}$. We equip $\tilde{\mathcal{S}}^m_{p,\delta,rg}(\Omega \times \mathbb{R}^p)$ with the initial topology for the injections

$$\tilde{\mathcal{S}}^m_{p,\delta,rg}(\Omega \times \mathbb{R}^p) \to \tilde{\mathcal{S}}^m_{p,\delta,rg}(K \times \mathbb{R}^p).$$

This topology is given by the family of ultra-pseudo-semi-norms $\{P^{(m)}_{p,\delta,K,rg}\}_{K \in \Omega}$ and is finer than the topology induced by $\tilde{\mathcal{S}}^m_{p,\delta}(\Omega \times \mathbb{R}^p)$. Indeed, for all $a \in \tilde{\mathcal{S}}^m_{p,\delta,rg}(\Omega \times \mathbb{R}^p)$, we have

$$P^{(m)}_{p,\delta,K,j}(a) \leq P^{(m)}_{p,\delta,K,rg}(a). \quad (2.6)$$

**Slow-scale symbols**

The classes of the factor space $\mathcal{G}^{rc}_{\mathcal{S}^m_{p,\delta,rg}(\Omega \times \mathbb{R}^p)}$ are called generalized symbols of slow-scale type. $\mathcal{G}^{rc}_{\mathcal{S}^m_{p,\delta,rg}(\Omega \times \mathbb{R}^p)}$ is included in $\tilde{\mathcal{S}}^m_{p,\delta,rg}(\Omega \times \mathbb{R}^p)$ and equipped with the topology induced by $\tilde{\mathcal{S}}^m_{p,\delta,rg}(\Omega \times \mathbb{R}^p)$. Substituting $\mathcal{S}^m_{p,\delta}(\Omega \times \mathbb{R}^p)$ with $\mathcal{S}^m_{p,\delta}(V)$, we obtain the set $\mathcal{G}^{rc}_{\mathcal{S}^m_{p,\delta}(V)}$ of slow-scale symbols on the open set $V \subseteq \Omega \times (\mathbb{R}^p \setminus 0)$.

**Generalized symbols of order $-\infty$**

Different notions of regularity are related to the sets $\tilde{\mathcal{S}}^{-\infty}(\Omega \times \mathbb{R}^p)$ and $\tilde{\mathcal{S}}_{\text{rg}}^{-\infty}(\Omega \times \mathbb{R}^p)$ of generalized symbols of order $-\infty$.

The space $\tilde{\mathcal{S}}^{-\infty}(\Omega \times \mathbb{R}^p)$ of generalized symbols of order $-\infty$ is defined as the $\hat{C}$-module $\mathcal{G}_{\tilde{\mathcal{S}}^{-\infty}(\Omega \times \mathbb{R}^p)}$. Its elements are equivalence classes $a$ whose representatives $(a_\varepsilon)_\varepsilon$ have the property $|a_\varepsilon|^{(m)}_{K,j} = O(\varepsilon^{-N})$ as $\varepsilon \to 0$, where $N$ depends on the order $m$ of the symbol, on the order $j$ of the derivatives and on the compact set $K \subseteq \Omega$. In analogy with
the construction of $\tilde{S}_{rg}^m(\Omega \times \mathbb{R}^p)$, the space $\tilde{S}_{rg}^{-\infty}(\Omega \times \mathbb{R}^p)$ of regular symbols of order $-\infty$ is introduced as

$$\bigcap_{K \in \Omega} \tilde{S}_{rg}^{-\infty}(K \times \mathbb{R}^p),$$

where $\tilde{S}_{rg}^{-\infty}(K \times \mathbb{R}^p)$ is the set of all $a \in \tilde{S}^{-\infty}(\Omega \times \mathbb{R}^p)$ such that there exists a representative $(a_\varepsilon)_\varepsilon$ satisfying the condition

$$\exists N \in \mathbb{N} \quad \forall m \in \mathbb{R} \quad \forall j \in \mathbb{N}, \quad |a_\varepsilon|^{(m)}_{K,j} = O(\varepsilon^{-N}) \text{ as } \varepsilon \to 0.$$  

**Symbols of refined order**

In §5 we will make use of the sets $\tilde{S}_{p,\delta}^{m/-\infty}(\Omega \times \mathbb{R}^p)$ and $\tilde{S}_{p,\delta,rg}^{m/-\infty}(\Omega \times \mathbb{R}^p)$ of symbols of refined order introduced in [13]. These arise from a finer partitioning of the classes in $\tilde{S}_{p,\delta}^{m}(\Omega \times \mathbb{R}^p)$ and $\tilde{S}_{p,\delta,rg}^{m}(\Omega \times \mathbb{R}^p)$, respectively, obtained through a factorization with respect to the set $\mathcal{N}^{-\infty}(\Omega \times \mathbb{R}^p) := \mathcal{N}^{-\infty}_{\mathcal{S}}((\Omega \times \mathbb{R}) \times \mathbb{R}^p)$ of negligible nets. In other words, if $a$ is a (regular) generalized symbol of order $m$ then for all representatives $(a_\varepsilon)_\varepsilon$ of $a$ we can write

$$\kappa((a_\varepsilon)_\varepsilon) := (a_\varepsilon)_\varepsilon + \mathcal{N}^{-\infty}(\Omega \times \mathbb{R}^p) \subseteq (a_\varepsilon)_\varepsilon + \mathcal{N}^{m}_{\mathcal{S}}(\Omega \times \mathbb{R}^p) = a.$$  

As already pointed out in [13] the factorization with respect to $\mathcal{N}^{-\infty}(\Omega \times \mathbb{R}^p)$ instead of $\mathcal{N}^{m}_{\mathcal{S}}(\Omega \times \mathbb{R}^p)$ does not change the action of the corresponding Fourier or pseudodifferential operator. In other words, $\kappa((a_\varepsilon)_\varepsilon)(x, D) = a(x, D)$ for all representatives $(a_\varepsilon)_\varepsilon$ of $a \in \tilde{S}_{p,\delta}^{m}(\Omega \times \mathbb{R}^n)$. In addition, as we will see in the next paragraph, the symbols of refined order have better properties with respect to the microsupport than the usual generalized symbols. For this reason, they are employed in the microlocal investigation of §5 and turn out to be particularly useful from a technical point of view.

**Generalized microsupports**

The $G$-regularity and $G^\infty$-regularity of generalized symbols on $\Omega \times \mathbb{R}^n$ is measured in conical neighbourhoods by means of the following notions of microsupports.

Let $a \in \tilde{S}_{p,\delta}^{m}(\Omega \times \mathbb{R}^n)$ and $(x_0, \xi_0) \in T^*(\Omega) \setminus 0$. The symbol $a$ is $G$-smoothing at $(x_0, \xi_0)$ if there exist a representative $(a_\varepsilon)_\varepsilon$ of $a$, a relatively compact open neighbourhood $U$ of $x_0$ and a conic neighbourhood $\Gamma \subseteq \mathbb{R}^n \setminus 0$ of $\xi_0$ such that

$$\forall m \in \mathbb{R} \quad \forall \alpha, \beta \in \mathbb{N}^n \quad \exists N \in \mathbb{N} \quad \exists \varepsilon > 0 \quad \exists \eta \in (0, 1) \quad \forall (x, \xi) \in U \times \Gamma \quad \forall \varepsilon \in (0, \eta], \quad |\partial^\alpha_x \partial^\beta_\xi a_\varepsilon(x, \xi)| \leq c(\xi)^m \varepsilon^{-N}. \quad (2.7)$$

The symbol $a$ is $G^\infty$-smoothing at $(x_0, \xi_0)$ if there exist a representative $(a_\varepsilon)_\varepsilon$ of $a$, a relatively compact open neighbourhood $U$ of $x_0$, a conic neighbourhood $\Gamma \subseteq \mathbb{R}^n \setminus 0$ of $\xi_0$ and a natural number $N \in \mathbb{N}$ such that

$$\forall m \in \mathbb{R} \quad \forall \alpha, \beta \in \mathbb{N}^n \quad \exists c > 0 \quad \exists \eta \in (0, 1) \quad \forall (x, \xi) \in U \times \Gamma \quad \forall \varepsilon \in (0, \eta], \quad |\partial^\alpha_x \partial^\beta_\xi a_\varepsilon(x, \xi)| \leq c(\xi)^m \varepsilon^{-N}. \quad (2.8)$$
We define the $\mathcal{G}$-microsupport of $a$, denoted by $\mu_{\mathcal{G}}(a)$, as the complement in $T^*(\Omega) \setminus \emptyset$ of the set of points $(x_0, \xi_0)$, where $a$ is $\mathcal{G}$-smoothing and the $\mathcal{G}^\infty$-microsupport of $a$, denoted by $\mu_{\mathcal{G}^\infty}(a)$, as the complement in $T^*(\Omega) \setminus \emptyset$ of the set of points $(x_0, \xi_0)$ where $a$ is $\mathcal{G}^\infty$-smoothing.

When $a \in \hat{\mathcal{S}}_{\rho,\delta}^{\beta,\alpha}((\Omega \times \mathbb{R}^n)$ we denote the complements of the sets of points $(x_0, \xi_0) \in T^*(\Omega) \setminus \emptyset$ where (2.7) and (2.8) hold for some representative of $a$ by $\mu_{\mathcal{G}}(a)$ and $\mu_{\mathcal{G}^\infty}(a)$ respectively. Note that for symbols of refined order conditions (2.7) and (2.8) do not depend on the choice of representatives. It is clear that

(i) if $a \in \hat{\mathcal{S}}^{-\infty}((\Omega \times \mathbb{R}^n)$, then $\mu_{\mathcal{G}}(a) = \emptyset$,

(ii) if $a \in \hat{\mathcal{S}}_{\rho,\delta}^{-\infty}((\Omega \times \mathbb{R}^n)$, then $\mu_{\mathcal{G}^\infty}(a) = \emptyset$,

(iii) if $a \in \hat{\mathcal{S}}_{\rho,\delta}^{-\infty}((\Omega \times \mathbb{R}^n)$ and $\mu_{\mathcal{G}}(a) = \emptyset$, then $a \in \hat{\mathcal{S}}^{-\infty}((\Omega \times \mathbb{R}^n)$,

(iv) if $a \in \hat{\mathcal{S}}_{\rho,\delta}^{-\infty}((\Omega \times \mathbb{R}^n)$ and $\mu_{\mathcal{G}^\infty}(a) = \emptyset$, then $a \in \hat{\mathcal{S}}_{\rho,\delta}^{-\infty}((\Omega \times \mathbb{R}^n)$,

(v) when $a$ is a standard symbol, i.e. $a \in \mathcal{S}_{\rho,\delta}^m((\Omega \times \mathbb{R}^n)$, then $\mu_{\mathcal{G}}(a) = \mu_{\mathcal{G}^\infty}(a)$,

(vi) if $a \in \hat{\mathcal{S}}_{\rho,\delta}^m((\Omega \times \mathbb{R}^n)$, then

$$\mu_{\mathcal{G}}(a) = \bigcap_{(a_\varepsilon) \in a} \mu_{\mathcal{G}}(\kappa((a_\varepsilon)_\varepsilon))$$

and

$$\mu_{\mathcal{G}^\infty}(a) = \bigcap_{(a_\varepsilon) \in a} \mu_{\mathcal{G}^\infty}(\kappa((a_\varepsilon)_\varepsilon)).$$

Note that assertions (iii) and (iv) do not hold in general for symbols that are not of refined order.

Continuity results

By simple reasoning at the level of representatives, one proves that the product is a continuous $\hat{\mathcal{C}}$-bilinear map from $\hat{\mathcal{S}}_{\rho,\delta}^{m_1}(\Omega \times \mathbb{R}^p) \times \hat{\mathcal{S}}_{\rho',\delta'}^{m_2}(\Omega \times \mathbb{R}^p)$ into $\hat{\mathcal{S}}_{\rho,\delta}^{m_1+m_2}(\Omega \times \mathbb{R}^p)$ with $\rho_3 = \min\{\rho_1, \rho_2\}$ and $\delta_3 = \max\{\delta_1, \delta_2\}$. Furthermore, the derivative-map

$$\partial_x^\alpha \partial_\xi^\beta : \hat{\mathcal{S}}_{\rho,\delta}^{m_1}(\Omega \times \mathbb{R}^p) \to \hat{\mathcal{S}}_{\rho,\delta}^{m_1-\rho|\alpha|+\beta}(\Omega \times \mathbb{R}^p)$$

and the map

$$\hat{\mathcal{S}}_{\rho_1,\delta_1}^{m_1}(\Omega \times \mathbb{R}^p) \to \hat{\mathcal{S}}_{\rho_2,\delta_2}^{m_2}(\Omega \times \mathbb{R}^p) : a \to (a_\varepsilon)_\varepsilon + \mathcal{N}_{\rho_2,\delta_2}^{m_2}(\Omega \times \mathbb{R}^p),$$

with $m_1 \leq m_2$, $\rho_1 \geq \rho_2$, $\delta_1 \leq \delta_2$, are continuous.
The product between a generalized function $u(y)$ in $G_c(\Omega)$ and a generalized symbol $a(y, \xi)$ in $\tilde{S}^m_{\rho,\delta}(\Omega \times \mathbb{R}^p)$ (product defined by pointwise multiplication at the level of representatives) gives an element $a(y, \xi)u(y)$ of $S^m_{\rho,\delta}(\Omega \times \mathbb{R}^p)$. In particular, the $\tilde{C}$-bilinear map

$$G_c(\Omega) \times \tilde{S}^m_{\rho,\delta}(\Omega \times \mathbb{R}^p) \to \tilde{S}^m_{\rho,\delta}(\Omega \times \mathbb{R}^p): (u, a) \to a(y, \xi)u(y)$$

(2.11)
is continuous. The previous results of continuity hold between spaces of regular generalized symbols and the map in (2.11) is continuous from $G_\infty c(\Omega) \times \tilde{S}^m_{\rho,\delta,rg}(\Omega \times \mathbb{R}^p)$ into $\tilde{S}^m_{\rho,\delta,rg}(\Omega \times \mathbb{R}^p)$.

**Integration**

If $l < -p$, each $b \in \tilde{S}^l_{\rho,\delta}(\Omega \times \mathbb{R}^p)$ can be integrated on $K \times \mathbb{R}^p$, $K \subset \Omega$, by setting

$$\int_{K \times \mathbb{R}^p} b(y, \xi) \, dy \, d\xi := \left[ \int_{K \times \mathbb{R}^p} b_\varepsilon(z, y, \xi) \, dz \, dy \, d\xi \right]_\varepsilon.$$

Moreover, if $\text{supp}_y b \subset \Omega$, we define the integral of $b$ on $\Omega \times \mathbb{R}^p$ as

$$\int_{\Omega \times \mathbb{R}^p} b(y, \xi) \, dy \, d\xi := \int_{K \times \mathbb{R}^p} b(y, \xi) \, dy \, d\xi,$$

where $K$ is any compact set containing $\text{supp}_y b$ in its interior. Integration defines a continuous $\tilde{C}$-linear functional on this space of generalized symbols with compact support in $y$.

**Proposition 2.1.** Let $b$ be a generalized symbol with $\text{supp}_y b \subset \Omega$.

(i) If $b \in \tilde{S}^l_{\rho,\delta}(\Omega' \times \Omega \times \mathbb{R}^p)$ and $l + \delta k < -p$, then

$$\int_{\Omega \times \mathbb{R}^p} b(x, y, \xi) \, dy \, d\xi := \left[ \int_{K \times \mathbb{R}^p} b_\varepsilon(z, x, y, \xi) \, dz \, dy \, d\xi \right]_\varepsilon,$$

where $K$ is any compact set of $\Omega$ containing $\text{supp}_y b$ in its interior, is a well-defined element of $G^{+}(\Omega')$.

(ii) If $b \in \tilde{S}^{-\infty}_{\rho,\delta}(\Omega' \times \Omega \times \mathbb{R}^p)$, then $\int_{\Omega \times \mathbb{R}^p} b(x, y, \xi) \, dy \, d\xi \in G(\Omega')$.

(iii) If $b \in \tilde{S}^{-\infty}_{\rho,\delta}(\Omega' \times \Omega \times \mathbb{R}^p)$, then $\int_{\Omega \times \mathbb{R}^p} b(x, y, \xi) \, dy \, d\xi \in G^{\infty}(\Omega')$.

**Proof.** We give the proof only of the first assertion, since the second and the third are immediate.

It is clear that if $(b_\varepsilon)_\varepsilon$ is a representative of $b$ and $l + \delta k < -p$, then

$$v_\varepsilon(x) := \int_{K \times \mathbb{R}^p} b_\varepsilon(z, x, y, \xi) \, dz \, dy \, d\xi$$
is a net of functions in $C^k(\Omega')$. More precisely, for any $\alpha \in \mathbb{N}^n$ with $|\alpha| \leq k$ and $K' \subseteq \Omega'$ we have that

$$\sup_{x \in K'} |\partial^\alpha v_c(x)| \leq \sup_{x \in K', y \in K, \xi \in \mathbb{R}^p} (\xi)^{-l-\delta|\alpha|} |\partial_x^\alpha b_c(x, y, \xi)| \int_{\mathbb{R}^p} (\xi)^{l+\delta|\alpha|} d\xi.$$  \hspace{1cm} (2.12)

This shows that $\int_{\Omega \times \mathbb{R}^p} b(x, y, \xi) dy d\xi$ is a well-defined element of $\mathcal{G}_{C^k(\Omega')}$. \hfill \Box

**Remark 2.2.** When $l + \delta k < -p$ the inequality (2.12) implies

$$\mathcal{P}_{K', k} \left( \int_{\Omega \times \mathbb{R}^p} b(x, y, \xi) dy d\xi \right) \leq \mathcal{P}_{\rho, \delta, K' \times K, k}^{(l)}(b)$$

and proves that integration gives a continuous map from $\mathcal{S}_{\rho, \delta}^l(\Omega' \times \Omega \times \mathbb{R}^p)$ to $\mathcal{G}_{C^k(\Omega')}$. In particular, if $b \in \mathcal{S}_{\rho, \delta, \text{rg}}^l(\Omega' \times \Omega \times \mathbb{R}^p)$, then by (2.6) it follows that

$$\mathcal{P}_{K', k} \left( \int_{\Omega \times \mathbb{R}^p} b(x, y, \xi) dy d\xi \right) \leq \mathcal{P}_{\rho, \delta, K' \times K; \text{rg}}^{(l)}(b).$$

### 2.5. Microlocal analysis in the Colombeau context: generalized wavefront sets in $\mathcal{L}(\mathcal{G}_c(\Omega), \tilde{\mathcal{C}})$

In this subsection we recall the basic notions of microlocal analysis which involve the duals of the Colombeau algebras $\mathcal{G}_c(\Omega)$ and $\mathcal{G}(\Omega)$ and have been developed in [11]. In this generalized context, the role which is classically played by $S'(\mathbb{R}^n)$ is given to the Colombeau algebra $\mathcal{G}_\delta(\mathbb{R}^n) := \mathcal{G}_\delta(\mathbb{R}^n)$. $\mathcal{G}_\delta(\mathbb{R}^n)$ is topologized as in §2.2 and its dual $\mathcal{L}(\mathcal{G}_\delta(\mathbb{R}^n), \tilde{\mathcal{C}})$ is endowed with the topology of uniform convergence on bounded subsets. In the following, $\mathcal{G}_\tau(\mathbb{R}^n)$ denotes the Colombeau algebra of tempered generalized functions defined as the quotient $\mathcal{E}_\tau(\mathbb{R}^n)/\mathcal{N}_\tau(\mathbb{R}^n)$, where $\mathcal{E}_\tau(\mathbb{R}^n)$ is the algebra of all $\tau$-moderate nets $(u_\varepsilon)_\varepsilon \in \mathcal{E}_\tau[\mathbb{R}^n] := \mathcal{O}_M(\mathbb{R}^n)^{[0, 1]}$ such that

$$\forall \alpha \in \mathbb{N}^n \exists N \in \mathbb{N}, \sup_{x \in \mathbb{R}^n} (1 + |x|)^{-N} |\partial^\alpha u_\varepsilon(x)| = O(\varepsilon^{-N}) \text{ as } \varepsilon \to 0,$$

and $\mathcal{N}_\tau(\mathbb{R}^n)$ is the ideal of all $\tau$-negligible nets $(u_\varepsilon)_\varepsilon \in \mathcal{E}_\tau[\mathbb{R}^n]$ such that

$$\forall \alpha \in \mathbb{N}^n \exists N \in \mathbb{N} \forall q \in \mathbb{N}, \sup_{x \in \mathbb{R}^n} (1 + |x|)^{-N} |\partial^\alpha u_\varepsilon(x)| = O(\varepsilon^q) \text{ as } \varepsilon \to 0.$$

Theorem 3.8 in [9] shows that we have the chain of continuous embeddings

$$\mathcal{G}_\delta(\mathbb{R}^n) \subseteq \mathcal{G}_\tau(\mathbb{R}^n) \subseteq \mathcal{L}(\mathcal{G}_\delta(\mathbb{R}^n), \tilde{\mathcal{C}}).$$

**The Fourier transform on $\mathcal{G}_\delta(\mathbb{R}^n)$, $\mathcal{L}(\mathcal{G}_\delta(\mathbb{R}^n), \tilde{\mathcal{C}})$ and $\mathcal{L}(\mathcal{G}(\Omega), \tilde{\mathcal{C}})$**

The Fourier transform on $\mathcal{G}_\delta(\mathbb{R}^n)$ is defined by the corresponding transformation at the level of representatives, as follows:

$$\mathcal{F} : \mathcal{G}_\delta(\mathbb{R}^n) \to \mathcal{G}_\delta(\mathbb{R}^n) : u \to [(u_\varepsilon)_\varepsilon].$$
\[ F \text{ is a } \tilde{C}\text{-linear continuous map from } \mathcal{G}_{\tilde{S}}(\mathbb{R}^n) \text{ into itself which extends to the dual in a natural way. In detail, we define the Fourier transform of } T \in \mathcal{L}(\mathcal{G}_{\tilde{S}}(\mathbb{R}^n), \tilde{C}) \text{ as the functional in } \mathcal{L}(\mathcal{G}_{\tilde{S}}(\mathbb{R}^n), \tilde{C}) \text{ given by}\]

\[ F(T)(u) = T(Fu). \]

As shown in [11, Remark 1.5], \( \mathcal{L}(\mathcal{G}(\Omega), \tilde{C}) \) is embedded in \( \mathcal{L}(\mathcal{G}_{\tilde{S}}(\mathbb{R}^n), \tilde{C}) \) by means of the map

\[ \mathcal{L}(\mathcal{G}(\Omega), \tilde{C}) \to \mathcal{L}(\mathcal{G}_{\tilde{S}}(\mathbb{R}^n), \tilde{C}) : T \to \left( u \to T((u_{\epsilon_{1\tilde{S}}})_\epsilon + \mathcal{N}(\Omega)) \right). \]

In particular, when \( T \) is a basic functional in \( \mathcal{L}(\mathcal{G}(\Omega), \tilde{C}) \) we have from [11, Proposition 1.6, Remark 1.7] that the Fourier transform of \( T \) is the tempered generalized function obtained as the action of \( T(y) \) on \( e^{-iy \xi} \), i.e. \( F(T) = T(e^{-i\xi}) = (T(e^{-i\xi}))_\epsilon + \mathcal{N}_\epsilon(\mathbb{R}^n) \).

**Generalized wavefront sets of a functional in \( \mathcal{L}(\mathcal{G}_c(\Omega), \tilde{C}) \)**

The notions of \( \mathcal{G} \)-wavefront set and \( \mathcal{G}^\infty \)-wavefront set of a functional in \( \mathcal{L}(\mathcal{G}_c(\Omega), \tilde{C}) \) were introduced in [11] as direct analogues of the distributional wavefront set in [17]. They employ a subset of the space \( \mathcal{G}^n_{\tilde{S}}(\Omega \times \mathbb{R}^n) \) of generalized symbols of slow-scale type denoted by \( \tilde{S}^n_{sc}(\Omega \times \mathbb{R}^n) \) and introduced in [13, Definition 1.1]. We refer the reader to [13, Definition 1.2] for the definition of slow-scale micro-ellipticity of \( a \in \tilde{S}^n_{sc}(\Omega \times \mathbb{R}^n) \) and to [11] for the action of \( a(x, D) \in \text{pr} \tilde{\Psi}^n_{sc}(\Omega) \) on the dual \( \mathcal{L}(\mathcal{G}_c(\Omega), \tilde{C}) \). We recall that \( \text{pr} \tilde{\Psi}^n_{sc}(\Omega) \) denotes the set of properly supported pseudodifferential operators with symbol in \( \tilde{S}^n_{sc}(\Omega \times \mathbb{R}^n) \).

Let \( T \in \mathcal{L}(\mathcal{G}_c(\Omega), \tilde{C}) \). The \( \mathcal{G} \)-wavefront set of \( T \) is defined as

\[ \text{WF}_\mathcal{G} T := \bigcap_{a(x, D) \in \text{pr} \tilde{\Psi}^n_{sc}(\Omega)} \text{Ell}_{sc}(a)^\epsilon. \]

The \( \mathcal{G}^\infty \)-wavefront set of \( T \) is defined as

\[ \text{WF}_{\mathcal{G}^\infty} T := \bigcap_{a(x, D) \in \text{pr} \tilde{\Psi}^\infty_{sc}(\Omega)} \text{Ell}_{sc}(a)^\epsilon. \]

\( \text{WF}_\mathcal{G} T \) and \( \text{WF}_{\mathcal{G}^\infty} T \) are both closed conic subsets of \( T^*(\Omega) \setminus 0 \). As proved in [11], if \( T \) is a basic functional in \( \mathcal{L}(\mathcal{G}_c(\Omega), \tilde{C}) \), then

\[ \pi_\Omega(\text{WF}_\mathcal{G} T) = \text{sing supp}_\mathcal{G} T \]

and

\[ \pi_\Omega(\text{WF}_{\mathcal{G}^\infty} T) = \text{sing supp}_{\mathcal{G}^\infty} T. \]
Characterization of WF\(_G \widehat{T}\) and WF\(_G^\infty \widehat{T}\) when \(T\) is a basic functional

In § 5 we will employ a useful characterization of the \(G\)-wavefront set and the \(G^\infty\)-wavefront set valid for functionals that are basic. It involves the sets of generalized functions \(G_{S,0}(\Gamma)\) and \(G^\infty_{S,0}(\Gamma)\), defined on the conic subset \(\Gamma\) of \(\mathbb{R}^n \setminus 0\), as follows:

\[
G_{S,0}(\Gamma) := \left\{ u \in G_c(\mathbb{R}^n) : \exists (u_\varepsilon)_\varepsilon \in u \forall l \in \mathbb{R} \exists N \in \mathbb{N}, \sup_{\xi \in \Gamma} |\langle \xi \rangle^l u_\varepsilon(\xi)| = O(\varepsilon^{-N}) \text{ as } \varepsilon \to 0 \right\},
\]

\[
G^\infty_{S,0}(\Gamma) := \left\{ u \in G_c(\mathbb{R}^n) : \exists (u_\varepsilon)_\varepsilon \in u \exists N \in \mathbb{N} \forall l \in \mathbb{R}, \sup_{\xi \in \Gamma} |\langle \xi \rangle^l u_\varepsilon(\xi)| = O(\varepsilon^{-N}) \text{ as } \varepsilon \to 0 \right\}.
\]

Let \(T \in \mathcal{L}(G_c(\Omega), \mathbb{C})\). Theorem 3.13 of [11] shows that

(i) \((x_0, \xi_0) \notin WF_G \widehat{T}\) if and only if there exists a conic neighbourhood \(\Gamma\) of \(\xi_0\) and a cut-off function \(\varphi \in C^\infty(\Omega)\) with \(\varphi(x_0) = 1\) such that \(\mathcal{F}(\varphi \widehat{T}) \in G_{S,0}(\Gamma)\),

(ii) \((x_0, \xi_0) \notin WF_G^\infty \widehat{T}\) if and only if there exists a conic neighbourhood \(\Gamma\) of \(\xi_0\) and a cut-off function \(\varphi \in C^\infty(\Omega)\) with \(\varphi(x_0) = 1\) such that \(\mathcal{F}(\varphi \widehat{T}) \in G^\infty_{S,0}(\Gamma)\).

3. Generalized oscillatory integrals: definition

This section is devoted to a notion of oscillatory integral where both the amplitude and the phase function are generalized objects of Colombeau type.

In the remainder of the paper, \(\Omega\) is an arbitrary open subset of \(\mathbb{R}^n\). We recall that \(\phi(y, \xi)\) is a phase function on \(\Omega \times \mathbb{R}^p\) if it is a smooth function on \(\Omega \times \mathbb{R}^p \setminus 0\), real valued, positively homogeneous of degree 1 in \(\xi\) with \(\nabla_{y,\xi} \phi(y, \xi) \neq 0\) for all \(y \in \Omega\) and \(\xi \in \mathbb{R}^p \setminus 0\). We denote the set of all phase functions on \(\Omega \times \mathbb{R}^p\) by \(\Phi(\Omega \times \mathbb{R}^p)\) and the set of all nets in \(\Phi(\Omega \times \mathbb{R}^p)^{0,1}\) by \(\Phi[\Omega \times \mathbb{R}^p]\). The notation concerning classes of symbols was introduced in § 2.4.

**Definition 3.1.** An element of \(\mathcal{M}_\Phi(\Omega \times \mathbb{R}^p)\) is a net \((\phi_\varepsilon)_\varepsilon \in \Phi[\Omega \times \mathbb{R}^p]\) satisfying the following conditions:

(i) \((\phi_\varepsilon)_\varepsilon \in \mathcal{M}_{bi}(\Omega \times \mathbb{R}^p \setminus 0)\);

(ii) for all \(K \subseteq \Omega\) the net

\[
\left( \inf_{y \in K, \xi \in \mathbb{R}^p \setminus 0} \left| \nabla \phi_\varepsilon \left( y, \frac{\xi}{|\xi|} \right) \right|^2 \right)_\varepsilon
\]

is strictly non-zero.

On \(\mathcal{M}_\Phi(\Omega \times \mathbb{R}^p)\) we introduce the equivalence relation \(\sim\) as follows: \((\phi_\varepsilon)_\varepsilon \sim (\omega_\varepsilon)_\varepsilon\) if and only if \((\phi_\varepsilon - \omega_\varepsilon) \in \mathcal{N}_{bi}(\Omega \times \mathbb{R}^p \setminus 0)\). The elements of the factor space

\[
\tilde{\Phi}(\Omega \times \mathbb{R}^p) := \mathcal{M}_\Phi(\Omega \times \mathbb{R}^p)/\sim
\]

will be called generalized phase functions.
We shall employ the equivalence class notation \[ [(\phi_\varepsilon)_\varepsilon] \] for \( \phi \in \tilde{\Phi}(\Omega \times \mathbb{R}^p) \).

When \((\phi_\varepsilon)_\varepsilon\) is a net of phase functions, i.e. \((\phi_\varepsilon)_\varepsilon \in \tilde{\Phi}[\Omega \times \mathbb{R}^p]\), Lemma 1.2.1 of [17] shows that there exists a family of partial differential operators \((L_{\phi_\varepsilon})_\varepsilon\) such that \(L_{\phi_\varepsilon} e^{i\phi_\varepsilon} = e^{i\phi_\varepsilon}\) for all \( \varepsilon \in (0, 1) \). \( L_{\phi_\varepsilon} \) is of the form

\[
\sum_{j=1}^{p} a_{j,\varepsilon}(y, \xi) \frac{\partial}{\partial \xi_j} + \sum_{k=1}^{n} b_{k,\varepsilon}(y, \xi) \frac{\partial}{\partial y_k} + c_\varepsilon(y, \xi),
\]

where the coefficients \((a_{j,\varepsilon})_\varepsilon\) belong to \( S^0[\Omega \times \mathbb{R}^p] \) and \((b_{k,\varepsilon}, c_\varepsilon)_\varepsilon\) are elements of \( S^{-1}[\Omega \times \mathbb{R}^p] \).

**Proposition 3.2.** If \((\phi_\varepsilon)_\varepsilon \in \mathcal{M}_\Phi(\Omega \times \mathbb{R}^p)\), then \((a_{j,\varepsilon})_\varepsilon \in \mathcal{M}_{S^0}(\Omega \times \mathbb{R}^p)\) for all \( j = 1, \ldots, p \), \((b_{k,\varepsilon})_\varepsilon \in \mathcal{M}_{S^{-1}}(\Omega \times \mathbb{R}^p)\) for all \( k = 1, \ldots, n \), and \((c_\varepsilon)_\varepsilon \in \mathcal{M}_{S^{-1}}(\Omega \times \mathbb{R}^p)\).

The proof of this proposition requires the following lemma.

**Lemma 3.3.** Let

\[ \varphi_{\phi_\varepsilon}(y, \xi) := |\nabla \phi_\varepsilon(y, \xi/|\xi|)|^{-2}. \]

If \((\phi_\varepsilon)_\varepsilon \in \mathcal{M}_\Phi(\Omega \times \mathbb{R}^p)\), then \((\varphi_{\phi_\varepsilon})_\varepsilon \in \mathcal{M}_{S^0}(\Omega \times \mathbb{R}^p \setminus 0)\).

**Proof.** One easily sees that \((\varphi_{\phi_\varepsilon})_\varepsilon\) is a net of symbols of order 0 on \( \Omega \times \mathbb{R}^p \setminus 0 \) homogeneous in \( \xi \). The modernness of \( \varphi_{\phi_\varepsilon} \) is obtained by combining the fact that \((\varphi_{\phi_\varepsilon})_\varepsilon \in \mathcal{M}_{S^0_{hg}(\Omega \times \mathbb{R}^p \setminus 0)}\) with the fact that the gradient of \((\phi_\varepsilon)_\varepsilon\) is strictly non-zero by Definition 3.1(ii).

**Proof of Proposition 3.2.** Let \( \chi \in C^\infty_c(\mathbb{R}^p) \) such that \( \chi(\xi) = 1 \) for \( |\xi| < 1/4 \) and \( \chi(\xi) = 0 \) for \( |\xi| > 1/2 \). From the proof of [17, Lemma 1.2.1] we have that

\[
\begin{align*}
    a_{j,\varepsilon}(y, \xi) &= i(1 - \chi(\xi)) \varphi_{\phi_\varepsilon}(y, \xi) \partial_{\xi_j} \phi_\varepsilon(y, \xi), \\
    b_{k,\varepsilon}(y, \xi) &= i(1 - \chi(\xi)) |\xi|^{-2} \varphi_{\phi_\varepsilon}(y, \xi) \partial_{y_k} \phi_\varepsilon(y, \xi), \\
    c_\varepsilon &= \chi(\xi) + \sum_{j=1}^{p} \partial_{\xi_j} a_{j,\varepsilon} + \sum_{k=1}^{n} \partial_{y_k} b_{k,\varepsilon}.
\end{align*}
\]

By Lemma 3.3 and the properties of \( \chi \) it follows that \((1 - \chi) \varphi_{\phi_\varepsilon})_\varepsilon \in \mathcal{M}_{S^0(\Omega \times \mathbb{R}^p)}\) and \((1 - \chi)|\xi|^{-2} \varphi_{\phi_\varepsilon})_\varepsilon \in \mathcal{M}_{S^{-2}(\Omega \times \mathbb{R}^p)}\). Moreover, \((\phi_\varepsilon)_\varepsilon \in \mathcal{M}_{S^1_{hg}(\Omega \times \mathbb{R}^p \setminus 0)}\) implies that the nets \((\partial_{\xi_j} \phi_\varepsilon)_\varepsilon\) and \((\partial_{y_k} \phi_\varepsilon)_\varepsilon\) belong to \( \mathcal{M}_{S^0_{hg}(\Omega \times \mathbb{R}^p \setminus 0)}\) and \( \mathcal{M}_{S^1_{hg}(\Omega \times \mathbb{R}^p \setminus 0)}\), respectively. This allows us to conclude that \((a_{j,\varepsilon})_\varepsilon \in \mathcal{M}_{S^0(\Omega \times \mathbb{R}^p)}\), \((b_{k,\varepsilon})_\varepsilon \in \mathcal{M}_{S^{-1}(\Omega \times \mathbb{R}^p)}\) and \((c_\varepsilon)_\varepsilon \in \mathcal{M}_{S^{-1}(\Omega \times \mathbb{R}^p)}\).

We proceed by comparing the families of partial differential operators \( L_{\phi_\varepsilon} \) and \( L_{\omega_\varepsilon} \) when \((\phi_\varepsilon)_\varepsilon \sim (\omega_\varepsilon)_\varepsilon\). This makes use of the following technical lemma.

**Lemma 3.4.** If \((\phi_\varepsilon)_\varepsilon, (\omega_\varepsilon)_\varepsilon \in \mathcal{M}_\Phi(\Omega \times \mathbb{R}^p)\) and \((\phi_\varepsilon)_\varepsilon \sim (\omega_\varepsilon)_\varepsilon\), then

\[
((\partial_{\xi_j} \phi_\varepsilon) \varphi_{\phi_\varepsilon} - (\partial_{\xi_j} \omega_\varepsilon) \varphi_{\omega_\varepsilon})_\varepsilon \in \mathcal{N}_{S^0_{hg}(\Omega \times \mathbb{R}^p \setminus 0)}
\]
for all \( j = 1, \ldots, p \) and
\[
((\partial y_k \phi) \frac{1}{\xi} \omega, -(\partial y_k \omega) \frac{1}{\xi} \omega) \in \mathcal{N}_{S_{R_0}^{-1}}(\Omega \times \mathbb{R}^p) \tag{3.3}
\]
for all \( k = 1, \ldots, n \).

**Proof.** The nets in (3.2) and (3.3) are of the form \( a |b|^2 - c |d|^2 \), where \( a \) and \( c \) are nets of moderate type, \( b \) and \( d \) are \( p + n \)-vectors with components of moderate type and \( |b|^2 \) and \( |d|^2 \) are strictly non-zero nets. We can write \( a |b|^2 - c |d|^2 \) as
\[
[a(d - b) \cdot (d + b)]/\frac{1}{2} + |b|^2(a - c)/|b|^2|d|^2 \tag{3.4}
\]
Since \( d - b \) is a vector with negligible components, \( a - c \) is a negligible net and all the other terms in (3.4) are moderate we have that \( a |b|^2 - c |d|^2 \) is negligible itself.

Concerning the net in (3.2) we have that
\[
a = (\partial y_k \phi) \in \mathcal{M}_{S_{R_0}^0}(\Omega \times \mathbb{R}^p),
b = \nabla \phi \in \mathcal{M}_{S_{R_0}^0(\Omega \times \mathbb{R}^p)}^{n+p},
c = (\partial y_k \omega) \in \mathcal{M}_{S_{R_0}^0(\Omega \times \mathbb{R}^p)},
d = \nabla \omega \in \mathcal{M}_{S_{R_0}^0(\Omega \times \mathbb{R}^p)}^{n+p}
\]
and \( d - b \in \mathcal{N}_{S_{R_0}^{n+p}}(\Omega \times \mathbb{R}^p) \), \( a - c \in \mathcal{N}_{S_{R_0}^{n+p}}(\Omega \times \mathbb{R}^p) \), \( 1/|b|^2, 1/|d|^2 \in \mathcal{M}_{S_{R_0}^0(\Omega \times \mathbb{R}^p)}^{n+p} \). Therefore, we obtain that
\[
((\partial y_k \phi) \phi, -(\partial y_k \omega) \omega) \in \mathcal{N}_{S_{R_0}^n(\Omega \times \mathbb{R}^p)}.
\]
Assertion (3.3) is proved in the same way, arguing with nets of symbols of order \(-1\). \( \square \)

An inspection of the proof of Proposition 3.2 combined with Lemma 3.4 leads to the following result.

**Proposition 3.5.** If \( \phi, \omega \in \mathcal{M}_{\Phi}(\Omega \times \mathbb{R}^p) \) and \( \phi, \omega \sim \omega \), then
\[
L\phi - L\omega = \sum_{j=1}^p a_{j,\varepsilon} y_{\xi} \frac{\partial}{\partial \xi} + \sum_{k=1}^n b_{k,\varepsilon} y_{\xi} \frac{\partial}{\partial y_k} + c_{\varepsilon} y_{\xi}, \tag{3.5}
\]
where \( (a_{j,\varepsilon} \in \mathcal{N}_{S_{R_0}^0(\Omega \times \mathbb{R}^p)}, (b_{k,\varepsilon} \in \mathcal{N}_{S_{R_0}^{-1}(\Omega \times \mathbb{R}^p)} \) and \( (c_{\varepsilon} \in \mathcal{N}_{S_{R_0}^{-1}(\Omega \times \mathbb{R}^p)} \) for all \( j = 1, \ldots, p \) and \( k = 1, \ldots, n \).

As a consequence of Propositions 3.2 and 3.5 we claim that any generalized phase function \( \phi \in \Phi(\Omega \times \mathbb{R}^p) \) defines a generalized partial differential operator
\[
L\phi(y, \xi, \partial y, \partial \xi) = \sum_{j=1}^p a_j(y, \xi) \frac{\partial}{\partial \xi} + \sum_{k=1}^n b_k(y, \xi) \frac{\partial}{\partial y_k} + c(y, \xi),
\]
whose coefficients \( \{a_j\}_{j=1}^p \), \( \{b_k\}_{k=1}^n \) and \( c \) are generalized symbols in \( \tilde{S}_{R_0}^1(\Omega \times \mathbb{R}^p) \) and \( \tilde{S}_{R_0}^{-1}(\Omega \times \mathbb{R}^p) \), respectively. By construction, \( L\phi \) maps \( \tilde{S}_{R_0}^m(\Omega \times \mathbb{R}^p) \) into \( \tilde{S}_{R_0}^{m-k}(\Omega \times \mathbb{R}^p) \), where \( s = \min\{\rho, 1 - \delta\} \). Hence, \( L\phi \) is continuous from \( \tilde{S}_{R_0}^m(\Omega \times \mathbb{R}^p) \) to \( \tilde{S}_{R_0}^{m-ks}(\Omega \times \mathbb{R}^p) \).
Proposition 3.6. Let $\phi \in \tilde{\Phi}(\Omega \times \mathbb{R}^p)$. The exponential
\[ e^{i\phi(y, \xi)} \]
\[ \text{is a well-defined element of } \tilde{S}^1_{0,1}(\Omega \times \mathbb{R}^p \setminus 0). \]

**Proof.** We leave it to the reader to check that if $(\phi_\varepsilon)_\varepsilon \in \mathcal{M}_\Phi(\Omega \times \mathbb{R}^p)$, then
\[ (e^{i\phi_\varepsilon(y, \xi)})_\varepsilon \in \mathcal{M}_{S^0_{0,1}(\Omega \times \mathbb{R}^p \setminus 0)}. \]

When $(\phi_\varepsilon)_\varepsilon \sim (\omega_\varepsilon)_\varepsilon$, the equality
\[ e^{i\omega_\varepsilon(y, \xi)} - e^{i\phi_\varepsilon(y, \xi)} = e^{i\omega_\varepsilon(y, \xi)}(1 - e^{i(\phi_\varepsilon - \omega_\varepsilon)(y, \xi)}) \]
implies that
\[ \sup_{y \in K, \xi \in \mathbb{R}^p \setminus 0} |\xi|^{-1} |e^{i\omega_\varepsilon(y, \xi)} - e^{i\phi_\varepsilon(y, \xi)}| = O(\varepsilon^q) \quad (3.6) \]
for all $q \in \mathbb{N}$. At this point, writing $\partial_\xi^\alpha \partial_y^\beta e^{i\omega_\varepsilon(y, \xi)}(1 - e^{i(\phi_\varepsilon - \omega_\varepsilon)(y, \xi)})$
\[ + \sum_{\alpha' < \alpha, \beta' < \beta} \left( \begin{array}{c} \alpha \\ \alpha' \end{array} \right) \left( \begin{array}{c} \beta \\ \beta' \end{array} \right) \partial_\xi^\alpha \partial_y^\beta e^{i\omega_\varepsilon(y, \xi)}(-\partial_\xi^{\alpha'} \partial_y^{\beta'} e^{i(\phi_\varepsilon - \omega_\varepsilon)(y, \xi)}), \]
we obtain the characterizing estimate of a net in $\mathcal{N}_{S^0_{0,1}(\Omega \times \mathbb{R}^p \setminus 0)}$, using (3.6) and the
moderateness of $(e^{i\omega_\varepsilon(y, \xi)})_\varepsilon$. \square

By construction of the operator $L_\phi$ the equality
\[ L^1_\phi e^{i\phi} = e^{i\phi} \]
holds in $\tilde{S}^1_{0,1}(\Omega \times \mathbb{R}^p \setminus 0)$. In addition, Proposition 3.6 and the properties of $L^k_\phi$ allow us to conclude that
\[ e^{i\phi(y, \xi)} L^k_\phi(a(y, \xi)u(y)) \]
is a generalized symbol in $\tilde{S}^{m-ks+1}_{0,1}(\Omega \times \mathbb{R}^p)$ which is integrable on $\Omega \times \mathbb{R}^p$ in the sense
of §2 when $m - ks + 1 < -p$. From now on we assume that $\rho > 0$ and $\delta < 1$.

**Definition 3.7.** Let $\phi \in \tilde{\Phi}(\Omega \times \mathbb{R}^p)$, $a \in \tilde{S}^{m}_{\rho,\delta}(\Omega \times \mathbb{R}^p)$ and $u \in \mathcal{G}_c(\Omega)$. The **generalized oscillatory integral**
\[ \int_{\Omega \times \mathbb{R}^p} e^{i\phi(y, \xi)} a(y, \xi) u(y) \, dy \, d\xi \]
is defined as
\[ \int_{\Omega \times \mathbb{R}^p} e^{i\phi(y, \xi)} L^k_\phi(a(y, \xi)u(y)) \, dy \, d\xi \]
where $k$ is chosen such that $m - ks + 1 < -p$. 

The functional
\[ I_\phi(a) : \mathcal{G}_c(\Omega) \to \mathcal{C} : u \to \int_{\Omega \times \mathbb{R}^p} e^{i\phi(y,\xi)} a(y,\xi) u(y) \, dy \, d\xi \]

belongs to the dual \( L(\mathcal{G}_c(\Omega), \mathcal{C}) \). Indeed, by (2.11), the continuity of \( L^k \) and of the product between generalized symbols, we have that the map
\[ \mathcal{G}_c(\Omega) \to \mathcal{S}_{0,1}^{m-k+1}(\Omega \times \mathbb{R}^p) : u \to e^{i\phi(y,\xi)} L^k_c(a(y,\xi) u(y)) \]
is continuous and thus, by an application of the integral on \( \Omega \times \mathbb{R}^p \), the resulting functional \( I_\phi(a) \) is continuous.

4. Generalized Fourier integral operators

We now study oscillatory integrals where an additional parameter \( x \), varying in an open subset \( \Omega' \) of \( \mathbb{R}^n' \), appears in the phase function \( \phi \) and in the symbol \( a \). The dependence on \( x \) is investigated in the Colombeau context. We denote by \( \Phi[\Omega'; \Omega \times \mathbb{R}^p] \) the set of all nets \((\phi_\varepsilon)_{\varepsilon \in (0,1]} \) of continuous functions on \( \Omega' \times \Omega \times \mathbb{R}^p \) which are smooth on \( \Omega' \times \Omega \times \mathbb{R}^p \setminus \{0\} \) and such that \((\phi_\varepsilon(x, \cdot, \cdot))_{\varepsilon} \in \Phi[\Omega \times \mathbb{R}^p] \) for all \( x \in \Omega' \).

**Definition 4.1.** An element of \( \mathcal{M}_\phi(\Omega'; \Omega \times \mathbb{R}^p) \) is a net \((\phi_\varepsilon)_{\varepsilon} \in \Phi[\Omega'; \Omega \times \mathbb{R}^p] \) satisfying the following conditions:

(i) \((\phi_\varepsilon)_{\varepsilon} \in \mathcal{M}_{S_{0,1}^m(\Omega' \times \Lambda)} \);

(ii) for all \( K' \subset \Omega' \) and \( K \subset \Omega \) the net
\[
\left( x \in K', y \in K, \xi \in \mathbb{R}^p : 0 \right) \inf \left| \nabla_{y,\xi} \phi_\varepsilon \left( x, y, \frac{\xi}{|\xi|} \right) \right|^2 \right)_\varepsilon
\]
is strictly non-zero.

On \( \mathcal{M}_\phi(\Omega'; \Omega \times \mathbb{R}^p) \) we introduce the equivalence relation \( \sim \) as follows: \((\phi_\varepsilon)_{\varepsilon} \sim (\omega_\varepsilon)_{\varepsilon} \) if and only if \((\phi_\varepsilon - \omega_\varepsilon)_{\varepsilon} \in \mathcal{N}_{S_{0,1}^m(\Omega' \times \Lambda)} \). The elements of the factor space
\[ \tilde{\Phi}(\Omega'; \Omega \times \mathbb{R}^p) := \mathcal{M}_\phi(\Omega'; \Omega \times \mathbb{R}^p) / \sim \]
are called generalized phase functions with respect to the variables in \( \Omega \times \mathbb{R}^p \).

Since in this paper we do not develop a calculus of generalized Fourier integral operators, we do not need the additional condition that the gradient with respect to \((x, \xi)\) of the phase function is strictly non-zero. This notion of generalized operator phase function can be found in [12], where we extend the action of a generalized Fourier integral operator to the dual of a Colombeau algebra and we investigate the composition with a generalized pseudodifferential operator.

Proposition 3.2 can be adapted to nets in \( \mathcal{M}_\phi(\Omega'; \Omega \times \mathbb{R}^p) \). More precisely, the operator
\[
L_{\phi_\varepsilon}(x, y, \xi, \partial_y, \partial_\xi) = \sum_{j=1}^p a_{j,\varepsilon}(x, y, \xi) \frac{\partial}{\partial_{x_j}} + \sum_{k=1}^n b_{k,\varepsilon}(x, y, \xi) \frac{\partial}{\partial_{y_k}} + c_\varepsilon(x, y, \xi) \tag{4.2}
\]
defined for any value of \( x \) by (3.1), has the property 
\[ I_{\phi_e(x, \cdot)}^T e^{i\phi_e(x, \cdot)} = e^{i\phi_e(x, \cdot)} \]
for all \( x \in \Omega' \) and \( \varepsilon \in (0, 1] \) and its coefficients depend smoothly on \( x \in \Omega' \).

**Proposition 4.2.** If \((\phi_e)_{\varepsilon} \in M_\Phi(\Omega'; \Omega \times \mathbb{R}^p)\), then the coefficients occurring in (4.2) satisfy the following: \((a_{j, \varepsilon})_{\varepsilon} \in M_{S^0(\Omega' \times \Omega \times \mathbb{R}^p)}\) for all \( j = 1, \ldots, p \), \((b_{k, \varepsilon})_{\varepsilon} \in M_{S^{-1}(\Omega' \times \Omega \times \mathbb{R}^p)}\) for all \( k = 1, \ldots, n \), and \((c_{\varepsilon})_{\varepsilon} \in M_{S^{-1}(\Omega' \times \Omega \times \mathbb{R}^p)}\).

The proof of Proposition 4.2 employs the following lemma concerning basic properties of the term \(|\nabla_{y, \xi} \phi_e(x, y, \xi / |\xi|)|^{-2}\).

**Lemma 4.3.** Let 
\[ \varphi_{\phi_e}(x, y, \xi) := |\nabla_{y, \xi} \phi_e(x, y, \xi / |\xi|)|^{-2}. \] (4.3)
If \((\phi_e)_{\varepsilon} \in M_\Phi(\Omega'; \Omega \times \mathbb{R}^p)\), then \((\varphi_{\phi_e})_{\varepsilon} \in M_{S^0(\Omega' \times \Omega \times \mathbb{R}^p) \setminus 0}\).

We leave it to the reader to check that Lemma 3.4 can be stated for nets of phase functions in \((y, \xi)\) and leads to negligible nets of amplitudes in \( S_{0g}^0(\Omega' \times \Omega \times \mathbb{R}^p \setminus 0) \) and \( S_{0g}^{-1}(\Omega' \times \Omega \times \mathbb{R}^p \setminus 0) \). As a consequence, we have a result on the dependence of \( L_{\phi_e} \) on the phase function.

**Proposition 4.4.** If \((\phi_e)_{\varepsilon}, (\omega_e)_{\varepsilon} \in M_\Phi(\Omega'; \Omega \times \mathbb{R}^p)\) and \((\phi_e)_{\varepsilon} \sim (\omega_e)_{\varepsilon}\), then 
\[ L_{\phi_e} - L_{\omega_e} = \sum_{j=1}^p a_{j, \varepsilon}(x, y, \xi) \frac{\partial}{\partial \xi_j} + \sum_{k=1}^n b_{k, \varepsilon}(x, y, \xi) \frac{\partial}{\partial y_k} + c_{\varepsilon}(x, y, \xi), \] (4.4)
where \((a_{j, \varepsilon})_{\varepsilon} \in N_{S^0(\Omega' \times \Omega \times \mathbb{R}^p)}\), \((b_{k, \varepsilon})_{\varepsilon} \in N_{S^{-1}(\Omega' \times \Omega \times \mathbb{R}^p)}\) and \((c_{\varepsilon})_{\varepsilon} \in N\) \( S_{0g}^{-1}(\Omega' \times \Omega \times \mathbb{R}^p)\) for all \( j = 1, \ldots, p \) and \( k = 1, \ldots, n \).

Combining Propositions 4.2 and 4.4 yields that any generalized phase function \( \phi \) in \( \tilde{\Phi}(\Omega'; \Omega \times \mathbb{R}^p)\) defines a partial differential operator
\[ L_{\phi}(x; y, \xi, \partial_y, \partial_\xi) = \sum_{j=1}^p a_j(x, y, \xi) \frac{\partial}{\partial \xi_j} + \sum_{k=1}^n b_k(x, y, \xi) \frac{\partial}{\partial y_k} + c(x, y, \xi) \] (4.5)
with coefficients \( a_j \in \tilde{S}_{0g}^0(\Omega' \times \Omega \times \mathbb{R}^p)\), \( b_k \in \tilde{S}_{0g}^{-1}(\Omega' \times \Omega \times \mathbb{R}^p)\) such that \( L_{\phi_e}^T e^{i\phi} = e^{i\phi} \) holds in \( \tilde{S}_{0g}^{-1}(\Omega' \times \Omega \times \mathbb{R}^p \setminus 0)\). Arguing as in Proposition 3.6 we obtain that \( e^{i\phi(x, y, \xi)} \) is a well-defined element of \( \tilde{S}_{0g}^{-1}(\Omega' \times \Omega \times \mathbb{R}^p \setminus 0)\). The usual composition argument implies that the map
\[ \mathcal{G}_c(\Omega) \to \tilde{S}_{0g}^{-k+1}(\Omega' \times \Omega \times \mathbb{R}^p) : u \to e^{i\phi(x, y, \xi)} L_{\phi}^x(u(x, y, \xi) u(y)) \]
is continuous.

The oscillatory integral
\[ I_{\phi}(a)(u)(x) = \int_{\Omega' \times \mathbb{R}^p} e^{i\phi(x, y, \xi)} a(x, y, \xi) u(y) \, dy \, d\xi \]

is continuous.
where $\phi \in \tilde{\Phi}(\Omega'; \Omega \times \mathbb{R}^p)$ and $a \in \tilde{\mathcal{S}}^m_{\rho,\delta}(\Omega' \times \Omega \times \mathbb{R}^p)$ is an element of $\tilde{\mathbb{C}}$ for fixed $x \in \Omega'$. In particular, $I_\phi(a)(u)$ is the integral on $\Omega \times \mathbb{R}^p$ of a generalized amplitude in $\tilde{\mathcal{S}}^m_{0,1}(\Omega' \times \Omega \times \mathbb{R}^p)$ having compact support in $y$. The order $l$ can be chosen to be arbitrarily low.

**Theorem 4.5.** Let $\phi \in \tilde{\Phi}(\Omega'; \Omega \times \mathbb{R}^p)$, $a \in \tilde{\mathcal{S}}^m_{\rho,\delta}(\Omega' \times \Omega \times \mathbb{R}^p)$ and $u \in \mathcal{G}_c(\Omega)$. The generalized oscillatory integral

$$I_\phi(a)(u)(x) = \int_{\Omega \times \mathbb{R}^p} e^{i\phi(x,y,\xi)}a(x,y,\xi)u(y) \, dy \, d\xi$$

(4.6)

defines a generalized function in $\mathcal{G}(\Omega')$ and the map

$$A : \mathcal{G}_c(\Omega) \to \mathcal{G}(\Omega') : u \to I_\phi(a)(u)$$

(4.7)

is continuous.

**Proof.** By Proposition 2.1 it follows that $I_\phi(a)(u)$ is a generalized function in $\mathcal{G}^{(\Omega)}$ and that, for all $k \in \mathbb{N}$, the net

$$\left( \int_{\Omega \times \mathbb{R}^p} e^{i\phi_k(x,y,\xi)}L^h_{\phi_k}(a_k(x,y,\xi)u_k(y)) \, dy \, d\xi \right)_\varepsilon, \quad (4.8)$$

where $sh > m + k + p + 1$, belongs to $\mathcal{M}^{(\Omega)}$ and it is a representative of $I_\phi(a)(u)$. By classical arguments valid for fixed $\varepsilon$ we know that the net given by the oscillatory integral

$$\int_{\Omega \times \mathbb{R}^p} e^{i\phi_k(x,y,\xi)}a_k(x,y,\xi)u_k(y) \, dy \, d\xi$$

is an element of $\mathcal{E}[\Omega]$ which coincides with (4.8) for every $k \in \mathbb{N}$. This means that $I_\phi(a)(u)$ is a generalized function in $\mathcal{G}^{(\Omega)}$ which has a representative in $\mathcal{E}_M^{(\Omega)}$, i.e. $I_\phi(a)(u) \in \mathcal{G}(\Omega)$. For any $k \in \mathbb{N}$ the generalized function $I_\phi(a)(u)$ belongs to $\mathcal{G}^{(\Omega')}$ and, by Remark 2.2, the map

$$\tilde{\mathcal{S}}^m_{0,1} - h^{s+1}(\Omega' \times \Omega \times \mathbb{R}^p) \to \mathcal{G}^{(\Omega')} : e^{i\phi(x,y,\xi)}L^h_{\phi}(a(x,y,\xi)u(y)) \to \int_{\Omega \times \mathbb{R}^p} e^{i\phi_k(x,y,\xi)}L^h_{\phi_k}(a_k(x,y,\xi)u_k(y)) \, dy \, d\xi$$

is continuous. This, combined with the continuity of the map

$$\mathcal{G}_c(\Omega) \to \tilde{\mathcal{S}}^m_{0,1} - h^{s+1}(\Omega' \times \Omega \times \mathbb{R}^p) : u \to e^{i\phi(x,y,\xi)}L^h_{\phi}(a(x,y,\xi)u(y))$$

for an arbitrarily large $h$, proves that the map $A : u \to I_\phi(a)(u)$ is continuous from $\mathcal{G}_c(\Omega)$ to $\mathcal{G}(\Omega')$. \hfill \Box

The operator $A$ defined in (4.7) is called a *generalized Fourier integral operator* with amplitude $a \in \tilde{\mathcal{S}}^m_{\rho,\delta}(\Omega' \times \Omega \times \mathbb{R}^p)$ and phase function $\phi \in \tilde{\Phi}(\Omega'; \Omega \times \mathbb{R}^p)$.
The phase function $\phi$ amplitudes, $A$ orator $A$ characteristic ordinary differential equation bounded. Let $\gamma_{30}$ zation parameter; see $g$ as the inverse of its Fourier transform we obtain the Fourier integral representation $a$ i.e. elements $A$ belongs to $\tilde{\rho}, \delta, m$ $\tilde{\rho}$, $\delta$ $m$ $\tilde{\rho}, \delta, m$ continuous.

**Remark 4.6.** By continuity of the $\tilde{C}$-bilinear map $\mathcal{G}_c(\Omega) \times \tilde{S}_p^m(\Omega' \times \Omega \times \mathbb{R}) \rightarrow \tilde{S}_p^m(\Omega' \times \Omega \times \mathbb{R}^p)$ : $(u, a) \rightarrow a(x, y, \xi)u(y)$, it is also clear that for fixed $u \in \mathcal{G}_c(\Omega)$ and $\phi \in \Phi(\Omega'; \Omega \times \mathbb{R}^p)$ the map

$$\tilde{S}_p^m(\Omega' \times \Omega \times \mathbb{R}^p) \rightarrow \mathcal{G}(\Omega') : a \rightarrow I_{\phi}(a)(u)$$

is continuous.

**Example 4.7.** Our outline of a basic theory of Fourier integral operators with Colombeau generalized amplitudes and phase functions is motivated to a large extent by potential applications in regularity theory for generalized solutions to hyperbolic partial differential (or pseudodifferential) equations with distributional or Colombeau-type coefficients (or symbols) and data (see [22, 27, 30]). To illustrate the typical situation we consider here the following simple model: let $u \in \mathcal{G}(\mathbb{R}^2)$ be the solution of the generalized Cauchy problem

$$\partial_t u + c\partial_x u + bu = 0,$$

$$u |_{t=0} = g,$$

where $g$ belongs to $\mathcal{G}_c(\mathbb{R})$ and the coefficients $b, c \in \mathcal{G}(\mathbb{R}^2)$. Furthermore, $b, c$ and $\partial_t c$ are assumed to be of local $L^\infty$-log type (concerning growth with respect to the regularization parameter; see [30]), $c$ being, in addition, generalized, real valued and globally bounded. Let $\gamma \in \mathcal{G}(\mathbb{R}^3)$ be the unique (global) solution of the corresponding generalized characteristic ordinary differential equation

$$\frac{d}{ds} \gamma(x, t; s) = c(\gamma(x, t; s), s),$$

$$\gamma(x, t; t) = x.$$  

Then $u$ is given in terms of $\gamma$ by $u(x, t) = g(\gamma(x, t; 0)) \exp(-\int_0^t b(\gamma(x, t; r), r) dr)$. Writing $g$ as the inverse of its Fourier transform we obtain the Fourier integral representation

$$u(x, t) = \int \int e^{i(\gamma(x, x; 0) - r)\xi} a(x, y, \xi)g(y) dy d\xi, \quad (4.9)$$

where $a(x, y, \xi) := \exp(-\int_0^t b(\gamma(x, t; r), r) dr)$ is a generalized amplitude of order 0. The phase function $\phi(x, t, y, \xi) := (\gamma(x, t; 0) - y)\xi$ has (full) gradient

$$(\partial_x \gamma(x, t; 0), \partial_t \gamma(x, t; 0), -\xi, \gamma(x, t; 0) - y)$$

and thus defines a generalized phase function $\phi$. Therefore, (4.9) reads $u = Ag$, where $A : \mathcal{G}_c(\mathbb{R}) \rightarrow \mathcal{G}(\mathbb{R}^2)$ is a generalized Fourier integral operator.

We now investigate the regularity properties of the generalized Fourier integral operator $A$. We will prove that for appropriate generalized phase functions and generalized amplitudes, $A$ maps $\mathcal{G}^\infty_c(\Omega)$ into $\mathcal{G}^\infty(\Omega')$. As in [15] we consider regular amplitudes, i.e. elements $a$ of the factor space $\tilde{S}_p^m(\Omega' \times \Omega \times \mathbb{R}^p)$ whose representatives $(a_{x})_x$ satisfy the condition given in (2.5) on each compact set of $\Omega' \times \Omega$. However, for the phase functions, the same kind of regularity assumption with respect to the parameter $\varepsilon$ does not entail the desired mapping property.
Example 4.8. Let $n = n' = p = 1$ and $\Omega = \Omega' = \mathbb{R}$ and $\phi_{\varepsilon}(x, y, \xi) = (x - \varepsilon y)\xi$. Then $(\phi_{\varepsilon})_{\varepsilon} \in M_{\Phi}(\mathbb{R}; \mathbb{R} \times \mathbb{R})$ and, in particular, we have $N = 0$ in all moderateness estimates (see Definition 4.1 (i)) and $|\nabla_{y, \xi, \xi}(x, y, \xi/|\xi|)|^2 \geq \varepsilon^2$. Choose the amplitude $a$ identically equal to 1. The corresponding generalized operator $A$ does not map $G_{c}^{\infty}(\mathbb{R})$ into $G_{c}^{\infty}(\mathbb{R})$. Indeed, for $0 \neq f \in C_{c}^{\infty}(\mathbb{R})$ we have that

$$A[(f)_{\varepsilon}] = \left[ \left( \int_{\mathbb{R} \times \mathbb{R}} e^{i(x - \varepsilon y)\xi} f(y) \, dy \, d\xi \right)_{\varepsilon} \right] = [(\varepsilon^{-1}f(x/\varepsilon))_{\varepsilon}] \in G(\mathbb{R}) \setminus G_{c}^{\infty}(\mathbb{R}).$$

Example 4.8 suggests that a stronger notion of regularity on generalized phase functions has to be designed. Such is provided by the concept of a slow-scale net.

Definition 4.9. We say that $\phi \in \hat{\Phi}(\Omega'; \Omega \times \mathbb{R}^p)$ is a slow-scale generalized phase function in the variables of $\Omega \times \mathbb{R}^p$ if it has a representative $(\phi_{\varepsilon})_{\varepsilon}$ fulfilling the following conditions:

(i) $(\phi_{\varepsilon})_{\varepsilon} \in M_{\Phi, sc}^{sc}(\Omega' \times \Omega \times \mathbb{R}^p \setminus 0)$,

(ii) for all $K' \in \Omega'$ and $K \in \Omega$ the net $(\phi_{\varepsilon})_{\varepsilon}$ is slow-scale-strictly non-zero.

In the following the set of all $(\phi_{\varepsilon})_{\varepsilon} \in \hat{\Phi}(\Omega'; \Omega \times \mathbb{R}^p)$ fulfilling conditions (i) and (ii) of Definition 4.9 will be denoted by $M_{\Phi, sc}(\Omega'; \Omega \times \mathbb{R}^p)$, while we use $\hat{\Phi}_{sc}(\Omega'; \Omega \times \mathbb{R}^p)$ for the set of slow-scale generalized functions as above. Similarly, using $\nabla_{x,y,\xi}$ in condition (ii) we define the space $\hat{\Phi}_{sc}(\Omega' \times \Omega \times \mathbb{R}^p)$ of slow-scale generalized phase functions on $\Omega' \times \Omega \times \mathbb{R}^p$.

In the case of slow-scale generalized phase functions and regular or slow-scale generalized amplitudes, a careful inspection of the proofs of Proposition 4.2 and Lemma 4.3 leads to the following properties concerning the partial differential operator $L_{\phi}$ and the Fourier integral operator $A$. We begin by observing that if $(\phi_{\varepsilon})_{\varepsilon} \in M_{\Phi, sc}(\Omega'; \Omega \times \mathbb{R}^p)$, then the net $(\varphi_{\phi_{\varepsilon}})_{\varepsilon}$ given by (4.3) is an element of $M_{\Phi, sc}^{sc}(\Omega' \times \Omega \times \mathbb{R}^p \setminus 0)$. Hence, when $\phi \in \hat{\Phi}_{sc}(\Omega'; \Omega \times \mathbb{R}^p)$ the operator $L_{\phi}$ in (4.5) has coefficients $a_{j} \in G_{sc}^{\infty}(\Omega' \times \Omega \times \mathbb{R}^p)$ and $b_{k} \in G_{sc}^{\infty}(\Omega' \times \Omega \times \mathbb{R}^p)$. It follows that $L_{\phi}$ is continuous from $S_{\rho, \delta, \rho g}(\Omega' \times \Omega \times \mathbb{R}^p)$ to $S_{\rho, \delta, \rho g}^{m,h}(\Omega' \times \Omega \times \mathbb{R}^p)$ and, since the coefficients of $L_{\phi}$ are of slow-scale type, the inequality

$$p_{\rho, \delta, K' \times K, \rho g}^{(m-h),(h)}(I_{\rho g} a) \leq e^{P_{\rho, \delta, K' \times K, \rho g}^{(m)}(a)}$$

holds for all $a$.

We will state the theorem on the regularity properties of

$$A : u \rightarrow \int_{\Omega' \times \mathbb{R}^p} e^{i\phi(x,y,\xi)} a(x, y, \xi) u(y) \, dy \, d\xi$$

when $\phi \in \hat{\Phi}_{sc}(\Omega'; \Omega \times \mathbb{R}^p)$ and $a \in S_{\rho, \delta, \rho g}^{m}(\Omega' \times \Omega \times \mathbb{R}^p)$ below. But first we observe that the product between $a(x, y, \xi)$ and $u(y)$ is a continuous $\mathbb{C}$-bilinear form from $S_{\rho, \delta, \rho g}^{m}(\Omega' \times \Omega \times \mathbb{R}^p) \times G_{c}^{\infty}(\Omega) \rightarrow S_{\rho, \delta, \rho g}^{m}(\Omega' \times \Omega \times \mathbb{R}^p)$ and that

$$e^{i\phi(x,y,\xi)} \in G_{sc}^{\infty}(\Omega' \times \Omega \times \mathbb{R}^p \setminus 0)$$
when $\phi \in \tilde{\Phi}_{sc}(\Omega'; \Omega \times \mathbb{R}^p)$. Consequently, if $\phi \in \tilde{\Phi}_{sc}(\Omega'; \Omega \times \mathbb{R}^p)$, $a \in \hat{S}_{\rho,\delta,K;\operatorname{rg}}^{m}(\Omega' \times \Omega \times \mathbb{R}^p)$ and $u \in G_{c}^{\infty}(\Omega)$, then

$$e^{i\phi(x,y,\xi)} L_{\phi}^{h}(a(x,y,\xi)u(y)) \in \hat{S}_{0,1,\operatorname{rg}}^{m-h_{s}+1}(\Omega' \times \Omega \times \mathbb{R}^p).$$

In this situation the oscillatory integral

$$\int_{\Omega \times \mathbb{R}^p} e^{i\phi(x,y,\xi)} a(x,y,\xi) dy d\xi = \int_{\Omega \times \mathbb{R}^p} e^{i\phi(x,y,\xi)} L_{\phi}^{h}(a(x,y,\xi)u(y)) dy d\xi$$

is the integral of a generalized symbol in $\hat{S}_{0,1,\operatorname{rg}}^{m-h_{s}+1}(\Omega' \times \Omega \times \mathbb{R}^p)$ with compact support in $y$.

**Theorem 4.10.** Let $\phi \in \tilde{\Phi}_{sc}(\Omega'; \Omega \times \mathbb{R}^p)$.

(i) If $a \in \hat{S}_{\rho,\delta,K;\operatorname{rg}}^{m}(\Omega' \times \Omega \times \mathbb{R}^p)$, the corresponding generalized Fourier integral operator

$$A : u \rightarrow \int_{\Omega \times \mathbb{R}^p} e^{i\phi(x,y,\xi)} a(x,y,\xi)u(y) dy d\xi$$

maps $G_{c}^{\infty}(\Omega)$ continuously into $G^{\infty}(\Omega')$.

(ii) If $a \in \hat{S}_{\rho,\delta,K;\operatorname{rg}}^{-m}(\Omega' \times \Omega \times \mathbb{R}^p)$, then $A$ maps $G_{c}(\Omega)$ continuously into $G^{\infty}(\Omega')$.

**Proof.** (i) By Theorem 4.5 we already know that $Au \in G(\Omega')$. A direct inspection of the representative given in (4.8) shows that when $\phi \in \tilde{\Phi}_{sc}(\Omega'; \Omega \times \mathbb{R}^p)$ and $a \in \hat{S}_{\rho,\delta,K;\operatorname{rg}}^{m}(\Omega' \times \Omega \times \mathbb{R}^p)$ the generalized function $Au$ has a representative in $E_{\omega}'(\Omega')$, i.e. $Au \in G^{\infty}(\Omega')$.

Concerning the continuity of the map $A$, we recall that $Au \in G_{C_{k}}^{\infty}(\Omega')$ for each $k \in \mathbb{N}$ and that, by Remark 2.2,

$$P_{K',k}(Au) \leq P_{0,1,K',K;\operatorname{rg}}^{(m-h_{s}+1)}(e^{i\phi(x,y,\xi)} L_{\phi}^{h}(a(x,y,\xi)u(y))),$$

when $m-h_{s}+1+k < -p$. Hence, the continuity of $L_{\phi}^{h}$ and of the map $G_{c}^{\infty}(\Omega) \rightarrow \hat{S}_{\rho,\delta,K;\operatorname{rg}}^{m}(\Omega' \times \Omega \times \mathbb{R}^p)$ : $u \rightarrow a(x,y,\xi)u(y)$ yields

$$P_{0,1,K',K;\operatorname{rg}}^{(m-h_{s}+1)}(e^{i\phi(x,y,\xi)} L_{\phi}^{h}(a(x,y,\xi)u(y))) \leq P^{(1)}_{0,1,K',K;\operatorname{rg}}(e^{i\phi(x,y,\xi)} L_{\phi}^{h}(a(x,y,\xi)u(y)))$$

$$\leq e^{2\xi^{*}}P^{(m)}_{\rho,\delta,K',K;\operatorname{rg}}(a)P_{\omega}'_{\omega}(u).$$

As a consequence, since $P_{\omega}'_{\omega}(K')(Au) = \sup_{k \in \mathbb{N}} P_{K',k}(Au)$, we may conclude that there exists a constant $C > 0$ such that $P_{\omega}'_{\omega}(K')(Au) \leq C P_{\omega}'_{\omega}(\omega)(u)$ for all $u \in G_{c}^{\infty}(\Omega)$ with compact support contained in $K \in \Omega$. This proves that $A$ is continuous from $G_{c}^{\infty}(\Omega)$ to $G^{\infty}(\Omega')$.

(ii) Let us assume that $a \in \hat{S}_{\rho,\delta,K;\operatorname{rg}}^{-m}(\Omega' \times \Omega \times \mathbb{R}^p)$. By Theorem 4.5 we have that $Au \in G(\Omega)$. Since the order of $a$ is $-\infty$, the integral we deal with is absolutely convergent. Again by Remark 2.2, when $u \in G_{K}(\Omega)$ and $m + k < -p$, we obtain

$$P_{K',k}(Au) \leq P_{0,1,K',K;\operatorname{rg}}^{(1)}(e^{i\phi(x,y,\xi)} L_{\phi}^{h}(a(x,y,\xi)u(y))) \leq C P_{\omega}'_{\omega}(K')(Au).$$
In this section we investigate the properties of the functional such that $|\nabla \phi|$ is invertible on $\Omega \times \mathbb{R}^p$ if for all relatively compact subsets $\Gamma$ of $\Omega_0$ there exists a constant $\epsilon > 0$ such that $|\nabla \phi|^2 \in G^\infty_{S_{\phi}}(\Omega \times \mathbb{R}^p \setminus 0)$. Therefore, $\epsilon < 374$.

By construction $\pi_\phi$ denotes the projection of $\phi$ on $\Omega$.

**Definition 5.1.** Let $\phi \in \tilde{\Phi}(\Omega \times \mathbb{R}^p)$. We define $C_\phi \subseteq \Omega \times \mathbb{R}^p \setminus 0$ as the complement of the set of all $(x_0, \xi_0) \in \Omega \times \mathbb{R}^p \setminus 0$ with the property that there exist a relatively compact open neighbourhood $U(x_0)$ of $x_0$ and a conic open neighbourhood $\Gamma(\xi_0)$ of $\xi_0$ such that $|\nabla \phi|^2$ is invertible on $U(x_0) \times \Gamma(\xi_0)$. We set $\pi_\Omega(C_\phi) = S_\phi$ and $R_\phi = (S_\phi)^c$.

By construction $C_\phi$ is a closed conic subset of $\Omega \times \mathbb{R}^p \setminus 0$ and $R_\phi \subseteq \Omega$ is open. It is routine to check that the region $C_\phi$ coincides with the classical one when $\phi$ is classical.

**Proposition 5.2.** The generalized symbol $|\nabla \phi|^2$ is invertible on $R_\phi \times \mathbb{R}^p \setminus 0$.

**Proof.** Let us fix a representative $(\phi_\epsilon) \in \tilde{\Phi}(\Omega \times \mathbb{R}^p)$. If $K \subseteq R_\phi$ then $K \times \{\xi : |\xi| = 1\} \subseteq (C_\phi)^c$. $K$ and $|\nabla \phi|^2$ can be covered by a finite number of neighbourhoods $(U(x_i))_{i=1}^N$ and $(\Gamma_{x_i}(\xi_j))_{j=1}^{M(y)}$ respectively, such that on each $U(x_i) \times \Gamma_{x_i}(\xi_j)$ the estimate $|\nabla \phi_\epsilon(y, \xi)|^2 \geq c_{i,j} \epsilon^{r_{i,j}}$.
holds for some constants \(c_{i,j} > 0, r_{i,j} \in \mathbb{R}\) and for all \(\varepsilon \in (0, \eta_{i,j}]\). It follows that there exist \(c > 0, r \in \mathbb{R}\) and \(\eta \in (0, 1]\) such that when \(y\) is varying in \(\bigcup_{i=1}^{N} U(x_i), \xi \in \mathbb{R}^p \setminus 0\) and \(\varepsilon \in (0, \eta]\) we have

\[
|\nabla_{\xi} \phi_{\varepsilon}(y, \xi)|^2 \geq c\varepsilon^r.
\]

This proves that \(|\nabla_{\xi} \phi|^2\) is invertible. \(\square\)

**Remark 5.3.** Proposition 5.2 says that, on every relatively compact open subset \(U\) of \(R_{\phi}\), \(\phi|_{U \times \mathbb{R}^p}\) has the property of a generalized phase function in \(\Phi(U; \mathbb{R}^p)\). More precisely, \(\phi_{\varepsilon}|_{U \times \mathbb{R}^p} \in \Phi(U; \mathbb{R}^p)\) when \(\varepsilon\) is varying in some smaller interval \((0, \eta]\subseteq (0, 1]\), the net \((\phi_{\varepsilon}|_{U \times \mathbb{R}^p})_{\varepsilon \in (0, \eta]}\) satisfies the \(S^{1}_{\Phi}(U \times \mathbb{R}^p \setminus 0)\)-moderateness condition and \((\nabla_{\xi} \phi_{\varepsilon}(y, \xi/|\xi|))_{\varepsilon}\) is strictly non-zero. In order to have a representative of \(\phi\) defined on the interval \((0, 1]\) we may take \(\phi_{\varepsilon}(y, \xi)\) if \(\varepsilon \in (0, \eta]\) and \(\xi\) if \(\varepsilon \in (\eta, 1]\). Clearly, the phase function \(\phi|_{U \times \mathbb{R}^p}\) does not depend on the choice of the classical phase function we use on the interval \((\eta, 1]\).

The more specific assumption of slow-scale invertibility concerning the generalized symbol \(|\nabla_{\xi} \phi|^2\) is employed in the definition of the following sets.

**Definition 5.4.** Let \(\phi \in \tilde{\Phi}(\Omega \times \mathbb{R}^p)\). We define \(C^{sc}_{\phi} \subseteq \Omega \times \mathbb{R}^p \setminus 0\) as the complement of the set of all \((x_0, \xi_0) \in \Omega \times \mathbb{R}^p \setminus 0\) with the property that there exist a relatively compact open neighbourhood \(U(x_0)\) of \(x_0\) and a conic open neighbourhood \(\Gamma(\xi_0) \subseteq \mathbb{R}^p \setminus 0\) of \(\xi_0\) such that \(|\nabla_{\xi} \phi|^2\) is slow-scale invertible on \(U(x_0) \times \Gamma(\xi_0)\). We set \(\pi_{\Omega}(C^{sc}_{\phi}) = S^{sc}_{\phi}\) and \(R^{sc}_{\phi} = (S^{sc}_{\phi})^{\circ}\).

By construction \(C^{sc}_{\phi}\) is a conic closed subset of \(\Omega \times \mathbb{R}^p \setminus 0\) and \(R^{sc}_{\phi} \subseteq R_{\phi} \subseteq \Omega\) is open. In analogy with Proposition 5.2 we can prove that \(|\nabla_{\xi} \phi|^2\) is slow-scale invertible on \(R^{sc}_{\phi} \times \mathbb{R}^p \setminus 0\).

**Theorem 5.5.** Let \(\phi \in \tilde{\Phi}(\Omega \times \mathbb{R}^p)\) and \(a \in \tilde{S}^{m}_{\rho, \delta}(\Omega \times \mathbb{R}^p)\).

(i) The restriction \(I_{\phi}(a)|_{R_{\phi}}\) of the functional \(I_{\phi}(a)\) to the region \(R_{\phi}\) belongs to \(\mathcal{G}(R_{\phi})\).

(ii) If \(\phi \in \tilde{\Phi}_{sc}(\Omega \times \mathbb{R}^p)\) and \(a \in \tilde{S}^{m}_{\rho, \delta, \tau_{R}}(\Omega \times \mathbb{R}^p)\), then \(I_{\phi}(a)|_{R^{sc}_{\phi}} \in \mathcal{G}^{\infty}(R^{sc}_{\phi})\).

**Proof.** (i) Let \(\Omega_0\) be a relatively compact open subset of \(R_{\phi}\). By Remark 5.3 we know that \(\phi_{0} := \phi|_{\Omega_0 \times \mathbb{R}^p}\) is a generalized phase function in \(\tilde{\Phi}(\Omega_0; \mathbb{R}^p)\). By Theorem 4.5 we have that the oscillatory integral

\[
\int_{\mathbb{R}^p} e^{i\phi_{0}(y, \xi)} a(y, \xi) \, d\xi
\]

defines a generalized function \(w_0\) in \(\mathcal{G}(\Omega_0)\). Now let \((\Omega_j)_{j \in \mathbb{N}}\) be an open covering of \(R_{\phi}\) such that each \(\Omega_j\) is relatively compact. Arguing as above, we obtain a sequence of generalized phase functions \(\phi_j \in \tilde{\Phi}(\Omega_j; \mathbb{R}^p)\) and a coherent sequence of generalized functions

\[
w_j(y) = \int_{\mathbb{R}^p} e^{i\phi_j(y, \xi)} a(y, \xi) \, d\xi \in \mathcal{G}(\Omega_j).
\]
Thus, the sheaf property of $G(R_\phi)$ yields the existence of a unique $w \in G(R_\phi)$ such that $w|_{\Omega_j} = w_j$ for all $j$. It remains to prove that

$$I_\phi(a)(u) = \int_{R_\phi} w(y) u(y) \, dy$$

for $u \in G_c(R_\phi)$. On the level of representatives, we may assume that $\text{supp}\; u$ is contained in some $\Omega_j$ for all $\varepsilon$ and we write the oscillatory integral

$$\int_{\Omega_j \times \mathbb{R}^p} e^{i\phi_j(x,y,\xi)} a_\varepsilon(y,\xi) u_\varepsilon(y) \, dy \, d\xi$$

as an iterated one. This yields the following equality between equivalence classes:

$$I_\phi(a)(u) = \int_{\Omega_j \times \mathbb{R}^p} e^{i\phi_j(y,\xi)} a(y,\xi) u(y) \, dy \, d\xi = \int_{\Omega_j} w_j(y) u(y) \, dy = \int_{R_\phi} w(y) u(y) \, dy.$$

(ii) Let $\phi \in \hat{\Phi}_{sc}(\Omega \times \mathbb{R}^p)$ and $a \in \tilde{S}^m_{p,\delta,rg} (\Omega \times \mathbb{R}^p)$. Then one easily sees that $\phi_j \in \hat{\Phi}_{sc}(\Omega_j; \mathbb{R}^p)$ for all $j$ and that, by Theorem 4.10, each $w_j$ is a regular generalized function. Hence, $w \in G^\infty(R^p_{sc})$ or, in other words, $I_\phi(a)|_{R^p_{sc}}$ belongs to $G^\infty(R^p_{sc})$. \hfill \square

Theorem 5.5 means that

$$\text{sing supp}_G I_\phi(a) \subseteq S_\phi$$

if $\phi \in \hat{\Phi}(\Omega \times \mathbb{R}^p)$ and $a \in \tilde{S}^m_{p,\delta,rg} (\Omega \times \mathbb{R}^p)$ and that

$$\text{sing supp}_G I_\phi(a) \subseteq S^{sc}_\phi$$

if $\phi \in \hat{\Phi}_{sc}(\Omega \times \mathbb{R}^p)$ and $a \in \tilde{S}^m_{p,\delta,rg} (\Omega \times \mathbb{R}^p)$.

**Example 5.6.** Returning to Example 4.7 we are now in the position to analyse the regularity properties of the generalized kernel functional $I_\phi(a)$ of the solution operator $A$ corresponding to the hyperbolic Cauchy problem. For any $v \in G_c(\mathbb{R}^3)$ we have

$$I_\phi(a)(v) = \iint e^{i\phi(x,t,y,\xi)} a(x,t,y,\xi) v(x,t,y) \, dx \, dt \, dy \, d\xi,$$  \hspace{1cm} (5.2)

where $a$ and $\phi$ are as in Example 4.7. Note that in the case of partial differential operators with smooth coefficients and distributional initial values the wavefront set of the distributional kernel of $A$ determines the propagation of singularities from the initial data. When the coefficients are non-differentiable functions, or even distributions or generalized functions, matters are not yet understood in sufficient generality. Nevertheless, the above results allow us to identify regions where the generalized kernel functional agrees with a generalized function or is even guaranteed to be a $G^\infty$-regular generalized function. To identify the set $C_\phi$ in the situation of Example 4.7 one simply has to study invertibility of $\partial_t \phi(x,t,y,\xi) = \gamma(x,t;0) - y$ as a generalized function in a neighbourhood of any given point $(x_0, t_0, y_0)$.
Under the assumptions on $c$ of Example 4.7, the representing nets $(\gamma_\varepsilon(\cdot, \cdot; 0))_{\varepsilon \in (0, 1]}$ of $\gamma$ are uniformly bounded on compact sets (e.g. when $c$ is a bounded generalized constant). For given $(x_0, t_0)$ define the generalized domain of dependence $D(x_0, t_0) \subseteq \mathbb{R}$ to be the set of accumulation points of the net $(\gamma_\varepsilon(x_0, t_0; 0))_{\varepsilon \in (0, 1]}$. Then we have that

$$\{(x_0, t_0, y_0) \in \mathbb{R}^3 : y_0 \notin D(x_0, t_0)\} \subseteq R_\phi.$$

When $c \in \mathbb{R}$ this may be proved by showing that if $(x_0, t_0, y_0) \in C_\phi$ then there exists an accumulation point $c'$ of a representative $(c_\varepsilon)_\varepsilon$ of $c$ such that $y_0 = x_0 - c't_0$.

Example 5.7. As an illustrative example concerning the regions involving the regularity of the functional $I_\phi(a)$ we consider the generalized phase function on $\mathbb{R}^2 \times \mathbb{R}^2$ given by $\phi_c(y_1, y_2, \xi_1, \xi_2) = -\varepsilon y_1 \xi_1 - s_\varepsilon y_2 \xi_2$, where $(s_\varepsilon)_\varepsilon$ is bounded and $(s_\varepsilon^{-1})_\varepsilon$ is a slow-scale net. Clearly, $\phi := [\phi_c]_\varepsilon \in \Phi_{\text{sc}}(\mathbb{R}^2 \times \mathbb{R}^2)$. Simple computations show that $R_\phi = \mathbb{R}^2 \setminus (0, 0)$ and $R_\phi^c = \mathbb{R}^2 \setminus \{y_2 = 0\}$. We leave it to the reader to check that the oscillatory integral

$$\int_{\mathbb{R}^2} e^{i\phi(y, \xi)}(1 + \xi_1^2 + \xi_2^2)^{1/2} d\xi = \left[ \int_{\mathbb{R}^2} e^{-i\varepsilon y_1 \xi_1 - i s_\varepsilon y_2 \xi_2}(1 + \xi_1^2 + \xi_2^2)^{1/2} d\xi_1 d\xi_2 \right]$$

defines a generalized function in $\mathbb{R}^2 \setminus (0, 0)$ whose restriction to $\mathbb{R}^2 \setminus \{y_2 = 0\}$ is regular.

The Colombeau-regularity of the functional $I_\phi(a)$ is easily proved in the case of generalized symbols of order $-\infty$.

**Proposition 5.8.**

(i) If $\phi \in \hat{\Phi}(\Omega \times \mathbb{R}^p)$ and $a \in \hat{S}^{-\infty}(\Omega \times \mathbb{R}^p)$, then $\text{sing supp}_G I_\phi(a) = \emptyset$.

(ii) If $\phi \in \hat{\Phi}_{\text{sc}}(\Omega \times \mathbb{R}^p)$ and $a \in \hat{S}^{-\infty}(\Omega \times \mathbb{R}^p)$, then $\text{sing supp}_G I_\phi(a) = \emptyset$.

**Proof.** (i) Arguing as in §3 we have that $e^{i\phi(y, \xi)}a(y, \xi)$ is a well-defined element of $\hat{S}^{-\infty}(\Omega \times \mathbb{R}^p)$. Hence, by Proposition 2.1 (ii) we obtain that $\int_{\mathbb{R}^p} e^{i\phi(y, \xi)}a(y, \xi) \, d\xi \in \mathcal{G}(\Omega)$.

A direct inspection of the action of $I_\phi(a)$ at the level of representatives shows that the functional $I_\phi(a)$ coincides with the generalized function $\int_{\mathbb{R}^p} e^{i\phi(y, \xi)}a(y, \xi) \, d\xi$. This means that $\text{sing supp}_G I_\phi(a) = \emptyset$.

(ii) When $\phi$ is a slow-scale generalized phase function and $a \in \hat{S}^{-\infty}_{\text{rg}}(\Omega \times \mathbb{R}^p)$ we have $e^{i\phi(y, \xi)}a(y, \xi) \in \hat{S}^{-\infty}_{\text{rg}}(\Omega \times \mathbb{R}^p)$. Therefore, by Proposition 2.1 (iii) we have that $\int_{\mathbb{R}^p} e^{i\phi(y, \xi)}a(y, \xi) \, d\xi \in \mathcal{G}(\Omega)$ and then $\text{sing supp}_G I_\phi(a) = \emptyset$. ☐

For technical reasons, we will multiply the generalized symbol $a \in \hat{S}^{n}_{\text{rg}}(\Omega \times \mathbb{R}^p)$ by a cut-off function $p \in C^\infty(\mathbb{R}^p)$ such that $p(\xi) = 0$ for $|\xi| \leq 1$ and $p(\xi) = 1$ for $|\xi| \geq 2$ in the following. One easily sees that $a(y, \xi)p(\xi) \in \hat{S}^{n}_{\text{rg}}(\Omega \times \mathbb{R}^p)$. Now let $V$ be a closed conic neighbourhood of cone supp $a$. There exists a smooth function $\chi(y, \xi) \in \Omega \times \mathbb{R}^p \setminus 0$, homogeneous of degree 0 in $\xi$ such that supp $\chi \subseteq V$ and $\chi$ is identically 1 in a smaller neighbourhood of cone supp $a$ when $|\xi| > 1$. It follows that $p(\xi)a(y, \xi)\chi(y, \xi) = a(y, \xi)p(\xi)$ in $\hat{S}^{n}_{\text{rg}}(\Omega \times \mathbb{R}^p)$. Note that the representing net $(p(\xi)a_c(y, \xi)\chi(y, \xi))_c$ of $p(\xi)a(y, \xi)$ is supported in the conic neighbourhood $V$ of cone supp $a$ uniformly with respect to $\varepsilon \in (0, 1]$. 
Before stating Proposition 5.9 we note that if \( x_0 \in (\pi_I(C_\phi \cap \text{cone supp } a))^c \), then there exists a relatively compact open neighbourhood \( U(x_0) \) of \( x_0 \) and a closed conic neighbourhood \( V \) of \( \text{cone supp } a \) such that

\[
(\overline{U(x_0)} \times \{ \xi : |\xi| \geq 1 \}) \cap C_\phi \cap V = \emptyset.
\]

**Proposition 5.9.**

(i) If \( \phi \in \tilde{\Phi}(\Omega \times \mathbb{R}^p) \) and \( a \in \tilde{S}^m_{\rho,\delta}(\Omega \times \mathbb{R}^p) \), then

\[
\text{sing supp } I_\phi(a) \subseteq \pi_I(C_\phi \cap \text{cone supp } a).
\]

(ii) If \( \phi \in \tilde{\Phi}_{sc}(\Omega \times \mathbb{R}^p) \) and \( a \in \tilde{S}^m_{\rho,\delta,rg}(\Omega \times \mathbb{R}^p) \), then

\[
\text{sing supp } I_\phi(a) \subseteq \pi_I(C_\phi^{\text{cone}} \cap \text{cone supp } a).
\]

**Proof.** (i) Since \((1 - p(\xi))a(y, \xi) \in \tilde{S}^{-\infty}(\Omega \times \mathbb{R}^p)\), Proposition 5.8 (i) yields that \( \text{sing supp } I_\phi(a) \) coincides with \( \text{sing supp } I_\phi(\text{ap}) \). By the previous considerations on the conic support of \( a \) we can insert a cut-off function \( \chi \) with support contained in a closed conic neighbourhood \( V \) of \( \text{cone supp } a \) as above. Hence, \( \text{sing supp } I_\phi(a) = \text{sing supp } I_\phi(\text{ap}) \). Now let \( x_0 \) be a point of \( (\pi_I(C_\phi \cap \text{cone supp } a))^c \) and let \( U(x_0) \) a relatively compact open neighbourhood of \( x_0 \) such that \( (\overline{U(x_0)} \times \{ \xi : |\xi| \geq 1 \}) \cap C_\phi \cap V = \emptyset \). The generalized symbol \( \text{ap} \), when restricted to the region \( U(x_0) \), has the representative \( \{(a_\varepsilon(y, \xi)p(\xi)\chi(y, \xi)) \text{ which is identically 0 on } (U(x_0) \times \mathbb{R}^p) \cap C_\phi \). By Theorem 5.5 (i) this means that the oscillatory integral

\[
\left( \int_{\mathbb{R}^p} e^{i\phi(y, \xi)} a(y, \xi)p(\xi)\chi(y, \xi) \, d\xi \right)_{U(x_0)}
\]

defines a generalized function in \( \mathcal{G}(U(x_0)) \) whose representatives can be written in the form

\[
\int_{\mathbb{R}^p} e^{i\phi(y, \xi)} L^k_{\phi_{\varepsilon}}(y, \xi, \partial_\xi)(a_\varepsilon(y, \xi)p(\xi)\chi(y, \xi)) \, d\xi
\]

for \( \varepsilon \) small enough. This proves that \( x_0 \notin \text{sing supp } I_\phi(a) \).

(ii) If \( a \in \tilde{S}^m_{\rho,\delta,rg}(\Omega \times \mathbb{R}^p) \), then \((1 - p(\xi))a(y, \xi) \in \tilde{S}^{-\infty}_{\text{rg}}(\Omega \times \mathbb{R}^p)\). By Proposition 5.8 (ii) it follows that \( \text{sing supp } I_\phi(a) = \text{sing supp } I_\phi(\text{ap}) \). Arguing as in Theorem 5.5 (ii) we obtain that if \( x_0 \in (\pi_I(C_\phi \cap \text{cone supp } a))^c \), then

\[
\left( \int_{\mathbb{R}^p} e^{i\phi(y, \xi)} a(y, \xi)p(\xi)\chi(y, \xi) \, d\xi \right)_{U(x_0)}
\]

belongs to \( \mathcal{G}^{\infty}(U(x_0)) \). Consequently, \( x_0 \notin \text{sing supp } I_\phi(a) \). \( \square \)
Remark 5.10. When we deal with generalized symbols of refined order, the conic support can be substituted by the microsupport. More precisely, a combination of Propositions 5.8 and 5.9 yields the following assertions:

(i) if $\phi \in \tilde{\Phi}(\Omega \times \mathbb{R}^n)$ and $a \in \tilde{S}^m_{\nu,\delta}(\Omega \times \mathbb{R}^n)$, then
$$\text{sing supp}_{\tilde{G}} I_\phi(a) \subseteq \pi_{\Omega}(C_{\phi} \cap \mu_{\tilde{G}}(a));$$

(ii) if $\phi \in \tilde{\Phi}_{sc}(\Omega \times \mathbb{R}^n)$ and $a \in \tilde{S}^m_{\rho,\delta,rg}(\Omega \times \mathbb{R}^n)$, then
$$\text{sing supp}_{\tilde{G}} I_\phi(a) \subseteq \pi_{\Omega}(C^m_{\phi} \cap \mu_{\tilde{G}^\infty}(a)).$$

Indeed, assuming that the cut-off $\chi$ is identically 1 in a conic neighbourhood of $\mu_{\tilde{G}}(a)$ when $|\xi| \geq 1$, then $ap(1 - \chi) \in \tilde{S}^{-\infty}(\Omega \times \mathbb{R}^n)$. Hence, $\text{sing supp}_{\tilde{G}} I_\phi(a) = \text{sing supp}_{\tilde{G}} I_\phi(ap\chi) \subseteq \pi_{\Omega}(C_{\phi} \cap \text{cone supp}(ap\chi)) \subseteq \pi_{\Omega}(C_{\phi} \cap \mu_{\tilde{G}}(a))$. By means of analogous arguments, one can easily prove the second inclusion above for $\phi \in \tilde{\Phi}_{sc}(\Omega \times \mathbb{R}^n)$ and $a \in \tilde{S}^m_{\rho,\delta,rg}(\Omega \times \mathbb{R}^n)$.

We conclude the paper by investigating the $G$-wavefront set and the $G^\infty$-wavefront set of the functional $I_\phi(a)$ under suitable assumptions on the generalized symbol $a$ and the phase function $\phi$. We leave it to the reader to check that when $\phi \in \tilde{\Phi}(\Omega \times \mathbb{R}^p)$, $U \subseteq U \subseteq \Omega$, $\Gamma \subseteq \mathbb{R}^{n-1} \setminus 0$, $V \subseteq \Omega \times \mathbb{R}^p \setminus 0$, then
$$\inf_{y \in U, \xi \in \Gamma, (y,\theta) \in V} \frac{|\xi - \nabla_y \phi(y,\theta)|}{|\xi| + |\theta|} := \left( \inf_{y \in U, \xi \in \Gamma, (y,\theta) \in V} \frac{|\xi - \nabla_y \phi(y,\theta)|}{|\xi| + |\theta|} \right)_{y,\theta}$$
is a well-defined element of $\hat{\mathcal{C}}$.

Theorem 5.11.

(i) Let $\phi \in \tilde{\Phi}(\Omega \times \mathbb{R}^p)$ and $a \in \tilde{S}^m_{\nu,\delta}(\Omega \times \mathbb{R}^p)$, the generalized wavefront set $WF_G I_\phi(a)$ is contained in the set $W_{\phi,a}$ of all points $(x_0,\xi_0) \in T^*(\Omega) \setminus 0$ with the property that, for all relatively compact open neighbourhoods $U(x_0)$ of $x_0$, for all open conic neighbourhoods $\Gamma(\xi_0) \subseteq \mathbb{R}^{n-1} \setminus 0$ of $\xi_0$, for all open conic neighbourhoods $V$ of $\text{cone supp} a \cap C_{\phi}$ such that $V \cap (U(x_0) \times \mathbb{R}^p \setminus 0) \neq \emptyset$, the generalized number
$$\inf_{y \in U(x_0), \xi \in \Gamma(\xi_0), (y,\theta) \in V \cap (U(x_0) \times \mathbb{R}^p \setminus 0)} \frac{|\xi - \nabla_y \phi(y,\theta)|}{|\xi| + |\theta|}$$
is not invertible.

(ii) If $\phi \in \tilde{\Phi}_{sc}(\Omega \times \mathbb{R}^p)$ and $a \in \tilde{S}^m_{\rho,\delta,rg}(\Omega \times \mathbb{R}^p)$, then $WF_G I_{\phi}(a)$ is contained in the set $W_{\phi,a}^{sc}$ of all points $(x_0,\xi_0) \in T^*(\Omega) \setminus 0$ with the property that, for all relatively compact open neighbourhoods $U(x_0)$ of $x_0$, for all open conic neighbourhoods $\Gamma(\xi_0) \subseteq \mathbb{R}^{n-1} \setminus 0$ of $\xi_0$, for all open conic neighbourhoods $V$ of $\text{cone supp} a \cap C_{\phi}^uc$, such that $V \cap (U(x_0) \times \mathbb{R}^p \setminus 0) \neq \emptyset$, the generalized number (5.3) is not slow-scale invertible.
Proposition 5.9, we have that

\[ y \text{ under the assumptions on } \Omega \times \mathbb{R}^p \text{ we arrive at} \]

Thus, \( WF_\Omega \times \chi \) generalized number in (5.3) is invertible. Assume that

\[ I_\phi(a(1-p)) \in \mathcal{G}(\Omega) \text{ by Proposition 5.8 (i).} \]

Hence, \( WF_\phi I_\phi(a) = WF_\phi I_\phi(ap) \). Inserting the cut-off function \( \chi \) and making use of Proposition 5.9 (i) we arrive at

\[ \text{sing supp}_\phi I_\phi(ap(1-\chi)) \subseteq \pi_\Omega(C_\phi \cap \text{cone supp } a \cap (V')^c) = \emptyset. \]

Thus, \( WF_\phi I_\phi(a) = WF_\phi I_\phi(ap \chi). \)

Since \((x_0, \xi_0) \notin W_{\phi,a}\) there exists a representative \((\phi_\varepsilon)\) of \( \phi, \eta \in (0,1] \) and \( r \in \mathbb{R} \) such that

\[ |\xi - \nabla y \phi_\varepsilon(y, \theta)| \geq \varepsilon^r (|\xi| + |\theta|) \]

for all \( y \in U(x_0), \xi \in \Gamma(\xi_0) \) and \((y, \theta) \in V \cap U(x_0) \times \mathbb{R}^p \setminus 0 \). Consider the family of differential operators

\[ L_\varepsilon := \sum_{j=1}^n \frac{\xi_j - \partial_{y_j} \phi_\varepsilon(y, \theta)}{|\xi - \nabla y \phi_\varepsilon(y, \theta)|^2} D_{y_j} \]

under the assumptions on \( y, \theta, \xi \) above and denote the coefficient \((\xi_j - \partial_{y_j} \phi_\varepsilon(y, \theta))/|\xi - \nabla y \phi_\varepsilon(y, \theta)|^2 \) by \( d_{j,\varepsilon}(y, \theta, \xi) \). Combining (5.4) with the fact that \((\phi_\varepsilon) \in \mathcal{M}_{S_{\delta_\varepsilon}(\Omega \times \mathbb{R}^p \setminus 0)}\) we get that

\[ \forall \alpha \in \mathbb{N}^n \ \exists N \in \mathbb{N} \ \exists \eta \in (0,1] \ \forall \xi \in \Gamma(\xi_0) \ \forall (y, \theta) \in V \cap (U(x_0) \times \mathbb{R}^p \setminus 0) \ \forall \varepsilon \in (0, \eta], \]

\[ |\partial_{y_j}^\alpha d_{j,\varepsilon}(y, \theta, \xi)| \leq \varepsilon^{-N} (|\theta| + |\xi|)^{-1}. \]

(5.5)

By construction, \( L_\varepsilon e^{i(\phi_\varepsilon(y, \theta)-y \xi)} = e^{i(\phi_\varepsilon(y, \theta)-y \xi)} \) and the transpose operator is of the form

\[ L_\varepsilon^T = \sum_{j=1}^n a_{j,\varepsilon}(y, \theta, \xi) D_{y_j} + c_\varepsilon(y, \theta, \xi), \]

with the coefficients \((a_{j,\varepsilon})\) and \((c_\varepsilon)\) satisfying condition (5.5). If \((b_\varepsilon) \in \mathcal{M}_{S_{\delta_\varepsilon}(\Omega \times \mathbb{R}^p)}\), an induction argument yields the following result:

\[ \forall \alpha \in \mathbb{N}^n \ \exists N \in \mathbb{N} \ \exists \eta \in (0,1] \ \forall \xi \in \Gamma(\xi_0) \ \forall (y, \theta) \in V \cap (U(x_0) \times \mathbb{R}^p \setminus 0) \ \forall \varepsilon \in (0, \eta], \]

\[ |(L_\varepsilon^T)^t b_\varepsilon(y, \theta)| \leq \varepsilon^{-N} (|\theta| + |\xi|)^{-1}(1 + |\theta|)^{m+\delta}. \]

(5.6)

We now have all the tools at hand for dealing with the Fourier transform of the functional \( \phi I_\phi(ap \chi) \in \mathcal{L}(\mathcal{G}(\Omega), \tilde{C}) \) when \( \phi \in C^\infty_c(U) \). By definition, it is the tempered generalized function given by the integral

\[ \int_{\Omega \times \mathbb{R}^p} e^{i(\phi(y, \theta)-y \xi)} \cdot a(y, \theta) p(\theta) \chi(y, \theta) e^{-iy \xi} \varphi(y) \ dy \ d\theta, \]
and from the previous considerations it follows that it has a representative \((f_\varepsilon)_\varepsilon\) of the form
\[
\int_{\Omega \times \mathbb{R}^p} e^{i(\phi_\varepsilon(y,\theta) - y \cdot \xi)} (L^T_\varepsilon)^{i}(a_\varepsilon(y,\theta)\phi(y)) \, dy \, d\theta
\]
when \(\varepsilon\) is small enough and \(\xi\) is varying in \(\Gamma(\xi_0)\). Making use of the estimate (5.6) and taking \(l\) so large that for \(\delta < \lambda < 1\) one has \(m + (\delta - \lambda)l < -p\), we conclude that
\[
\exists l \in \mathbb{N} \quad \exists \varepsilon > 0 \quad \exists \eta \in (0,1] \quad \forall \xi \in \Gamma(\xi_0) \cap \{ \xi : |\xi| \geq 1 \} \quad \forall \varepsilon \in (0, \eta],
\]
\[
|f_\varepsilon(\xi)| \leq \varepsilon \varepsilon^{-N} |\xi|^{-l(1-\lambda)} \int_{\mathbb{R}^p} (1 + |\theta|)^{m+(\delta-\lambda)l} \, d\theta. \quad (5.7)
\]
This shows that \((\varphi I_\phi(\alpha \chi))\hat{\chi}\) is a generalized function in \(\mathcal{G}_{\mathbb{R},0}(\Gamma)\). The characterization of the wavefront set of a functional given in [11] proves that \((x_0, \xi_0)\) does not belong to \(WF_\mathbb{G} I_\phi(\alpha \chi) = WF_\mathbb{G} I_\phi(a)\).

(ii) We now work with \(\phi \in \tilde{\Phi}_{sc}(\Omega \times \mathbb{R}^p)\), \(a \in \mathcal{E}_{p,\delta,rg}^{m}(\Omega \times \mathbb{R}^p)\) and \((x_0, \xi_0) \notin W_{\phi,a}^{sc}\). Choosing \(p(\theta)\) and \(\chi(x, \theta)\) as in the first case, with \(V\) and \(V\)’s neighbourhoods of cone \(supp \alpha\cap C_{\phi}^{sc}\), we have that \(I_\phi(a(1-p)) \in \mathcal{G}^{\infty}(\Omega)\) by Proposition 5.8 (ii). Moreover, Proposition 5.9 (ii) leads to
\[
supp \mathcal{G} I_\phi(\alpha \chi) \subseteq \pi_\Omega(C_{\phi}^{sc}) \cap cone \, supp \, a \cap (V')^c = \emptyset.
\]
Hence, \(WF_\mathbb{G} \approx I_\phi(a) = WF_\mathbb{G} \approx I_\phi(\alpha \chi)\). By the definition of \(W_{\phi,a}^{sc}\), there exists a representative \((\phi_\varepsilon)_\varepsilon\) of \(\phi\), a slow-scale net \((s_\varepsilon)_\varepsilon\) and a number \(\eta \in (0,1]\) such that
\[
|\xi - \nabla_y \phi_\varepsilon(y, \theta)| \geq s_\varepsilon^{-1}(|\xi| + |\theta|)
\]
for all \(\xi \in \Gamma(\xi_0)\), \((y, \theta) \in V \cap (U(x_0) \times \mathbb{R}^p \setminus 0)\) and \(\varepsilon \in (0, \eta]\). This, combined with the hypothesis \(\phi \in \tilde{\Phi}_{sc}(\Omega \times \mathbb{R}^p)\), implies that the coefficients of the operator \(L^T_\varepsilon\) are nets of slow-scale type. Furthermore, when \((b_\varepsilon)_\varepsilon\) is the representative of a generalized symbol \(b\) in \(\mathcal{S}_{p,\delta,rg}^{m}(\Omega \times \mathbb{R}^p)\), we are allowed to change the order of the quantifiers \(\forall l \in \mathbb{N}\) and \(\forall \eta \in \mathbb{N}\) in (5.6). As a consequence, the estimate (5.7) holds with some \(N\) independent of \(l\). We conclude that \([(\varphi I_\phi(\alpha \chi))\hat{\chi}]\) is a generalized function in \(\mathcal{G}_{\mathbb{R},0}^{\infty}(\Gamma)\) and then \((x_0, \xi_0) \notin WF_\mathbb{G} \approx I_\phi(\alpha \chi) = WF_\mathbb{G} \approx I_\phi(a)\).

Example 5.12. Theorem 5.11 can be employed for investigating the generalized wavefront sets of the kernel \(K_A := I_\phi(a)\) of the Fourier integral operator introduced in Example 4.8. For simplicity we assume that \(c\) is a bounded generalized constant in \(\tilde{\mathbb{R}}\) and that \(a = 1\). Let \(((x_0, t_0, y_0), \xi_0) \in WF_\mathbb{G} K_A\). From the first assertion of Theorem 5.11 we know that the generalized number given by
\[
\inf_{(x,t,y) \in U, \xi \in \Gamma, p} \frac{|\xi - (\theta, -c_\varepsilon \theta, -\theta)|}{|\xi| + |\theta|}
\]
is not invertible, for every choice of neighbourhoods \(U\) of \((x_0, t_0, y_0)\), \(\Gamma\) of \(\xi_0\) and \(V\) of \(C_\phi\). Note that it is not restrictive to assume that \(|\theta| = 1\). We fix some sequences \((U_n)\), \((T_n)\), \((V_n)\) and \(\{\xi_0 : \lambda > 0\}\) of neighbourhoods shrinking to \((x_0, t_0, y_0)\), \(\xi_0\lambda : \lambda > 0\) and \(C_\phi\), respectively.
By (5.9) we find a sequence \(\varepsilon_n\) tending to 0 such that for all \(n \in \mathbb{N}\) there exists \(\xi_n \in \Gamma_n\), \((x_n, t_n, y_n, \theta_n) \in V_n\) with \(|\theta_n| = 1\) and \((x_n, t_n, y_n) \in U_n\) such that
\[
|\xi_n - (\theta_n, -c_{\varepsilon_n} \theta_n, -\theta_n)| \leqslant \varepsilon_n(|\xi_n| + 1).
\]
In particular, \(\xi_n\) remains bounded. Passing to suitable subsequences, we obtain that there exist \(\theta\) such that \((x_0, t_0, y_0, \theta) \in C_\phi\), an accumulation point \(c\) of \((c_\varepsilon)\) and a multiple \(\xi'\) of \(\xi_0\) such that \(\xi' = (\theta, -c' \theta, -\theta)\). It follows that
\[
\frac{\xi_0}{|\xi_0|} = \frac{\xi'}{|\xi'|} = \frac{1}{\sqrt{2 + (c')^2 \theta^2}} (\theta, -c' \theta, -\theta).
\]
In other words, the \(G\)-wavefront set of the kernel \(K_A\) is contained in the set of points of the form \(((x_0, t_0, y_0), (\theta_0, -c' \theta_0, -\theta_0))\), where \((x_0, t_0, y_0, \theta_0) \in C_\phi\) and \(c'\) is an accumulation point of a net representing \(c\). Since in the classical case (when \(c \in \mathbb{R}\)) the distributional wavefront set of the corresponding kernel is the set \(\{(x_0, t_0, y_0), (\theta_0, -c \theta_0, -\theta_0)\} : (x_0, t_0, y_0, \theta_0) \in C_\phi\}\), the result obtained above for \(WF_G K_A\) is a generalization in line with what we deduced about the regions \(R_\phi\) and \(C_\phi\) in Example 5.6.

**Remark 5.13.** It is instructive to give an interpretation of the results stated in Theorem 5.11 in the case of classical phase functions.

When \(\phi\) is a classical phase function, the set \(W_{\phi,a}\) as well as the set \(W_{\phi,a}^{sc}\) coincide with
\[
\{(x, \nabla_x \phi(x, \theta)) : (x, \theta) \in cone \text{ supp } a \cap C_\phi\}.
\]
Indeed, if \((x_0, \xi_0)\) is in the complement of the region defined in (5.10), then there exists a relatively compact neighbourhood \(U(x_0)\) of \(x_0\), a closed conic neighbourhood \(\Gamma(\xi_0) \subseteq \mathbb{R}^n \setminus 0\) of \(\xi_0\) and a conic neighbourhood \(V\) of \(cone \text{ supp } a \cap C_\phi^{sc}\) with \(V \cap (U(x_0) \times \mathbb{R}^p \setminus 0) \neq \emptyset\) such that \(\nabla_x \phi(x, \theta) \notin \Gamma(\xi_0)\) for all \((x, \theta) \in V\) with \(x \in U(x_0)\). By continuity and homogeneity of \(\phi\), we conclude that there exists \(c > 0\) such that
\[
\inf_{y \in U, \xi \in \Gamma, (y, \theta) \in V} \frac{|\xi - \nabla_y \phi(y, \theta)|}{|\xi| + |\theta|} > c.
\]
It follows that \((x_0, \xi_0) \notin W_{\phi,a}\). Clearly, if \((x_0, \xi_0) \notin W_{\phi,a}\), then \((x_0, \xi_0)\) does not belong to the set in (5.10).

When the functional \(I_\phi(a)\) is given by a generalized symbol of refined order on \(\Omega \times \mathbb{R}^n\), a more precise evaluation of the wavefront sets \(WF_G I_\phi(a)\) and \(WF_G^{\infty} I_\phi(a)\) can be obtained by making use of the generalized microsupports \(\mu_G\) and \(\mu_G^{\infty}\) instead of the conic support of \(a\) in the definition of the sets \(W_{\phi,a}\) and \(W_{\phi,a}^{sc}\), respectively. As noted in §2.4, symbols of refined order have to be used in connection with generalized microsupports.

**Corollary 5.14.**

(i) Let \(\phi \in \tilde{\Phi}(\Omega \times \mathbb{R}^n)\) and let \(a \in \tilde{S}_{m,\phi}^{\infty}(\Omega \times \mathbb{R}^n)\). The generalized wavefront set \(WF_G I_\phi(a)\) is contained in the set \(W_{\phi,a,G}\) of all points \((x_0, \xi_0) \in T^*(\Omega) \setminus 0\) with the
property that, for all relatively compact open neighbourhoods $U(x_0)$ of $x_0$, for all open conic neighbourhoods $I(x_0) \subseteq \mathbb{R}^n \setminus 0$ of $x_0$, for all open conic neighbourhoods $V$ of $\mu G a \cap C_\phi$ such that $V \cap (U(x_0) \times \mathbb{R}^n \setminus 0) \neq \emptyset$, the generalized number

$$\inf_{y \in U(x_0), \xi \in I(x_0), (y, \theta) \in V \cap (U(x_0) \times \mathbb{R}^n \setminus 0)} \frac{|\xi - \nabla_\phi y|}{|\xi| + |\theta|}$$

is not invertible.

(ii) If $\phi \in \Phi_{sc}(\Omega \times \mathbb{R}^n)$ and $a \in \tilde{\mathcal{S}}_{\rho, \delta, rG}^{m/\infty} (\Omega \times \mathbb{R}^n)$, then $\operatorname{WF} G a I_\phi (a)$ is contained in the set $W_{\phi, a, \rho, \delta, rG}^{\infty}$ of all points $(x_0, \xi_0) \in T^*(\Omega) \setminus 0$ with the property that, for all relatively compact open neighbourhoods $U(x_0)$ of $x_0$, for all open conic neighbourhoods $I(x_0) \subseteq \mathbb{R}^n \setminus 0$ of $x_0$, for all open conic neighbourhoods $V$ of $\mu G a \cap C_\phi$ such that $V \cap (U(x_0) \times \mathbb{R}^n \setminus 0) \neq \emptyset$, the generalized number (5.11) is not slow-scale invertible.

Note that, since $\mu G a \subseteq \mu G \sim a \subseteq \text{cone supp } a$ for any symbol of refined order, we have that $W_{\phi, a, \rho, \delta, rG} \subseteq W_{\phi, a, \rho, \delta} \subseteq W_{\phi, a, \rho, \delta, rG}^{\infty}$ by construction.

**Proof of Corollary 5.14.** (i) Let $p \in C^\infty(\mathbb{R}^n)$ such that $p(\theta) = 0$ for $|\theta| \leq 1$, let $p(\theta) = 1$ for $|\theta| \geq 2$ and let $\chi(y, \theta)$ be a smooth function in $\Omega \times \mathbb{R}^n \setminus 0$, homogeneous of degree 0 in $\theta$ with support contained in a neighbourhood $V$ of $\mu G a \cap C_\phi$, and identically 1 is a smaller neighbourhood $V'$ of $\mu G a \cap C_\phi$ when $|\theta| \geq 1$. Remark 5.10 (i) implies that $\operatorname{WF} G a I_\phi (a) = \operatorname{WF} G a I_\phi (ap \chi)$. At this point an application of Theorem 5.11 (i) yields the desired inclusion, since cone supp $(ap \chi) \subseteq \text{supp } \chi \subseteq V$.

(ii) The second assertion of the theorem is obtained by Remark 5.10 (ii) combined with the second statement of Theorem 5.11. \(\square\)

**Remark 5.15.** When $\phi$ is a classical phase function on $\Omega \times \mathbb{R}^n$, Corollary 5.14 and the truncation arguments employed in Remark 5.13 yield the inclusions

$$\operatorname{WF} G a I_\phi (a) \subseteq \{(x, \nabla_x \phi (x, \theta)) : (x, \theta) \in \mu G a \cap C_\phi\}, \quad \text{(5.12)}$$

$$\operatorname{WF} G a I_\phi (a) \subseteq \{(x, \nabla_x \phi (x, \theta)) : (x, \theta) \in \mu G a \cap C_\phi\}, \quad \text{(5.13)}$$

valid for $a \in \mathcal{S}_{\rho, \delta, rG}^{m/\infty} (\Omega \times \mathbb{R}^n)$ and $a \in \tilde{\mathcal{S}}_{\rho, \delta, rG}^{m/\infty} (\Omega \times \mathbb{R}^n)$, respectively.

Finally, we consider a generalized pseudodifferential operator $a(x, D)$ on $\Omega$ and its kernel $K_{a(x, D)} \in \mathcal{L} G c (\Omega \times \Omega) \tilde{\mathcal{C}}$. From (5.12), we have that $\operatorname{WF} G (K_{a(x, D)})$ is contained in the normal bundle of the diagonal in $\Omega \times \Omega$ when $a \in \mathcal{S}_{\rho, \delta}^m (\Omega \times \mathbb{R}^n)$. By (5.13), $\operatorname{WF} G a I_\phi (a(x, D))$ is a subset of the normal bundle of the diagonal in $\Omega \times \Omega$ when $a$ is regular. We define the sets

$$\operatorname{WF} G (a(x, D)) = \{(x, \xi) \in T^* (\Omega) \setminus 0 : (x, x, \xi, -\xi) \in \operatorname{WF} G (K_{a(x, D)})\}$$

and

$$\operatorname{WF} G a (a(x, D)) = \{(x, \xi) \in T^* (\Omega) \setminus 0 : (x, x, \xi, -\xi) \in \operatorname{WF} G a (K_{a(x, D)})\}.$$
Proposition 5.16. Let $a(x, D)$ be a generalized pseudodifferential operator.

(i) If $a \in \tilde{S}^{m}_{\rho, \delta}(\Omega \times \mathbb{R}^{n})$, then $WF_{G}(a(x, D)) \subseteq \mu \supp_{G}(a)$.

(ii) If $a \in \tilde{S}^{m}_{\rho, \delta, \text{rg}}(\Omega \times \mathbb{R}^{n})$, then $WF_{G}(a(x, D)) \subseteq \mu \supp_{G}(a)$.

Proof. (i) Let $(a_{\varepsilon})_{\varepsilon}$ be a representative of $a$ and $\kappa((a_{\varepsilon})_{\varepsilon}) = (a_{\varepsilon})_{\varepsilon} + \mathcal{N}^{-\infty}(\Omega \times \mathbb{R}^{n})$. From (5.12) we have that

$$WF_{G}(K_{\kappa((a_{\varepsilon})_{\varepsilon})}(x, D)) \subseteq \{(x, x, \xi, -\xi) \in T^{*}(\Omega \times \Omega) \setminus 0 : (x, \xi) \in \mu_{G}(\kappa((a_{\varepsilon})_{\varepsilon}))\}.$$ 

The intersection over all representatives of $a$ combined with (2.9) yields

$$WF_{G}(h_{a(x, D)}) \subseteq \{(x, x, \xi, -\xi) \in T^{*}(\Omega \times \Omega) \setminus 0 : (x, \xi) \in \mu \supp_{G}(a)\}.$$ 

Hence,

$$WF_{G}(a(x, D)) \subseteq \mu \supp_{G}(a).$$

(ii) The second assertion of the proposition is obtained as above from (5.13) and the equality (2.10). \hfill \Box

In consistency with the notation introduced in [13, Definition 3.9] and [11, Definition 3.11] we can define the $G$-microsupport of a properly supported generalized pseudodifferential operator as

$$\mu \supp_{G}(A) := \bigcap_{a \in \tilde{S}^{m}_{\rho, \delta}(\Omega \times \mathbb{R}^{n}), \ a(x, D) = A} \mu \supp_{G}(a)$$

and the $G^{\infty}$-microsupport as

$$\mu \supp_{G}(A) := \bigcap_{a \in \tilde{S}^{m}_{\rho, \delta, \text{rg}}(\Omega \times \mathbb{R}^{n}), \ a(x, D) = A} \mu \supp_{G}(a).$$

From Proposition 5.16 it follows that $WF_{G}(A) \subseteq \mu \supp_{G}(A)$. In particular, if $A$ is given by a symbol in $\tilde{S}^{m}_{\rho, \delta, \text{rg}}(\Omega \times \mathbb{R}^{n})$, then $WF_{G}(A) \subseteq \mu \supp_{G}(A)$.

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