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Critical Load Profile Estimation for Sizing of Battery Storage System

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Abstract—In this paper, a method to find the critical load profile for estimating the battery storage size is proposed. The critical load profile consists of broadest peak in annual historical load profile data and is assumed an outlier. The LOF (local outlier factor) approach is implemented in finding the outliers, which are ranked according to degree of anomalies. The discharge duration in critical load profile, with consideration of annual load growth, helps in deciding the expected size of battery energy storage system (BESS) for the year of interest. The BESS sized with this power and energy ratings is useful in daily time deferrals, load leveling and peak shaving applications.

Index Terms—Broadest peak, discharge intervals, critical load profile, local outlier factor

Nomenclature

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ω</td>
<td>Load profile data</td>
</tr>
<tr>
<td>CENj</td>
<td>Centroid load profile of jth cluster</td>
</tr>
<tr>
<td>dCENj</td>
<td>Demand in CENj at jth time interval, MW</td>
</tr>
<tr>
<td>Cj</td>
<td>Set of load profile in jth cluster</td>
</tr>
<tr>
<td>iPeak</td>
<td>Set of load profile in cluster of peak load</td>
</tr>
<tr>
<td>CPLb</td>
<td>Critical load profile for base year</td>
</tr>
<tr>
<td>CPLr</td>
<td>Critical load profile for year of interest</td>
</tr>
<tr>
<td>nC</td>
<td>No. of clusters in load profile data</td>
</tr>
<tr>
<td>nT</td>
<td>No. of load profiles in iPeak</td>
</tr>
<tr>
<td>T</td>
<td>Total no. of time intervals in a day</td>
</tr>
<tr>
<td>ETot</td>
<td>Daily total energy demand, MWh</td>
</tr>
<tr>
<td>Nsch</td>
<td>Daily no. of discharge intervals, hrs</td>
</tr>
<tr>
<td>δsch</td>
<td>Discharge duration, hrs</td>
</tr>
<tr>
<td>Pmax</td>
<td>Maximum power demand, MW</td>
</tr>
</tbody>
</table>

I. INTRODUCTION

With the advancement in the energy storage technologies, it is becoming feasible to store some amount of electricity for certain period of time. At the substation and feeder levels, the batteries can be installed for reducing the impact of intermittency of renewable power generation, peak load shaving and load leveling, voltage stabilization, reduced cold loads and load transfers, reactive power compensation, etc. If the batteries are located near to the load end, the distribution system reliability can be enhanced very effectively even with the variability associated with distributed energy sources, and electric vehicles. With employment of batteries, two-way power flow is possible in the system as and when required. The wind and solar energy generation can be stored to dispatch later during peak load demand which is less predictable [1-5].

In the load leveling applications in the distribution system, the batteries flatten the load demand at upstream grid on assumed time intervals. The battery capacity during discharging with varying electricity demand depends on pattern of the load at different time intervals that is to be covered by the BESS. Thus, there is a need to estimate the battery capacity change during each interval [6]. Sizing of BESS is done for desired level of peak reduction using the load following method from a real load demand data [7].

The lead-acid, sodium-sulphur, and flow batteries with appropriate sizes are the good choice for bridging power and energy management at distribution level [8]. A methodology, to determine the size of lowest-cost zinc-bromine flow battery-based energy storage system, is developed and impact of control strategy on sizing is quantified for assessment [9]. Selecting suitable size of battery helps in shaving the peak demand, storing the excess energy and releasing the energy, whenever required, with minimum cost [10]. Authors of the paper [11] worked to find a unique critical value of the battery size such that total cost remains the same whether the battery size is larger than or equal to this value. The tool for finding optimal size of hybrid energy storage systems (HESS) incorporating batteries and ultra-capacitors for regenerative braking in electric railway systems has been proposed in [12].

The input and output rated power values of energy storage system (ESS) directly depend on charging and discharging features such as current and rate of charging/discharging and operational voltage. The variations in these parameters are kept within the limits so that there is no violation in the condition of maximum depth of discharge (DOD) [8]. The DOD plays major role in deciding the size of battery as upper limit of state of charge (SOC) is just a technical limit while the lower limit of SOC is directly related to maximum allowed DOD [12]. The energy storage, used with other energy resources, the capacity required to fulfillment of local electricity consumption is based on the average hourly load of the electrical network, desired typical hours of energy autonomy, and maximum depth of discharge and energy

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transformation efficiency of energy storage system [8]. Once
the peak load shaving is established, the minimum size of
BESS is obtained by finding maximum of the minimum
energy supplied by the BESS and the minimum energy
charged to the BESS [10].

To the best of authors’ knowledge, no work is available
which implements the concepts of LOF in practical load
history data to obtain the critical load profile, which is
assumed an outlier, for the size of battery. In this paper, an
approach is proposed to establish the critical load profile for
base year and year of interest which aims to find possible
loading conditions during the season of peak demands. The
critical load profile, which is an outlier, consists of the
broader peak in whole historical load pattern data. k-means
clustering technique is implemented to isolate different groups
of large and least varying electricity consumption days. The
cluster of large variation consists of broadest peak demand
profile and it is identified using concept of LOF. Though, the
proposed approach is conservative but it is robust as well. The
effectiveness of the proposed work is tested on a practical
distribution system.

II. BATTERY : AN OVERVIEW

A. Dynamics of battery

During charging/discharging operations, battery follows
following dynamic equation [11].

\[ \frac{dE_{bat}(t)}{dt} = P_{bat}(t) \]

where \( E_{bat}(t) \) is stored energy (Wh) in battery and \( P_{bat}(t) \)
(W) is charging/discharging rate at time \( t \). \( \Delta E_{bat}(t) \) is the
change in energy stored, as shown below.

\[ E_{bat}(t + 1) = E_{bat}(t) + \Delta E_{bat}(t) \]

B. Applications

The storages of energy find various applications in
delivery of electrical energy from generation to end users and
these can be deployed at any of subsystems of the power
system. A value chain diagram, as shown in Fig. 1, depicts
where and what are the applications in power system. At
distribution level, the BESS is used in load leveling and peak
shaving applications. With advancement in technologies and
reduction in cost of installation, and operational and
maintenance, the battery energy storage systems are emerging
as powerful tool in, day-by-day, balancing of demand and
supply at substation and end users level.

C. Size

Storage size requirement is expressed in pair of power and
energy capacities that are decided in order to balance power
flow during each interval, considering projected overload [3].
Power balance requirement is fluctuating power injections
(increments) into and absorptions (decrement) from bulk
power system [4]. The main points, which are to be considered
in deciding the size of energy storage, are the operational
constraints in the system. Size of the battery is fully utilized if
it is designed based on 100% of DOD of battery. In such a
case, battery will be cycled from state of full charge to full
discharge [5].

III. K-MEANS CLUSTERING ALGORITHM

k-means is one of the simplest clustering algorithms which
separate a given data set into a certain assumed number of
clusters. The different groups are obtained based on
attributes/features by an objective function such as sum of
squares of distances between data and corresponding cluster
centroid. Data objects in \( n \) numbers are separated into \( k \)
groups by minimizing the objective function, as given below, with
Euclidean distance as similarity feature [14].

\[ J = \sum_{j=1}^{k} \sum_{i=1}^{n} || x_i^{(j)} - c_j ||^2 \]

The \( k \)-means clustering algorithm can be summarized in
following steps:

1. Choose \( k \) initial centers \( (c_1, c_2, ..., c_k) \).
2. Assign each data object \( x_i^{(j)} \) to its nearest cluster
center \( c_j \).
3. Obtain mean of all \( x_i^{(j)} \) to update each cluster center \( c_j \).
4. Repeat steps 2 and 3 till no further change is found in
cluster centers i.e. they are converged to a set of
values.

IV. LOCAL OUTLIER FACTOR

The LOF [13] has a local approach and does comparison
of density of each data object with that of objects in its
neighborhood, and hence, it is based on relative densities of
the neighboring data objects. The LOF comes from the field of
knowledge discovery in databases (KDD) which assigns a
degree of ‘outlierness’ to each object in the database, termed
as LOF. An object having higher value of the LOF means that
there is difference between the density around this object and
its \( k \)-nearest neighbors and these objects are termed as
outliers. Others, which are having the LOF approximately
equal to one, exist within region of homogeneous density.
With following steps, the LOF of each object can be
computed.

1. First \( k \)-distance, the distance from an object to its \( k \)
nearest neighbor, is computed and then \( k \)NN objects
which are within \( k \)-distance sphere are identified.
2. Reachability distance of an object \( p \) with respect to \( o \),
an object under consideration, is computed as
reach-dist(\( p, o \)) = max\{k-distance(o), d(p, o)\}, where \( d(p, o) \)
is the distance between objects \( p \) and \( o \).
3. Local reachability density, \( lrd(o) \), defined as inverse of
average of reachability distance of \( k \)-nearest neighbors
of an object under consideration \( o \), is computed as

\[ lrd(o) = \sum_{p \in \text{reach-dist}(o)} \frac{|N_p(o)|}{|N_k(o)|} \]

4. \( \text{LOF}(o) \), of an object \( o \) is computed as average of the
ratios of local reachability density of \( k \)

nearest neighbors of object \( o \) to local reachability
density of object \( o \) itself as

\[ \text{LOF}(o) = \frac{1}{k} \sum_{p \in \text{reach-dist}(o)} \frac{1}{lrd(p)} \]
The objects having LOF close to 1 are identified as part of cluster and the LOF for outliers are computed greater than 1. Outliers in each cluster are isolated with respect to a threshold assumed on LOF heuristically, and clusters are filtered into homogeneous objects.

V. PROPOSED APPROACH TO ESTABLISH CRITICAL LOAD PROFILE

There is different usage of electricity on different days in a year depending on several factors such as weather conditions, types of customers, days of week, times of year, etc. Thus, energy and power requirements are different on different days. Load profile information provides valuable analysis for implementation of storage for end user applications and is very useful in sizing of storage and designing appropriate control schemes.

Storage discharge duration is a key parameter in determination of its size, used for customer level applications and it is defined as amount of time that storage must be able to discharge energy, at the design power rating, without recharging. Discharge duration is estimated based, almost entirely, on load pattern having peak demand at each node in the distribution system. Therefore, a critical load profile is to be established for estimation of design discharge duration. Critical load profile can be obtained from historical hourly electricity consumption on a day or days when peak broad demand occurs. Estimating design discharge duration from critical load profile is a methodology, which is conservative and robust, with assumption that there is not unusual change in electricity consumption behavior [3].

The proposed approach implements k-means algorithm for clustering purpose and local outlier factor helps in identification of abnormal consumption, as per their degree of anomalies, which include load patterns with broadest peaks. Centroid load profile of a cluster is obtained by taking mean of electricity consumptions in all load profiles of that cluster at different time intervals. In one cluster, out of all optimal number of clusters, there is a large variation in electricity consumption. This group, \( C_{peak} \), consists of load profiles of peak load and can be identified as

\[
C_{peak} = \left\{ C_j \mid \max_{i \in \Omega} (dCEN_i), \forall C_j \in \Omega \right\} \tag{6}
\]

Critical load profile, \( CLP^b \), is having maximum discharge duration and hence, it is an outlier in \( C_{peak} \).

\[
CLP^b = \left\{ LP \in C_{peak} \mid \max_{i \in \Omega} (N_{peak}(LP)) \& \text{LOF}(LP) > \right\} \tag{7}
\]

\( E_{tot}^b \), for any load profile \( LP \), is determined by the area between the critical load profile curve and line for reference upstream grid demand \( P_{grid}^{ref} \) as

\[
E_{tot}^b = \int_0^T (P_{LP} - P_{grid}^{ref})dt, \quad P_{LP} > P_{grid}^{ref} \tag{8}
\]

Rated value of energy capacity \( E_{rated} \) is decided while taking in account a minimum value of energy in battery.

\[
E_{rated} = \frac{E_{tot}^b}{\eta_{batt}} + SOC_{max} E_{bat} \tag{9}
\]

For the base year and assumed year \( r \) from base year, the rated power of battery energy storage, \( P_{rated}^b \), is set equal to \( P_{CLP^b}^b \) and \( P_{CLP^r}^r \), respectively.

Load growth, \( L_{gr}^r \) in year \( r \) is estimated as

\[
L_{gr}^r = r(L_{BL} + L_{SG}) \tag{10}
\]

where \( L_{BL} \) is block loads added, due to housing developments, commercial buildings, industrial or agricultural operations etc., to the base year peak load in year of interest. \( L_{SG} \) is standard or core load growth, happens due to regular increase in population and their financial capacities instead of block load additions, in load of base year.

Load growth information is very useful in determining projected load in coming years for deciding energy storage ratings. Heuristically, load growth is decided in percentage of base year peak load [3]. Critical load profile in year of interest \( r \) is estimated as

\[
CLP^r = CLP^b + L_{gr}^r \tag{11}
\]

The peak hours on days just before and after day of critical load profile are lesser than that on day of this load profile. Thus, there is high possibility that the BESS is fully charged on day before, and, on day after, it will have enough charging interval after discharging fully on day of critical load profile. Steps to determine nominal values of battery energy system are given below.

1) Determine optimal no. of clusters (\( c_1, c_2, \ldots, c_n \))
2) Identify \( C_{peak} \)
3) Find critical load profile for base year \( CLP^b \)
4) Obtain load growth \( L_{gr}^r \) in year \( r \) from base year
5) Modify critical load profile for year \( r \) as \( CLP^r \)
6) Set \( P_{grid}^{ref} \), reference demand at upstream grid
7) Estimate \( E_{rated}, P_{rated} \)

VI. TEST RESULTS AND DISCUSSIONS

The effectiveness of the proposed approach is tested on Indian Institute of Technology Kanpur (IITK) distribution system getting power supply from Panki power grid via 33 kV lines. One 10 MVA and 2x5 MVA, 33kV/11kV transformers are installed in main substation. The 10 MVA transformer (Transformer 3) of main substation caters the major demand in IITK. Hourly load data of year 2013 of 10 MVA, 33/11 kV transformer is considered for finding the feasibility of BESS installation. With optimal usage of batteries, it is possible to avoid overloading and minimize losses in the system. With battery energy storage, it is possible to set the reference power profile of upstream grid, using historical data of demand, while not violating the constraints of the BESS.
A. Implementation of Clustering Algorithm

The \( k \)-means clustering algorithm is applied on hourly loading of feeder of Transformer 3. Optimal number of clusters is found while validating with Silhouette coefficient. For 2 numbers of clusters, Silhouette coefficient is obtained as 0.7865 which is maximum among that of different number of groups of load profiles. Centroid load profile is calculated for both clusters and group of maximum demands, \( c_{\text{peak}} \) is identified. In IITK system, the peak electrical load demand occurs between 09:00 and 17:00 as shown in Fig. 2 and, during this period, major electricity consumption is in academic area.

In cluster 2, except outliers, the electricity consumption by the end user is having less variation, and no peak and valley are identified and can be seen from Figs 2 and 3. So, during these days power distribution system is not overloaded and losses would not be higher. In days of cluster 1, variation in electricity consumption is found with peak demands during 09:00 to 17:00 hrs. So, the whole distribution system associated with transformer 1 is overloaded. More shutdowns are needed for preventive and maintenance work. Although maximum electricity consumption is demanded on a few days in a year but on these days, the reliability of the system is jeopardized.

B. Finding Local Outlier in different Clusters

In different clusters, LOF is obtained for each load pattern to distinguish outliers from other homogeneous load patterns. In this paper, heuristically, thresholds are set for LOF as 1.5 in cluster 1 and 1.7 in cluster 2, to show 9 outliers as given in Table I. These outliers occur, mainly, due to shutdowns taken for maintenance purpose and regular/irregular broad peak demand. These irregular consumptions are ranked according to their outlying nature. The abnormal consumptions of both the clusters are shown in Fig. 4.

<table>
<thead>
<tr>
<th>TABLE I.</th>
<th>DAYS WITH LOF IN DESCENDING ORDER FROM HIGHEST</th>
</tr>
</thead>
<tbody>
<tr>
<td>Cluster 1</td>
<td>day</td>
</tr>
<tr>
<td>Cluster 2</td>
<td>day</td>
</tr>
</tbody>
</table>

C. Finding Critical Load Profile

In different clusters, with proposed approach, the critical profile is obtained for estimation of size of battery energy storage. In cluster 2, the electricity consumption is flat i.e. no major peak and valley occurs, Fig. 2 and 3. \( CLP_B \) , found in \( c_{\text{peak}} \) , is July 17 and Aug 06, 2013 as on both days, the \( N_{\text{disch}} \) is same and equal to 11 as shown in Table II. In this paper, base year is 2013, and \( r = 5 \) (i.e. year of interest from base year) is considered. Block load additions \( L_{\text{HL}} \) and standard load growth \( L_{SG} \) are assumed zero and 2\% of base year peak load, respectively. \( CLP^r \) is estimated to determine the size of battery energy storage system. The critical load profile considering 5 years load growth factor with 3.5 MW reference system demands are shown in Fig 5. The power and energy rated values are decided based on this reference demand.
Number of discharge intervals on days of these two critical profiles is maximum Table II. There are enough intervals for charging on same and next consecutive days. Power rating and energy rating are based on two different technologies of storage systems. Maximum power demand and the energy demand as 1.238 MW and 6.455 MWh in two critical load profiles are used to design size of storage. So power rating of storage is sized as 1.25 MW and energy rating is obtained using (9), considering $\eta_{\text{disch}} = 0.8$ and $SO_{C_{\min}} = 0.2$ depending on different discharging capability as shown in Table III.

### Table II. Power and Energy Demand in Critical Load Profile (Reference Upstream Grid Demand=3.5 MW)

<table>
<thead>
<tr>
<th>Day</th>
<th>$P_{\text{max}}$ (MW)</th>
<th>$E_{\text{tot}}$ (MWh)</th>
<th>$N_{\text{disch}}$</th>
<th>$\delta_{\text{disch}}$ (100% eff.)</th>
<th>$\delta_{\text{disch}}$ (70% eff.)</th>
</tr>
</thead>
<tbody>
<tr>
<td>July 17</td>
<td>1.238</td>
<td>5.746</td>
<td>11</td>
<td>4.64</td>
<td>6.63</td>
</tr>
<tr>
<td>Aug 06</td>
<td>0.894</td>
<td>6.455</td>
<td>11</td>
<td>7.22</td>
<td>10.32</td>
</tr>
</tbody>
</table>

### Table III. Energy Rating Based on Discharging Capability (2% Annual Growth, Upstream Grid Demand=3.5 MW)

<table>
<thead>
<tr>
<th>Discharging Capability (min)</th>
<th>60</th>
<th>30</th>
<th>15</th>
<th>05</th>
<th>01</th>
</tr>
</thead>
<tbody>
<tr>
<td>Energy rating (MWh)</td>
<td>8.88</td>
<td>4.44</td>
<td>2.22</td>
<td>0.74</td>
<td>0.15</td>
</tr>
</tbody>
</table>

VII. Concluding Remarks

A method is developed to find critical load profile to size the battery storage system. The $k$-means clustering algorithm is implemented to separate the similar load profiles in historical yearly electrical consumption data of practical system. Cluster of load profiles, consisting peak demand, is obtained and broadest peak load profile, considering it as an outlier, is identified using concept of local outlier factor. The obtained and broadest peak load profile, considering it as an outlier, is identified using concept of local outlier factor. The proposed algorithm suggests the power rating of BESS and energy rating is calculated for different rate of required discharge capabilities. The battery storage system with power rating 1.25 MW and energy rating 8.9 MWh is able to maintain the demand not more than 3.5 MW at transformer no. 3 of 33/11 kV substation at IIT Kanpur. The different energy rating can be decided depending on discharging capability as shown in Table III. The sized BESS will be capable to be used in peak shaving and load leveling applications till 2018.

### References

1. http://energystorage.org