Myoelectric stimulation on peroneal muscles with electrodes of the muscle belly size attached to the upper shank gives the best effect in resisting simulated ankle sprain motion

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Abstract: The inadequate reaction time of the peroneal muscles in response to an incorrect foot contact event has been proposed as one of the aetiological factors contributing to ankle joint inversion injury. Thus, the current study aimed to investigate the efficacy of a myoelectric stimulation applied to the peroneal muscles in the prevention of a simulated ankle inversion trauma. Ten healthy male subjects performed simulated inversion and supination tests on a pair of mechanical sprain simulators. An electrical signal was delivered to the peroneal muscles of the subjects through a pair of electrode pads. The start of the stimulus was synchronized with the drop of the sprain simulator's platform. In order to determine the maximum delay time which the stimulus could still resist the simulated ankle sprain motion, different delay time were tested (0, 5, 10, and 15ms). Together with the control trial (no stimulus), there were 5 testing conditions for both simulated inversion and supination test.

The effect was quantified by the drop of maximum ankle tilting angle and angular velocity, as determined by a motion analysis system with a standard laboratory procedure. Results showed that the myoelectric stimulation was effective in all conditions except the one with myoelectric stimulus delayed for 15ms in simulated supination test. It is concluded that myoelectric stimulation on peroneal muscles could resist an ankle spraining motion.
Dear Editor of Journal of Biomechanics,

**Re: Submission of an article titled “Myoelectric stimulation on peroneal muscles resists simulated ankle sprain motion”**

The mentioned manuscript was submitted as “Original Article” on 31st Jan, 2012 (Ref: Ms. No. BM-D-12-00115). As suggested by the referee, we revised the manuscript as a “Short Communication”.

We declare that each author were fully involved in the study and preparation of the manuscript and that the material within has not been and will not be submitted for publication elsewhere.

Daniel Tik-Pui FONG  
Vikki Wing-Shan CHU  
Kai-Ming CHAN

10 Apr, 2012
Dear Dr Fong,

Thank you for your submission to the Journal of Biomechanics. After considering the enclosed reviews from our referees, I regret to inform you that our referee panel recommends against publication of your manuscript in its current form, although a revised manuscript may be resubmitted and considered after further review. Although it is obvious your manuscript represents considerable work, and the referees and I believe it to be relevant to the Journal, one of the referees raised several major issues that would need to be addressed prior to publication. Their comments are attached for your information.

In addition, please rewrite your results section so that each paragraph is led with a clear statement of a key result. Refer to Tables and figures parenthetically (rather than "Table 1 showed ").

The Results section was rewritten.

Please note that in consideration of the authors' and the reviewers' time, I normally allow only one major revision; if the reviewers request another major revision, I regret that we will not be able to publish your manuscript. Unfortunately, we have been forced to decrease our acceptance rate significantly due to an increase in manuscript submissions.

To submit a revision, go to http://ees.elsevier.com/bm/ and log in as an Author. You will see a menu item called Submission Needing Revision. You will find your submission record there. Please update accordingly and submit your revised manuscript.

If you choose to submit a revised manuscript, please provide a list of points of how you have responded to the reviewers' suggestions with the revised manuscript, at your earliest convenience. If you do not wish to proceed, please let us know in order to complete our records. The maximum time

*Revision Notes*
allowed for revision is 8 weeks, after which the file on this manuscript will be closed. If you feel you need longer than this please contact me.

Please note:
* Any figures and tables should be included, even if these are unaltered.
* It is the author's responsibility to ensure that data presented in figures and tables agree with that provided in the text. Please cross check figures, tables and text carefully.
* Please double-check formatting of your references
* Please use your word processor to automatically number the lines of your manuscript
* Please provide a word count, from the Introduction through the Acknowledgments.

Thank you again for submitting to the Journal of Biomechanics. I look forward to receiving your revised manuscript.

Yours sincerely,

Stephen Piazza, Ph.D.
Associate Editor

Farshid Guilak, Ph.D.
Editor-in-Chief
Journal of Biomechanics
Reviewer #1:

GENERAL COMMENT: The authors have produced an interesting paper which is of importance to the biomechanics community and particularly those with an interest in ankle joint sprain neuromechanics. I feel that the manuscript is not as concisely written and well presented as other works from this group, and the English language needs significant revision in places. However with some work, the paper in my opinion is worthy of publication as a short communication.

The manuscript was rewritten as a short communication as suggested.

SECTION: ABSTRACT

LINE: The slow reaction time of peroneal muscles is an aetiology to ankle sprain injury which causes the failure of adaptation to incorrect foot landing. This study proposed the use of myoelectric stimulation on peroneal muscles to initiate quick contraction to prevent ankle sprain injury, and evaluated its effect by its performance in resisting simulated ankle sprain motions in a laboratory setting.

COMMENT: My suggestion would be to re-phrase Inadequate reaction time of the peroneal muscles in response to an incorrect foot contact event has been proposed as one of the aetiologic factors contributing to ankle joint inversion injury. Thus, the current study aimed to investigate the efficacy of a myoelectric stimulation applied to the peroneal muscles in the prevention of a simulated ankle inversion trauma.

Changed as suggested

LINE: The delay time was set at 0, 5, 10 and 15ms to determine the maximum delay from the start of the electrical trigger which the device could still resist the simulated ankle sprain motion.

COMMENT: This line needs also to be re-phrased.

The sentences was rewritten to “The start of the stimulus is synchronized with the drop of the sprain simulator’s platform. In order to determine the maximum delay time which the stimulus could still resist the simulated ankle sprain motion, different delay time were test (1, 5, 10, and 15ms). Together with the control trial (no stimulus), there were 5 testing conditions for both simulated inversion and supination test.”

LINE: The two most commonly suggested aetiologies are the incorrect foot positioning at landing which generates sudden and excessive ankle inversion or supination torque, and the slow reaction
time of the peroneal muscles at the lateral aspect of the ankle to accommodate by resistive eversion or pronation torque (Fong et al, 2009).

COMMENT: I would suggest breaking up this sentence.

[1] The first idea to introduce is the role of an incorrect foot contact event. This can occur during landing from a jump or also during gait.

My suggestion would be to introduce this as follows: "One factor commonly reported to contribute to the ankle sprain injury mechanism and particularly in the case of chronic ankle instability is an inappropriate positioning of the foot prior to and at initial contact with the ground during gait, landing from a jump and other sporting activities."

Appropriate references might be:


Changed as suggested and 3 references Mok et al, 2011, Delahunt et al, 2006 and 2007 were added.

[2] Next the authors should introduce the rationale behind a feedforward and feedback deficit in peroneal activation.

My suggestion would be to introduce this as follows: "It has also been suggested that a deficit in peroneal feedforward and feedback neuromuscular response may contribute to inappropriate positioning of the foot prior to and at initial contact. Furthermore, an increased latency in the peroneal muscles could further contribute to the injury mechanism, whereby these muscles cannot react in a time efficient manner to prevent an inversion trauma."

Appropriate references would be:


Orthopaedic sport medicine specialists and sport scientists are working on ankle sprain prevention by different measures, such as ankle muscle strength and endurance training (So et al, 1994), proprioception and neuromuscular training (Xu et al, 2004). On top of these training, prophylactic apparels such as brace and taping are also widely used for ankle sprain prevention (Cordova et al, 2007), however, it may restrict the ankle range of motion so does the performance (Hume et al, 1998).

This section is a little weak and should be improved. I think that it is sufficient to say that recent studies suggest that neuromuscular training protocols incorporating strength, postural stability and proprioceptive exercises are effective in reducing functional insufficiencies associated with ankle sprain. However, the optimal training protocol has yet to be designed. In the absence of such a protocol the investigation of novel technologies is warranted [this then leads into the anti-sprain shoes development section].

The authors need to incorporate some more up-to-date references regarding neuromuscular training protocols.


A new idea of prophylactic apparel, an intelligent anti-sprain shoe, was proposed in 2006. It provides protection actively when a sprain risk is sensed. During unharmed condition, it just likes a normal sport shoe, allows full range of ankle motion (Chan, 2006).

Please re-read to improve the English of these two sentences. Also the authors should use inversion sprain at all times, as we are interested in lateral ligament complex injury.

The sentences were rewritten to “In 2006, Chan proposed a new idea of prophylactic apparel – an intelligent anti-inversion-sprain shoe. It detects the foot motion continuously. Once hazardous motion is detected, a corrective mechanism will be activated to correct the landing motion (Chan 2006).”

Each subject performed five trials of simulated inversion test and five trials of simulated supination test.

Please improve the English here.
LINE: The voltage was gradually increased until the subject became unbearable. It was about 110V - 130V.

COMMENT: This should be "the voltage was gradually increased until it became intolerable to the subject (range 110 - 130V)."

Changed as suggested

LINE: Control trial with no myoelectric stimulation being delivered during the simulated spraining test was collected for comparison.

COMMENT: This does not make sense. Please revise.

The sentence was rewritten to “Three trials were performed for each delay time in simulated inversion and supination test respectively. Average value was used for analysis. Subject also performed 3 control trials which is simulated spraining test without myoelectric stimulation.”

STATISTICAL ANALYSIS:

COMMENT: In this section it would be advisable for the authors to outline the specific independent variables and the dependent variables. What was the correlation among the dependent variables (max heel tilt, max heel tilt velocity)? If the correlation is weak or strong it may be a better option to run two separate one-way repeated measures ANOVA (one for inversion and one for supination). In this case the dependent variables would be max heel tilt, max heel tilt velocity, while the independent variable would be condition (with 5 levels - represented by control, 0, 5, 10 and 15 ms). The authors would be able to present the main effect reporting Wilks Lambda, F value, p value and eta squared value. Then post-hoc analysis would be conducted with the results presented in a table.

The statistic was redone as suggested. Since the maximum tilting angle and velocity is highly correlated (Pearson correlation > 0.7), two separate one-way repeated measures ANOVA (one for inversion and one for supination) was used.

LINE: Both the maximum heel tilting angle and angular velocity did not significantly differ from that in control condition.

COMMENT: I do not understand this line. Please clarify.

The result section was rewritten.

TABLE: Presumably there should be reference to (b) Supination?

Reference to (b) Supination was added in all tables.

DISCUSSION:

COMMENT: All is clear and makes sense.
Reviewer #2:

I think this is an important work and should be published.
Title page

Title:
Myoelectric stimulation on peroneal muscles resists simulated ankle sprain motion

Authors:
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Kai-Ming CHAN\textsuperscript{1,2}, MBBS

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Keywords: ankle ligamentous sprain, injury prevention, biomechanics

Word count: 1497
Abstract

The inadequate reaction time of the peroneal muscles in response to an incorrect foot contact event has been proposed as one of the aetiological factors contributing to ankle joint inversion injury. Thus, the current study aimed to investigate the efficacy of a myoelectric stimulation applied to the peroneal muscles in the prevention of a simulated ankle inversion trauma. Ten healthy male subjects performed simulated inversion and supination tests on a pair of mechanical sprain simulators. An electrical signal was delivered to the peroneal muscles of the subjects through a pair of electrode pads. The start of the stimulus was synchronized with the drop of the sprain simulator’s platform. In order to determine the maximum delay time which the stimulus could still resist the simulated ankle sprain motion, different delay time were test (0, 5, 10, and 15ms). Together with the control trial (no stimulus), there were 5 testing conditions for both simulated inversion and supination test.

The effect was quantified by the drop of maximum ankle tilting angle and angular velocity, as determined by a motion analysis system with a standard laboratory procedure. Results showed that the myoelectric stimulation was effective in all conditions except the one with myoelectric stimulus delayed for 15ms in simulated supination test. It is concluded that myoelectric stimulation on peroneal muscles could resist an ankle spraining motion.
Introduction

Ankle sprain is one of the most common sport-related injuries (Fong et al, 2007; Fong et al, 2008). One factor commonly reported to contribute to the ankle sprain injury mechanism and particularly in the case of chronic ankle instability is an inappropriate positioning of the foot prior to and at initial contact with the ground during gait, landing from a jump and other sporting activities (Mok et al, 2011, Delahunt et al, 2006 and 2007). It has also been suggested that a deficit in peroneal feedforward and feedback neuromuscular response may contribute to inappropriate positioning of the foot prior to and at initial contact. Furthermore, an increased latency in the peroneal muscles could further contribute to the injury mechanism, whereby these muscles cannot react in a time efficient manner to prevent an inversion trauma (Delahunt et al, 2006 and Fong et al, 2009).

Recent studies suggest that neuromuscular training protocols incorporating strength, postural stability and proprioceptive exercises are effective in reducing functional insufficiencies associated with ankle sprain (Holmes 2009). However, the optimal training protocol has yet to be designed. In the absence of such a protocol the investigation of novel technologies is warranted. In 2006, Chan proposed a new idea of prophylactic apparel – an intelligent anti-inversion-sprain shoe. It detects the foot motion continuously. Once hazardous motion is detected, a corrective mechanism will be
activated to correct the landing motion (Chan 2006).

One possible corrective mechanism for this intelligent shoe is to deliver a myoelectric stimulation to the peroneal muscles to trigger quick reflex contraction. Such technique, named “functional electrical stimulation”, has been adopted in rehabilitation settings and motor control research (Sabut et al., 2010). In our approach, the rationale is to utilize its function and quick reaction to initiate peroneal muscle contraction and generate the subsequent ankle joint pronation torque within 21-25ms (Ginz et al., 2004). The stimulus could then take over the role of the slower peroneal muscles which react within 60-90ms to resist the sudden ankle torque happening within 40-50ms after the start of an ankle joint inversion event (Fong et al., 2009).

The purpose of this study is to verify the action of artificial myoelectric stimulation of the peroneal muscles and the appropriate timing necessary to reduce ankle inversion and supination ranges during simulated sprain motion.

**Materials and methods**

Ten recreational male athletes (age=22.6±2.4 year, height=1.72±0.04 m, body mass=68.1±8.0 kg) were recruited. The university ethics committee approved the study. A
A pair of mechanical sprain simulators was used to simulate inversion and supination motion (Chan et al, 2008). In each trial, the subject stood with his body weight evenly distributed on both platforms. One of the platform fell suddenly to a 30-degree tilted orientation without prior notice to the subject.

A battery-powered myoelectric stimulation device was fabricated by the university electronics services unit by modifying a previous design (Thorsen et al, 2009), with adjustable voltage magnitude, activation time, and delay time of the stimulus from the time of platform falls. The device was synchronized with the fall of the platform. A pair of electrode pads (Panasonic EW4312P, Japan) was attached to the subject’s peroneal muscle belly. A myoelectric signal was delivered to the peroneal muscles to check if the system was well equipped, as indicated by an involuntary ankle pronation motion right after the delivery of myoelectric signal. The voltage was gradually increased until it became intolerable to the subject (range 110V - 130V).

The delay time was set at 0, 5, 10 and 15ms in order to determine the maximum delay between the moments an ankle sprain starts to occur until the latest time which the device could still save the ankle joint. Since the electromechanical delay was reported to be 21-25ms (Ginz et al, 2004), a delay time greater than 15ms was not investigated as it
could hardly catch up with a vigorous ankle sprain motion happening within 40-50ms.

The activation time was set to 500ms, which is enough to cover the duration of an ankle sprain motion. **Three trials were performed for each delay time in simulated inversion and supination test respectively. Average value was used for analysis. Subject also preformed 3 control trials which is simulated spraining test without myoelectric stimulation.**

Twelve reflective markers (5mm diameter) were attached to lateral fibula epicondyle, tibial tuberosity, lateral proximal shank, medial proximal shank, anterior distal shank, lateral distal shank, medial distal shank, posterior heel, lateral heel, medial heel, medial foot and dorsal foot. Marker coordinates were recorded by an optical motion analysis system (VICON, UK) at 500Hz. It were filtered by Generalized Cross-Validation package of Woltring with 15Hz cut-off frequency (Woltring et al, 1986). A static calibration trial with the subject standing on the platforms in the anatomical position served as the offset position to determine the segment embedded axes of the shank and foot segment. The foot and shank segment were embedded with the Laboratory Coordinate System (LCS). A singular value decomposition method was employed to calculate the transformation from triad reference frame to anatomical shank and foot reference frame (Grood et al, 1983). **Joint kinematics was deduced by the Joint Coordinate System (JCS) method (Soderkvist et al, 1993).** Heel tilting angle was defined as the angle between the LCS vertical axis and
foot transverse plane directional axis (Figure 2), and the heel tilting velocity was its change with respect to time. The maximum measurements of these two parameters were investigated. The data analysis was batch-processed by a customized Matlab program.

Statistical analysis

Shapiro-Wilk test was conducted to check the normality of each parameter in each condition first. All parameter showed normality. Since maximum heel tilting angle and angular velocity were highly correlated (Pearson correlation > 0.7), two separate one-way repeated measures ANOVA were used for inversion and supination respectively. The dependent variables choose for analysis were maximum heel tilting angle. The independent variables were condition with 5 level (control, 0, 5, 10, 15 ms delay time).

Post-hoc Bonferroni t-tests were then conducted to investigate which condition is differ. Statistical significance was set at p ≤ 0.05.

Results

In both simulated inversion and supination tests, the maximum heel tilting angle dropped from 18 degrees to 9-13 degrees, and the maximum heel tilting angular velocity dropped from 200-250 degree/s to 140-170 degree/s. (Table 1)
One way ANOVA with repeated measures results showed that there was different between conditions in both inversion and supination test (Table 2). Post-hoc Bonferroni t-tests further showed that the significant drop of the maximum heel tilting angle was found between the conditions with and without stimulus, except 15ms delay time. There was no different among the trials with stimulus (Table 3).

Discussion

In this study, the myoelectric stimulation on peroneal muscles was found to be effective in reducing the maximum heel tilting angle and angular velocity in the simulated ankle sprain tests, except with delay time 15ms in supination test. There was no significant different among 0, 5, 10 and 15ms delay groups. During simulated inversion motion without myoelectric stimulation, the maximum angular velocity occurred at 83 ms after the fall. Compare with the case report of an accidental ankle sprain injury, the maximum inversion velocity occurred at 30 ms after the foot strike (Fong et al, 2009). The time of maximum velocity occurred later in simulated inversion motion than real injury case and the value is much lower (253 deg/s in simulated motion and 632 deg/s in injury case). This is because the motion in real injury case is much more vigorous, so larger angular velocity can be reached within a short period of time.
Our research team is developing an ankle sprain identification method utilizing motion sensors to detect any hazardous ankle spraining motion (Chan et al, 2010; Chu et al, 2010). This result suggested that there is maximum 10ms of time for the sensors to detect a sprain motion, and to actuate the corrective system to protect the ankle joint in time.

The time limit may be even shorter in the real application since the injury motion is more rigorous, hence more time or higher stimulation level is needed to resist/stop the motion.

In this study, the starting time was determined by the electrical trigger to initiate the fall of the platform. In the future intelligent shoe, motion sensor is to be used as the trigger.

Conclusion

This study showed a good feasibility of delivering myoelectric stimulation on peroneal muscles with 10ms to resist sudden simulated ankle sprain motions. This corrective mechanism could be implemented in the intelligent shoe to prevent ankle sprain injury.

Acknowledgement

This research project was made possible by the donation of The Hong Kong Jockey Club Charities Trust. It is a project of The Hong Kong Research Institute of Textiles and Apparel and is financially supported by the Innovation and Technology Fund from
Innovation and Technology Commission, Hong Kong Special Administrative Region

Government, Project number: ITP/017/10TP. The authors acknowledge Mr Shee-Sun Chiu of Electronics Services Unit of The Chinese University of Hong Kong for his help to fabricate the myoelectric stimulation device.

References


techniques on isometric skeletal muscle strength. British Journal of Anaesthesia 92, 367-72.


Table legends

Table 1 – Mean and SD of maximum heel tilting angle and angular velocity.

Table 2 – Results of two one-way ANOVA with repeated measures. Dependent variable was maximum heel tilting angle.

Table 3 – Results of post-hoc Bonferrion test.

Figure legends

Figure 1 – The simulated ankle sprain test.

Figure 2 – Heel tilting angle was defined as the ankle between the Laboratory Coordinate System (LCS) vertical axis and foot transverse plane directional axis.
Table 1 – Mean and SD of maximum heel tilting angle and angular velocity.

<table>
<thead>
<tr>
<th></th>
<th>Maximum heel tilting angle (degree)</th>
<th>Maximum heel tilting angular velocity (degree/s)</th>
<th>Maximum heel tilting angle (degree)</th>
<th>Maximum heel tilting angular velocity (degree/s)</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>(a) Inversion test</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Control</td>
<td>18.4 (3.9)</td>
<td>252.5 (47.3)</td>
<td>Control</td>
<td>17.7 (6.3)</td>
</tr>
<tr>
<td>Delay = 0ms</td>
<td>9.9 (4.8)</td>
<td>150.3 (56.3)</td>
<td>Delay = 0ms</td>
<td>12.1 (5.9)</td>
</tr>
<tr>
<td>Delay = 5ms</td>
<td>9.4 (5.7)</td>
<td>144.2 (70.4)</td>
<td>Delay = 5ms</td>
<td>13.6 (6.4)</td>
</tr>
<tr>
<td>Delay = 10ms</td>
<td>11.5 (5.2)</td>
<td>158.8 (57.3)</td>
<td>Delay = 10ms</td>
<td>13.5 (6.8)</td>
</tr>
<tr>
<td>Delay = 15ms</td>
<td>12.5 (6.0)</td>
<td>172.6 (66.2)</td>
<td>Delay = 15ms</td>
<td>12.7 (6.8)</td>
</tr>
</tbody>
</table>
Table 2 – Results of two one-way ANOVA with repeated measures. Dependent variable was maximum heel tilting angle.

<table>
<thead>
<tr>
<th></th>
<th>Wilks’ Lambda</th>
<th>F-value</th>
<th>p-value</th>
<th>Partial Eta Squared</th>
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</thead>
<tbody>
<tr>
<td>(a) Inversion test</td>
<td>0.111</td>
<td>12.042</td>
<td>0.005</td>
<td>0.8890</td>
</tr>
<tr>
<td>(b) Supination test</td>
<td>0.092</td>
<td>14.749</td>
<td>0.003</td>
<td>0.908</td>
</tr>
</tbody>
</table>
Table 3 - Results of post-hoc Bonferrion test.

<table>
<thead>
<tr>
<th></th>
<th>Maximum heel tilting angle (degree)</th>
<th>Bonferroni test with control</th>
<th>Mean differences (95% Confidence Interval)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>(a) Inversion test</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Control</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Delay = 0ms</td>
<td>0.001*</td>
<td>8.4 (3.9-13.0)</td>
<td></td>
</tr>
<tr>
<td>Delay = 5ms</td>
<td>0.003*</td>
<td>9.0 (3.0-14.9)</td>
<td></td>
</tr>
<tr>
<td>Delay = 10ms</td>
<td>0.002*</td>
<td>6.9 (2.6-11.2)</td>
<td></td>
</tr>
<tr>
<td>Delay = 15ms</td>
<td>0.040*</td>
<td>5.9 (0.2-11.6)</td>
<td></td>
</tr>
<tr>
<td>(b) Supination test</td>
<td></td>
<td></td>
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<tr>
<td>Control</td>
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</tr>
<tr>
<td>Delay = 0ms</td>
<td>0.002*</td>
<td>5.5 (2.3-8.8)</td>
<td></td>
</tr>
<tr>
<td>Delay = 5ms</td>
<td>0.001*</td>
<td>4.6 (3.0-7.3)</td>
<td></td>
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<tr>
<td>Delay = 10ms</td>
<td>0.046*</td>
<td>4.2 (0.1-8.4)</td>
<td></td>
</tr>
<tr>
<td>Delay = 15ms</td>
<td>0.240</td>
<td>4.9 (-1.8-11.7)</td>
<td></td>
</tr>
</tbody>
</table>

In Bonferroni test, significant difference with p value less than 0.05 was denoted by an asterisk (*).
Conflict of interest

Dear Editor of Journal of Biomechanics,

REF: Submission of manuscript titled “Myoelectric stimulation on peroneal muscles resists simulated ankle sprain motion”.

The authors declare no financial and personal relationships with other people or organizations that could inappropriately influence this submitted work.

Daniel Tik-Pui FONG