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Active micromachines: Microfluidics powered by mesoscale turbulence

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Dense active matter, from bacterial suspensions and microtubule bundles driven by motor proteins to cellular monolayers and synthetic Janus particles, is characterized by mesoscale turbulence, which is the emergence of chaotic flow structures. By immersing an ordered array of symmetric rotors in an active fluid, we introduce a microfluidic system that exploits spontaneous symmetry breaking in mesoscale turbulence to generate work. The lattice of rotors self-organizes into a spin state where neighboring discs continuously rotate in permanent alternating directions due to combined hydrodynamic and elastic effects. Our virtual prototype demonstrates a new research direction for the design of micromachines powered by the nematohydrodynamic properties of active turbulence.

INTRODUCTION

A hallmark of active fluids, such as bacterial suspensions and filament-motor protein mixtures, is the emergence of large-scale chaotic, turbulent-like structures known as mesoscale (or active) turbulence (1–4). The intrinsic disorder of these flow fields acts as a barrier to the extraction of useful power from active suspensions. Presdesigned microfluidic systems have been built to direct cell motion (5–8), pump fluid (9), or drive microrotors (10, 11). These impose symmetry breaking through geometrical constraints or external biases. In particular, it is possible to obtain a persistent rotation for specially designed microscopic gears submerged in bacterial baths (12–14). However, it has been argued that an asymmetric gear shape is required to achieve a persistent rotation and that bacterial “traps” in the form of symmetric teeth are essential for generating directed motion of gears (13). Here, we argue that asymmetry of the gears is not a prerequisite and propose a means of exploiting spontaneous symmetry breaking of mesoscale turbulence to turn many symmetric rotors.

We use numerical simulations to demonstrate that mesoscale turbulence can be exploited to generate work by considering a two-dimensional (2D) square array of cylindrical rotors that are free to turn in response to mesoscale flows in the solution. The array of discs achieves a state of permanent rotation below a given interdisc spacing (Fig. 1A). The spin state of the rotors is fixed, with neighboring discs rotating in opposite directions. Hence, the disc array rectifies the active turbulence into a steady power source.

To determine how the antiferromagnetic spin state of the rotors is established, we consider a solitary disc immersed in an active bath. Protracted, but nonpermanent, rotation can be achieved by synergistic hydrodynamic and elastic effects, which both depend on the properties of the active flow and on the orientational anchoring of the active fluid at the disc surface. We find an exponential dependence of the rotational persistence time on rotor size, which suggests that the decorrelation of rotor angular velocity is controlled by an activated barrier-crossing process. In addition, by placing a single rotor within an immobile circular cavity, we explain how rotation stabilization results from fluid confinement between neighboring discs in the lattice configuration and demonstrate that the characteristic length of activity-induced vortices sets the optimal length scales for the microfluidic design.

RESULTS

A square lattice of 64 rotors is deployed in simulations with periodic boundary conditions on domain boundaries and with either homotropic (perpendicular to the boundary), planar (parallel to the boundary), or no anchoring of the director (characterizing the orientation field) at the rotor surface. Drag on the rotors due to spontaneous active flows causes them to spin (Fig. 1A). Each disc preferentially rotates in the opposite direction to its nearest neighbors. Although Fig. 1A shows only a subset of rotors, the alternating pattern repeats throughout the entire system (movies S1 and S2). This strong anticorrelation between angular velocities occurs when the gap size $d$ between of the nearest neighbors is small. However, if the spacing is increased, the spins of neighboring rotors decorrelate, and the rotors spin randomly (Fig. 1B).

Moreover, the rotation of a single disc in the array is extremely enduring (Fig. 1C and movie S3). When the separation between rotors is small, it becomes constant on the time scale of our simulations (107 simulation time steps, which covers more than 1000 rotations of the rotors), but when the spacing increases, the angular velocity autocorrelation function of a single rotor, $\langle \omega(t) \omega(0) \rangle$, approaches zero over time (Fig. 1C). The autocorrelation function describes the propensity of the rotor to continue rotating in its current direction and is characterized by the time scale $\tau$. Even for the largest spacings, the rotors maintain a nonzero persistence time of rotation.

Streamlines in Fig. 1A demonstrate that local flows move in the same direction as each rotor spins for small gap sizes. The array of spinning rotors stabilizes the active fluid flow, which would otherwise exhibit mesoscale turbulence. Simulations that consider the extreme case of infinite friction (by disallowing disc rotation) show the same streamlines and director fields as the arrays of free rotors, although with reduced flow speeds. This indicates that the self-organized spin state should be expected in experimental realizations of microfluidic systems of rotors that include finite rotational friction or have been designed to act as active turbines.
For a free rotor to change its direction of rotation in the small separation regime, it must overcome the local flow field, which is not only established through the boundary conditions of the disc in question but also entrenched by the flow field of neighboring rotors. Although the decorrelation time of the angular velocity increases with decreasing gap size, the rotation rate is nonmonotonic with a sharp maximum (Fig. 1B, inset). The maximum is set by the competition between gap size and active nematic fields. To better understand the mechanisms leading to steady anticorrelated rotation and the impact of rotor spacing, we systematically investigate the dynamics of a solitary rotor and a single rotor within a concentric cavity. These single-rotor results demonstrate how the permanent spin state arises in the array and explain how the optimal rotation rate relates to the intrinsic characteristic vorticity length scale of the active turbulence.

A solitary disc in an active fluid begins to rotate once activity-driven flow fields are established (Fig. 2). The surrounding active fluid exhibits self-sustained mesoscale turbulence (Fig. 2A) even at zero Reynolds number (15). The chaotic vorticity field is driven by a “reverse energy cascade” produced at microscopic length scales and escalating to larger scales (16, 17). In active nematic fluids, the continuous fluid motion is coupled to the formation of lines of strong bend distortions in the orientation field, referred to as walls (18, 19), and their unzipping through the creation and annihilation of topological defect pairs (20, 21). Notably, the resulting stochastic velocity and vorticity...
fields have been noted to exhibit many features of turbulent flow (1, 15, 22) and can be characterized by the vorticity-vorticity correlation length scale.

The rotational dynamics are controlled by both the nature of the mesoscale turbulence and the rotor characteristics. Spontaneous symmetry breaking randomly establishes clockwise or counterclockwise spin, and, thereafter, the rotor sporadically switches direction. Hence, as shown in Fig. 3B, the rotation of the disc in response to the flow is propulsive, at short times

$$\langle \Delta \theta(t)^2 \rangle = \omega_{\text{rms}}^2 t^2, \ t \ll \tau$$  

where $\omega_{\text{rms}}$ is the root mean square angular velocity. The short-time behavior is referred to as propulsive rather than ballistic because rotor inertia is visously damped and rotation is due to the nematohydrodynamic propulsion from the active flow field. At longer times, there is a crossover to a diffusive regime

$$\langle \Delta \theta(t)^2 \rangle = 2D_r t, \ t \gg \tau$$  

where $D_r$ is the effective rotational diffusion constant. The diffusive regime arises as active vortices impinge on the rotor and is therefore controlled by the characteristic decay time of the vorticity-vorticity correlation function $D_r \sim \tau^{-1}$. The decay time $\tau$ is substantially prolonged by increasing the size of the rotor, as is apparent from both Fig. 3B and the decay of the angular velocity autocorrelation function.

The rotation is driven by two synergistic mechanisms: (i) entrainment of an active turbulence vortex around the rotor and (ii) wall-driven flow at the surface of the rotor (Fig. 2B, inset). The second mechanism arises due to the orientational boundary condition on the surface of a disc. For homeotropic anchoring, bend deformations in the director field appear naturally at the surface (23, 24). The bend deformations result in the formation of a wall around the perimeter of each rotor (Fig. 2B, inset) (18, 19). Simulations of colloids pulled through active nematic fluids have previously shown that orientational distortion can lead to local flows that cause non-Stokesian dynamics and even negative drag (25). Likewise, in this system, the rotor-encircling wall establishes a unidirectional flow (18) that generates localized vorticity (movie S3). Supporting this argument, if, instead of homeotropic anchoring, no anchoring boundary conditions are implemented, the rotational persistence time of the rotor is significantly diminished because no wall is formed at the disc surface (Fig. 3C and movie S4). The wall-generated flows spontaneously establish a direction of rotation, and any corotational vortices enhance the rotational velocity when the characteristic vortex size of the mesoscale turbulence is commensurate to the rotor size. Thus, the unidirectional flow generated within the wall and the swirling flows within active vortices collude to give a persistent rotation of the disc.

Fig. 2. Rotation of a single rotor immersed in a turbulent flow of active matter with homeotropic anchoring. (A) Color maps show the vorticity contours, and solid lines represent streamlines. Vorticity is normalized to its maximum value, and blue and red represent clockwise and anticlockwise rotation, respectively. An animated version is available (movie S3). (B) Director field around the rotating disc. Red dots and yellow triangles denote $+1/2$ and $-1/2$ topological defects, respectively. Inset: Schematic of the wall in the director field that encircles each rotor and the resulting active flow of fluid along the wall.

Fig. 3. Rotational dynamics of a single rotor in mesoscale turbulence. (A) Mean-squared angular displacement of rotors versus time for different rotor radii $R$. Director boundary conditions on the rotor surface are homeotropic. (B) Persistence time as a function of $R$ comparing homeotropic and no anchoring director boundary conditions on the rotor surface.
As the gap size leads to an enduring rotation of the inner cylindrical rotor (Fig. 5A), the confinement of the annulus to induce a unidirectional flow, which described orientation at the surfaces, the active fluid self-organizes within manner (Fig. 5B). However, for still larger gaps, obvious vortices appear in the flow field (Fig. 5C), and the rotor rotation rate slowly decreases with increasing D (Fig. 5).

The maximum in the rotation rate is also marked by the appearance of topological defects in the director field. These leave the streamlines relatively unperturbed, with the defects advected in a laminar manner (Fig. 5B). However, for still larger gaps, obvious vortices appear in the flow field (Fig. 5C), and the rotor rotation rate slowly decreases with increasing D (Fig. 5).

The rotational persistence time of the rotor is finite at large gap sizes with multiple vortices but is substantially enhanced when only a single stabilized vortex fits within the confinement. On the other hand, dissipation is increased when the gap size is smaller than the natural size of the vortices. From this, we understand the persistent counter-rotating spin state of a disc array (Fig. 1A): each rotor establishes a wall-induced active shear flow, while neighboring rotors do the same, simultaneously creating a confinement that stabilizes the local flow. This process is most efficient if the spacing between rotors is comparable to the characteristic vorticity length scale of the mesoscale turbulence (Fig. 5 and movie S5). In typical bacterial suspensions in 2D geometries, the characteristic length scale is ~ 40 μm (15).

Fig. 5. Confinement-induced rotation of a disc immersed in a bath of active matter showing the transition from unidirectional to turbulent flow. (A) The main panel shows the variation of the angular velocity of the rotor with increasing gap size. The vertical dashed line corresponds to the characteristic length scale of bulk mesoscale turbulence measured from the vorticity-vorticity correlation function in bulk. The insets show the transition from unidirectional flow to active turbulence with increasing gap size D: (i) D = 8; (ii) D = 30; (iii) D = 70. Shown is the director field (dashed green lines), superposed by streamlines (solid black lines with arrows) and topological defects (red and blue dots denoting +1/2, and −1/2 defects, respectively). (B) Mean square angular displacement of the rotor as a function of simulation time, where the transition from propulsive to diffusive behavior is seen when gap size is > 70.

**Fig. 4. Characterization of a single rotor in mesoscale turbulence.** (A) Increasing activity results in an enhanced angular velocity. (B) Increasing activity shortens the rotational persistence time.
DISCUSSION

We have demonstrated the persistent, correlated rotation of an array of symmetric rotors immersed in a dense suspension of active matter, such as bacterial suspensions (1), filament-motor protein solutions (28), or cellular monolayers (29). The results show that harnessing useful work from the disordered and chaotic flows of active materials does not require specifically designed asymmetric microscopic gears or external fields.

The persistent spin state of the rotor array is antiferromagnetic, similar to the recently observed spin states of bacteria suspensions confined within interconnected cavities (30). However, the physical mechanisms leading to these particular spin states are markedly different. Whereas the rotation of *Bacillus subtilis* in interconnected circular cavities is dictated by a counter-rotating single-cell layer that is controlled by the size of the intersection compared to the cell size (30), the antiferromagnetic spin state of rotors studied here arises through a combination of an activated barrier-crossing process and of mooring active nematic vortices to each rotor. The array of spinning rotors stabilizes the active fluid flow, which would otherwise be in a state of mesoscale turbulence.

The way the rotor lattice constrains active excitations of the vorticity field, which in turn causes nonzero torques to arise on the rotors themselves, bears a strong conceptual similarity to Casimir forces (as defined in the general sense and not just for the electromagnetic field fluctuations) (31). The notion of using this concept to design micromachines has been explored in the context of the traditional Casimir forces, revealing interesting possibilities afforded because of a lack of physical contact (32, 33). A key aspect of the Casimir effect is that it depends primarily on geometric characteristics of the system and, as such, offers a simple route to tuning the behavior of the micromachine. We note that Casimir forces have been postulated to exist in active systems (34–36).

By investigating the dynamics of solitary rotors, we determine how different length scales, namely, the rotor size, the lattice spacing, and the gap between the rotors, affect the behavior of the array of rotors. We find that in larger gaps, decorrelating vortices can be excited between rotors, whereas in smaller spaces, counter-rotating vortices affect the behavior of the array of rotors. The spin state of each rotor is locked by an energy barrier due to the antiferromagnetic spin state of rotors studied here arises through a finite-difference approach is used for spatial discretization, and the temporal evolution is obtained through a Euler integration scheme. For details, see the studies of Thampi et al. (21), Marenduzzo et al. (24), and Fielding et al. (44).

As usual in lattice Boltzmann schemes, discrete space and time steps are chosen as unity, and all quantities can be converted to physical units in a material-dependent manner (37, 45, 46). The parameters used in the simulations are $\Gamma = 0.34$, $K = 0.01$, $\zeta = 0.01$, and $\eta = 2/3$, in lattice units. These parameters result in active turbulence in the bulk. Unless otherwise stated, simulations were performed in a 2D domain of size $200 \times 200$. Microrotors are modeled as discs discretized on the simulation lattice. Each rotor is fixed in space but allowed to spin freely with a moment of inertia $I = 10^7$ for all radii. For the parameters used here, viscous damping dominates over inertia in approximately $\sim I/\eta R^2 \approx 10^8$ time steps. No-slip boundary conditions allow flows to apply torques to the rotors.

SUPPLEMENTARY MATERIALS

Supplementary material for this article is available at http://advances.sciencemag.org/cgi/content/full/2/7/e1501854/DC1

movie S1. Antiferromagnetic spin state in an array of rotating discs.
movie S2. Antiferromagnetic spin state in an array of rotating discs.
movie S3. Rotation of a single rotor immersed in active turbulence.
movie S4. Rotation of a single rotor immersed in active turbulence.
movie S5. Confinement-induced rotation of a disc immersed in an active nematic bath.

REFERENCES AND NOTES


MATERIALS AND METHODS

We use the equations of active nematohydrodynamics based on the theory of liquid crystals, which has proven successful in describing spatiotemporal dynamics of active matter systems, including bacterial suspensions (37), microtubule bundles (2, 38, 39), and cellular monolayers (29, 40). The orientational order of microscopic active particles is represented by the nematic tensor $Q = \frac{N}{2} (n \cdot I - \frac{1}{3})$, where $q$ is the magnitude of the orientational order, $n$ is the director, and $I$ is the identity tensor, which evolves due to a corotation term and relaxation through rotational diffusivity $\Gamma$ of the molecular field, which accounts for both the Landau–de Gennes bulk free energy and the nematic distortion free energy (41), assuming a single elastic constant $K$. The total density and the velocity field $u$ of the active matter obey the incompressible Navier-Stokes equations, with a stress tensor $\Pi$ that must account for contributions from the viscosity $\eta$, the elastic stress (which includes the pressure $P$ (42), and the active contribution to the stress $\Pi^{act} = - \zeta Q$ (43)). Any gradient in $Q$ generates a flow field through the active stress, with the strength determined by the activity coefficient $\zeta$.

The equations of active nematohydrodynamics are solved using a hybrid lattice Boltzmann technique (21) that does not include thermal fluctuations. The momentum equation is solved using the lattice Boltzmann method to resolve the hydrodynamics. The method of lines (21) is implemented to determine the order parameter, in which a finite-difference approach is used for spatial discretization, and the temporal evolution is obtained through a Euler integration scheme.

For details, see the studies of Thampi et al. (21), Marenduzzo et al. (24), and Fielding et al. (44).

As usual in lattice Boltzmann schemes, discrete space and time steps are chosen as unity, and all quantities can be converted to physical units in a material-dependent manner (37, 45, 46). The parameters used in the simulations are $\Gamma = 0.34$, $K = 0.01$, $\zeta = 0.01$, and $\eta = 2/3$, in lattice units. These parameters result in active turbulence in the bulk. Unless otherwise stated, simulations were performed in a 2D domain of size $200 \times 200$. Microrotors are modeled as discs discretized on the simulation lattice. Each rotor is fixed in space but allowed to spin freely with a moment of inertia $I = 10^7$ for all radii. For the parameters used here, viscous damping dominates over inertia in approximately $\sim I/\eta R^2 \approx 10^8$ time steps. No-slip boundary conditions allow flows to apply torques to the rotors.


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